



# Core Decomposition of Uncertain Graphs

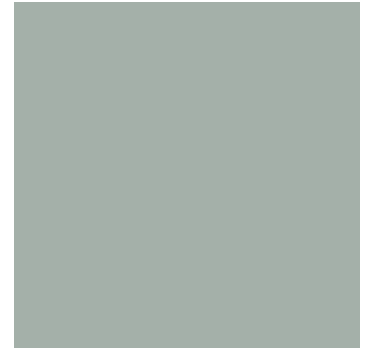
**Francesco Bonchi** (Yahoo Labs, Barcelona)

**Francesco Gullo** (Yahoo Labs, Barcelona)

**Andreas Kaltenbrunner** (Barcelona Media)

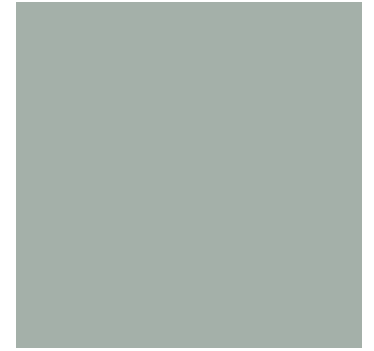
**Yana Volkovich** (Cornell Tech, Barcelona Media)

# Introduction



Core Decomposition of Uncertain Graphs

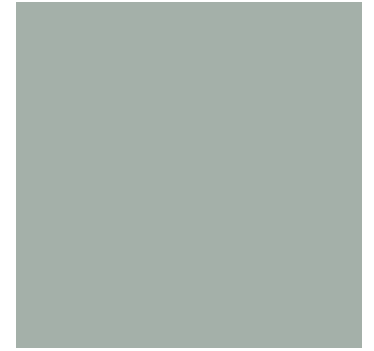
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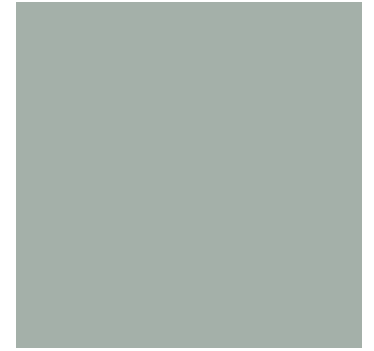
# Dense subgraphs

- finding dense subgraphs is a fundamental primitive in many graph problems



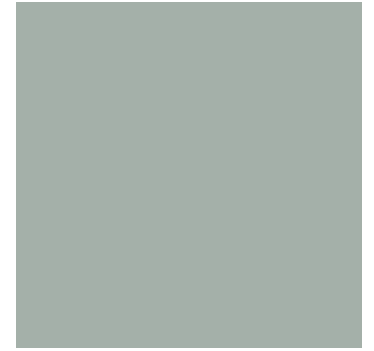
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- different definitions of dense subgraphs: cliques, n-cliques, n-clans, k-plexes, k-cores, etc.



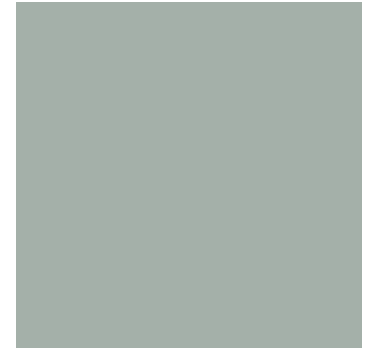
# Dense subgraphs

- finding dense subgraphs is a fundamental primitive in many graph problems
- different definitions of dense subgraphs: cliques, n-cliques, n-clans, k-plexes, k-cores, etc.
- most of them are computationally prohibitive: **NP-hard** or at least quadratic



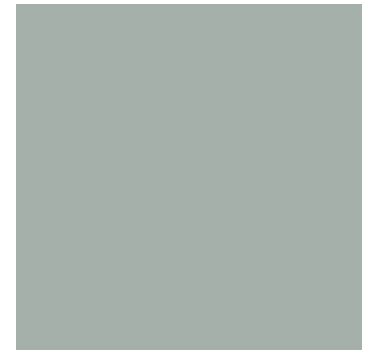
# k-core decomposition

- core decomposition is particularly appealing:
  - it can be computed in linear time
  - it relates to many definitions of dense subgraphs



# k-core decomposition

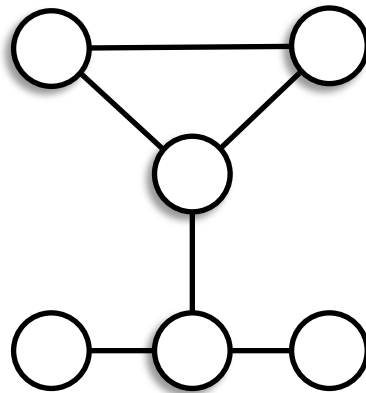
- $G = (V, E)$  is an undirected graph
- **k-core** of  $G$  is a maximal subgraph  $H = (C, E | C)$  such that  $\forall v \in C : \deg_H(v) \geq k$





