

Open Problem: The Oracle Complexity of Smooth Convex Optimization in Nonstandard Settings

Cristóbal Guzmán

Universidad de Chile (DII)

cguzman@gatech.edu

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Oracle-based Algorithms

- **Instance family:** (κ, L) -smooth cvx. functions, $\kappa \in (1, 2]$

$$\|\nabla f(x) - \nabla f(y)\|_* \leq L \|x - y\|^{\kappa-1} \quad \mathcal{F}_{\|\cdot\|}(\kappa, L)$$

- **Domain** $X \subseteq \mathbb{R}^n$: symmetric convex body
- **Oracle** \mathcal{O} : e.g., $x \mapsto (f(x), \nabla f(x))$
- Algorithm A after T (adaptive) queries outputs $x^T(A)$
- Worst-case oracle complexity:

$$\text{Risk}(T) = \inf_A \sup_{f \in \mathcal{F}_{\|\cdot\|}(\kappa, L)} [f(x^T(A)) - \text{Opt}(f)]$$

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Standard setting: $X = B_{\|\cdot\|}$

Non-Standard Settings

Example: Linear prediction

- Predictor $x \in X = B_p^n$

- Random examples: $(1/q + 1/q_* = 1)$

$$(a_1, b_1), \dots, (a_m, b_m) \in B_{q_*}^n \times [-1, 1]$$

- Linear regression model

$$\min \left\{ \underbrace{\frac{1}{m} \sum_{j=1}^m (a_j^T x - b_j)^2}_{\mathcal{F}_{\|\cdot\|_q}(2,L)} : \underbrace{\|x\|_p \leq 1}_{B_p^n} \right\}$$

ℓ_p/ℓ_q -Lower Bounds

Range q	Range p	Rate LB	UB/LB
$1 \leq q \leq 2$	$p < q$	$\tilde{\Omega} \left(\frac{1}{T^{\kappa[\frac{3}{2} + \frac{1}{p} - \frac{1}{q}] - 1}} \right)$	$\tilde{O} \left(T^{\kappa[\frac{1}{p} - \frac{1}{q}]} \right)$
	$p \geq q$	$\tilde{\Omega} \left(\frac{n^{\kappa[\frac{1}{q} - \frac{1}{p}]}}{T^{\frac{3\kappa}{2} - 1}} \right)$	$\tilde{O}(1)$
$2 < q \leq \infty$	$p < q$	$\tilde{\Omega} \left(\frac{1}{T^{\kappa[1 + \frac{1}{p}] - 1}} \right)$	$\tilde{O} \left(T^{\kappa[\frac{1}{p} - \frac{1}{q}]} \right)$
	$p \geq q$	$\tilde{\Omega} \left(\frac{n^{\kappa[\frac{1}{q} - \frac{1}{p}]}}{T^{\kappa[1 + \frac{1}{q}] - 1}} \right)$	$\tilde{O}(1)$

Analogous LBs for matrix Schatten norms

Non-Standard Settings

Application: Compressed Sensing ($p = 1, q = 2$)

$$\min\{\|Ax - b\|_2^2 : \|x\|_1 \leq 1\}$$

$$\text{UB} = O\left(\frac{1}{T^2}\right) \quad \text{vs} \quad \text{LB} = \Omega\left(\frac{1}{T^3}\right)$$

Conjecture

In the $\ell_1 - \ell_2$ setup above, oracle complexity is $\ll \frac{1}{T^2}$

When it would be useful?

- E.g., compressed sensing

$$(p = 1, q = 2, \text{ and } f(x) = \|Ax - b\|_2^2)$$

- Smoothness constants

$$\|A\|_{1 \rightarrow 1} \leq \|A\|_{1 \rightarrow 2} \leq \sqrt{m} \|A\|_{1 \rightarrow 1}$$

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- Complexities (*if conjecture were true*)

$$O\left(\frac{\|A\|_{1 \rightarrow 1}^2}{T^2}\right) \quad \text{vs.} \quad O\left(\frac{\|A\|_{1 \rightarrow 2}^2}{T^3}\right)$$

- Substantial acceleration when $\|A\|_{1 \rightarrow 1} \approx \|A\|_{1 \rightarrow 2}$