



Complex Event Detection and Prediction in Traffic

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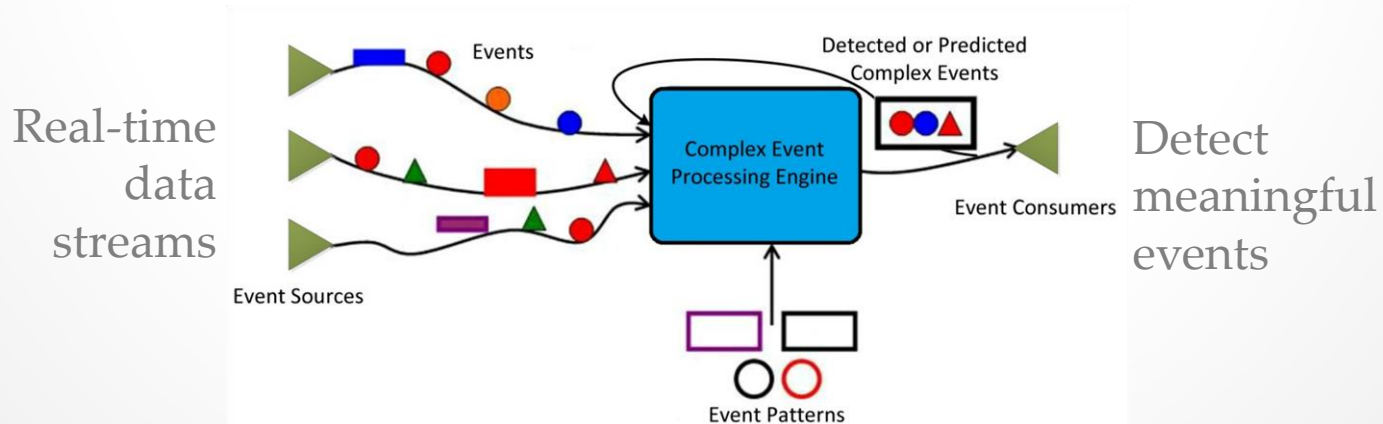


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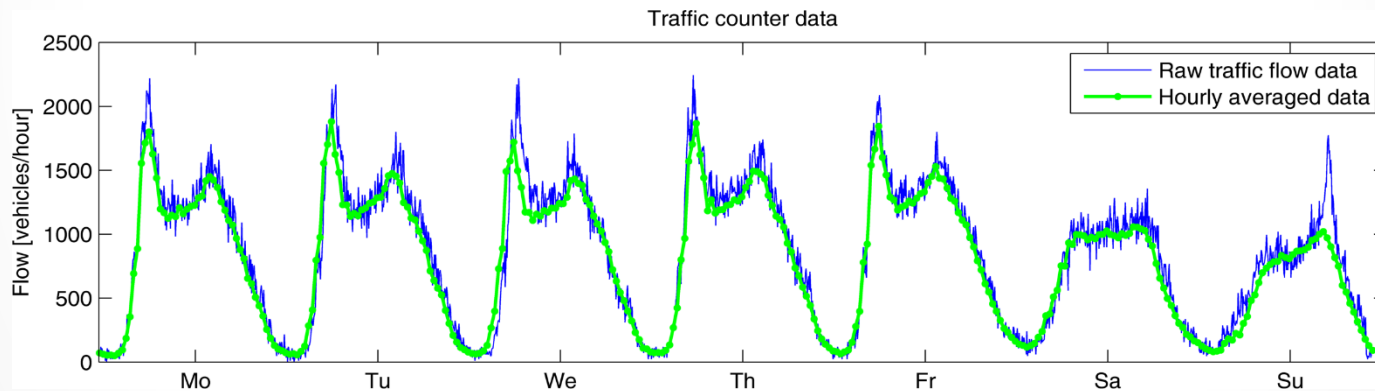
Motivation

- Develop Complex Event Processing system (CEP) that could detect (and predict) complex events in traffic
- Background knowledge required:
 - From domain expert
 - Using data mining techniques



Complex events in traffic

- Most traffic is caused by predictable events such as working schedules
 - Known bottlenecks, School schedules, Holidays,...



- Research how bigger social events affects on traffic nearby – Extract rules

Outline

- Data description
 - Description of used data sources
- Data preprocessing:
 - Complex event detection
 - Database of extracted complex events
- Data mining results:
 - Analyze how social events affect on nearby traffic
 - Find correlations between different complex events
 - Find rules to predict complex traffic events

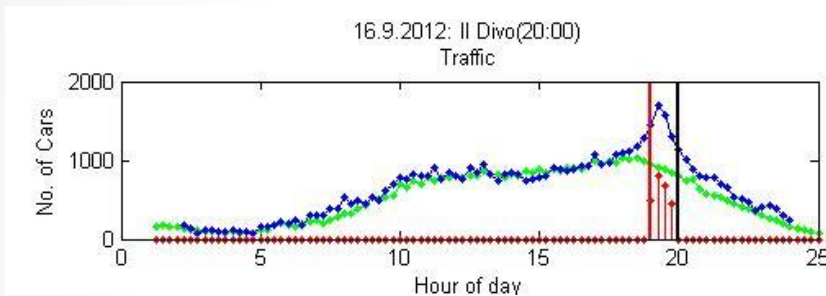
Data description

- Traffic Counters
 - Flow (vehicles/hour)
 - 5 min stream
 - 2011-2013
- Social events
 - 50 major social events
 - Stadium Stozice
 - Demand (1-4)
- Parking sensors
 - Parking availability count



Complex event detection

Traffic data

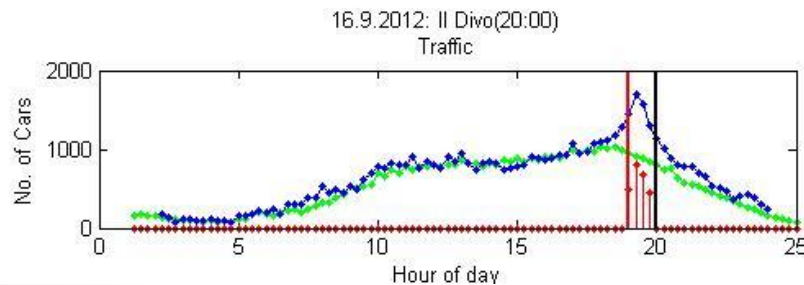


Traffic complex event: “ $t - 60$ ”

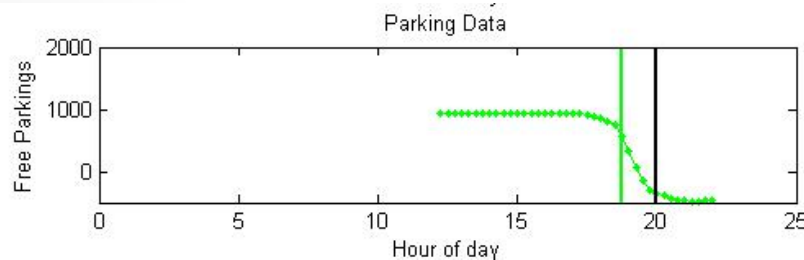
- Complex event is considered as the start of an anomaly
- Local averages are used to describe “normal” traffic
- Anomaly: if RMSE is larger than certain threshold

Complex event detection

Parking data



Traffic complex event: “ $t - 60$ ”

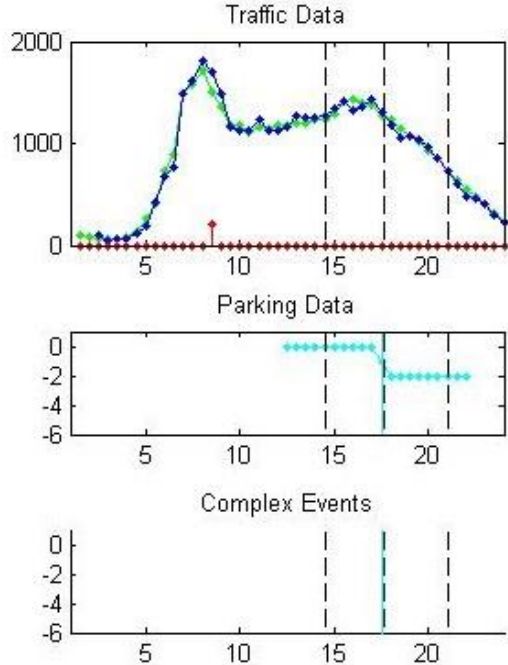


Parking complex event: “ $t - 90$ ”

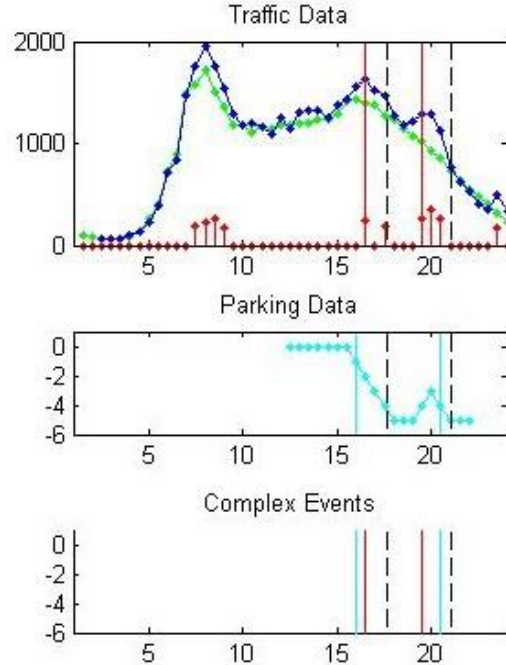
- Parking sensor did not have specific daily pattern
- Complex event in parking sensor is considered as start of “*downward trend*” in parking availability

Complex event detection

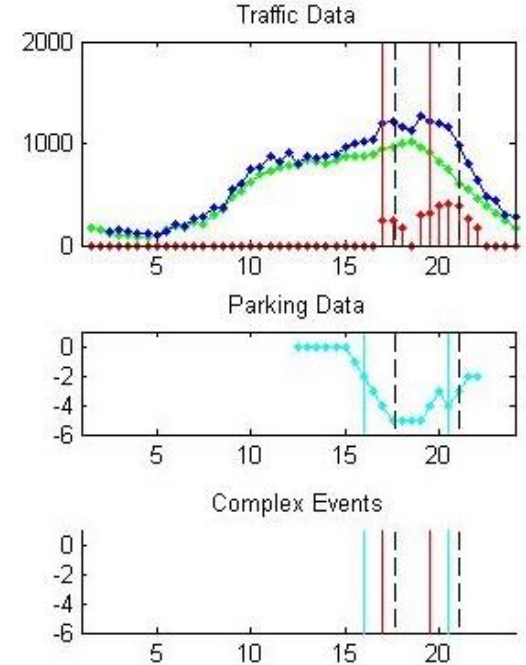
11.9.2013: lat-ukr(14:30), bel-srb(17:45), ltu-fra(21:00)



18.9.2013: srb-esp(17:30), slo-fra(21:00)



22.9.2013: esp-cro(17:30), fra-ltu(21:00)



Extracted data set

Event Description	Date	Hour	Visitors	Demand	Parking Sensor	Traffic Sensor
...
SLO - UKR	21.09.2013	21:00	10000	4	t-90	t-90
ESP - CRO	22.09.2013	17:30	6050	2	t-90	t-30
FRA - LTU	22.09.2013	21:00	10000	4	t-30	t-90
Elton John	11. 11. 2011	21:00	8000	3	?	t-60
...

- **Event demand attribute:** 4 possible values (1-4)
- **Parking sensor attribute:** 5 possible vales (“no” – “t-90”)
- **[Target] Traffic sensor attribute:** 5 possible vales (“no” – “t-90”)

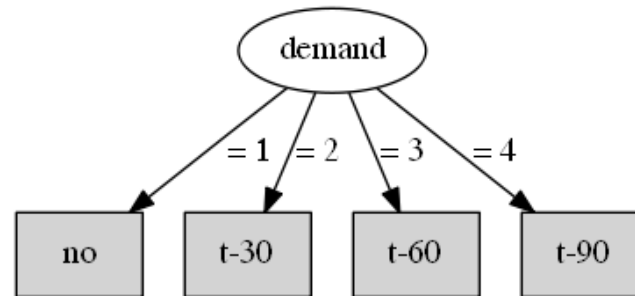
- **Number of instances:** 50 (number of events)

* UCI Machine Learning Repository – Dogers Loop Sensor Data Set (81 events)

* "Adaptive event detection with time-varying Poisson processes" A. Ihler, J. Hutchins, and P. Smyth. Proceedings of the 12th ACM SIGKDD Conference (KDD-06), August 2006.

Decision tree

- Decision Tree (*Wekas J48) - Pruned



- Target attribute: Traffic
- Evaluation:

Correctly Classified Instances: **76.6 % (36)**

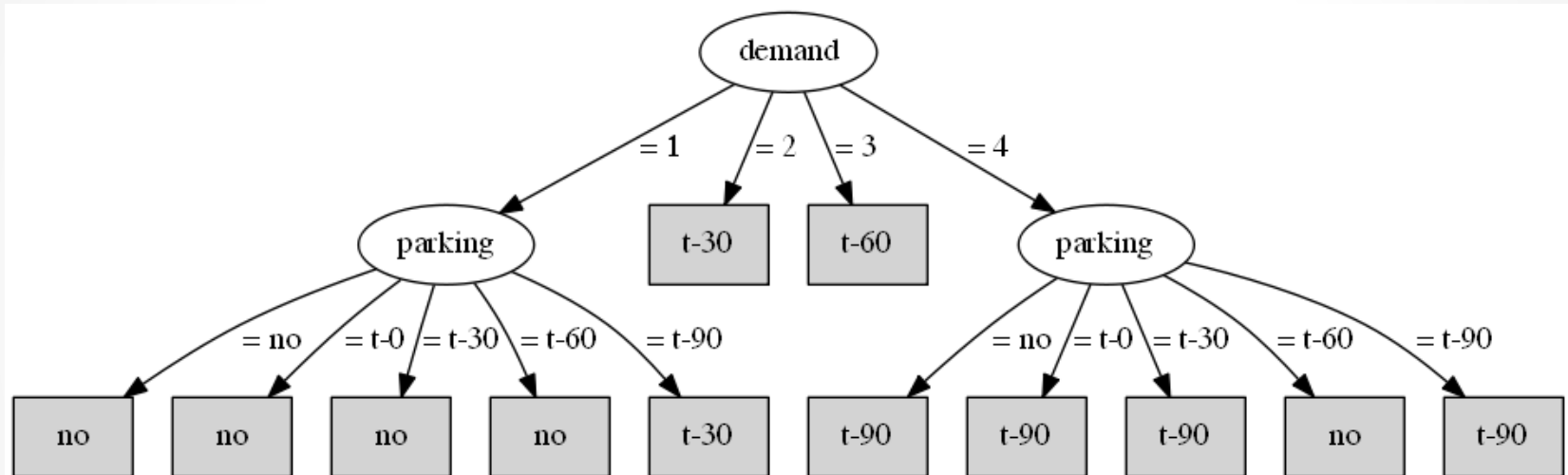
Incorrectly Classified Instances: **23.4 % (11)**

Baseline Classification (ZeroR): 38.3%

```
=== Confusion Matrix ===  
  
 a  b  c  d  <-- classified as  
17  0  0  1 | a = no  
 3  4  1  1 | b = t-30  
 1  1  8  2 | c = t-60  
 0  0  1  7 | d = t-90
```

Decision tree

- Decision Tree (Wekas J48) - Unpruned



- Evaluation:

Correctly Classified Instances: **74.5 % (35)**

Incorrectly Classified Instances: **25.5 % (12)**

Baseline Classification (ZeroR): 38.3%

=== Confusion Matrix ===

a	b	c	d	<-- classified as
17	0	0	1	a = no
3	4	1	1	b = t-30
1	2	7	2	c = t-60
0	0	1	7	d = t-90

Rule learner

- JRIP Rules - Pruned

```
JRIP rules:
=====

(demand = 4) => traffic=t-90
(demand = 2) => traffic=t-30
(demand = 3) => traffic=t-60
=> traffic=no
```

- Evaluation:

Correctly Classified Instances: **76.6% (36)**

Incorrectly Classified Instances: **23.4 % (11)**

Baseline Classification (ZeroR): 38.3%

```
=== Confusion Matrix ===
```

	a	b	c	d	<-- classified as
17	0	0	1	1	a = no
3	4	1	1	1	b = t-30
1	1	8	2	1	c = t-60
0	0	1	7	1	d = t-90

Rule learner

- JRIP Rules - Unpruned

```
JRIP rules:
=====

(demand = 4) and (parking = t-30) => traffic=t-90
(demand = 4) and (parking = t-90) => traffic=t-90
(demand = 2) => traffic=t-30
(demand = 3) and (parking = t-90) => traffic=t-60
(demand = 3) => traffic=t-60
=> traffic=no
```

- Evaluation:

Correctly Classified Instances: **74.5 % (35)**

Incorrectly Classified Instances: **25.5 % (12)**

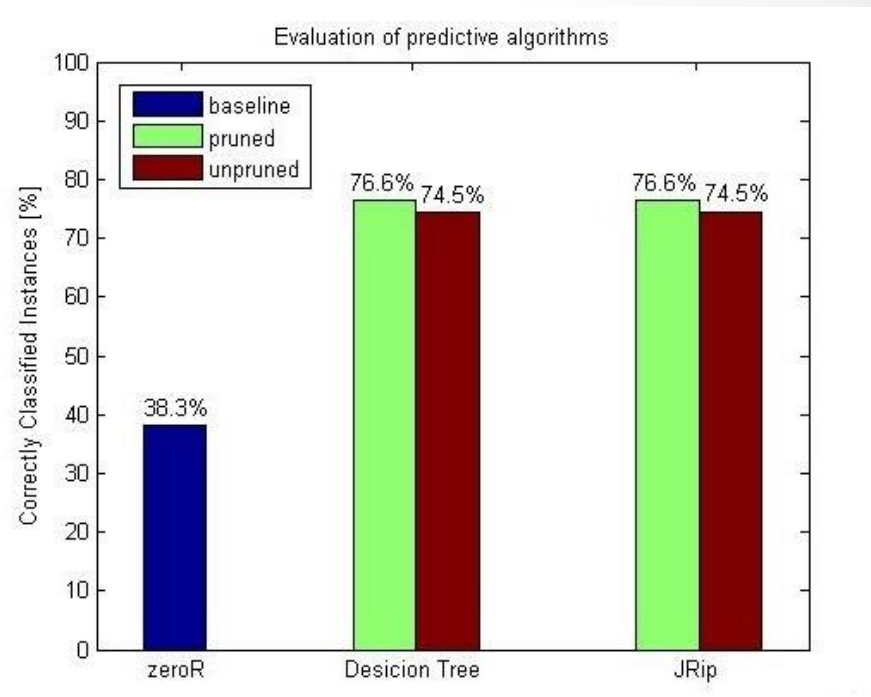
Baseline Classification (ZeroR): 38.3%

```
=== Confusion Matrix ===
```

a	b	c	d	<-- classified as
18	0	0	0	a = no
3	4	1	1	b = t-30
2	1	8	1	c = t-60
2	0	1	5	d = t-90

Conclusions

- Extracted rules:
 - demand 4 -> traffic “t-90”
 - ...
- More data sources, more complex rules
 - Weather, traffic reports, ...
- Can lead to automated rule generation
 - Extracting rules for large number of sensors



Thank You
any questions?