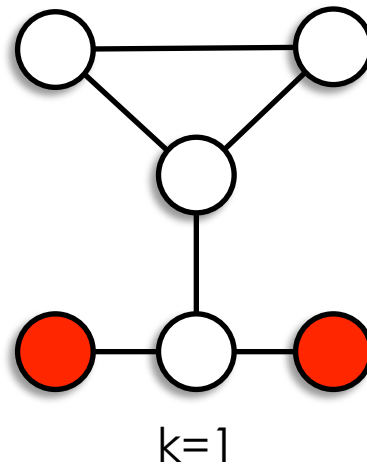
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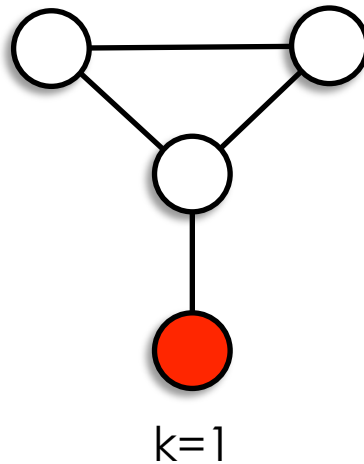
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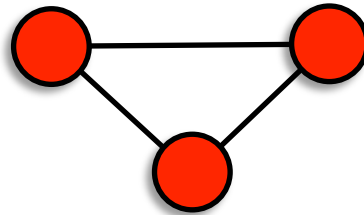
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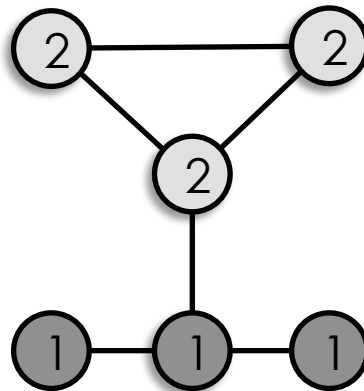
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$k=2$

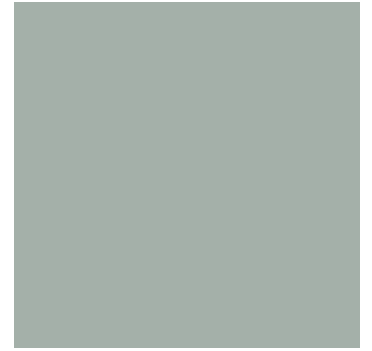
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- **core index** of a vertex  $v$  is the highest order of a core that contains  $v$

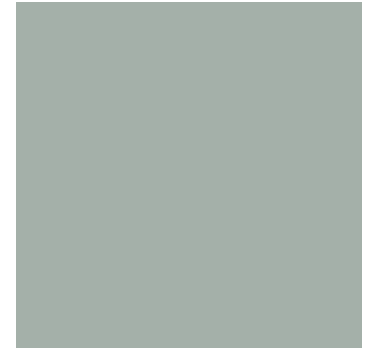
# Introduction



Core Decomposition of **Uncertain Graphs**

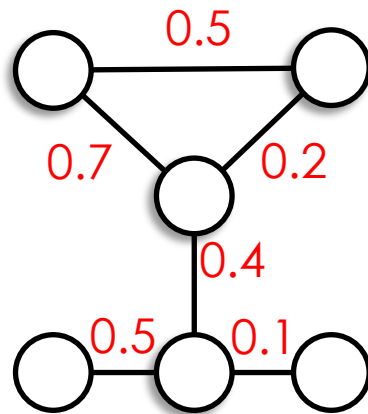
# Uncertain graphs

- Many real live networks are associated with uncertainty:
  - data collection process
  - employed machine-learning methods
  - privacy-preserving reasons
- biological networks, protein-interaction networks
- social networks



# Uncertain graphs

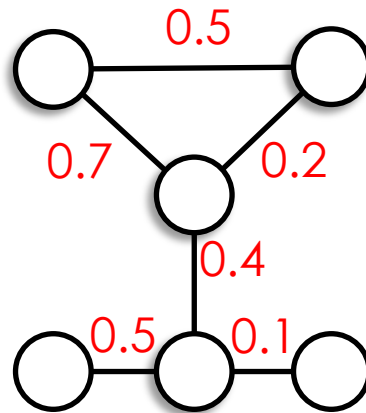
- Edges in an **uncertain graph** are associated with a probability of existence





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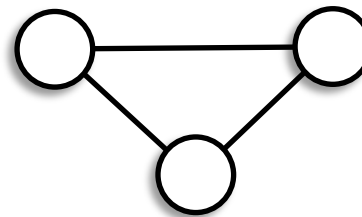
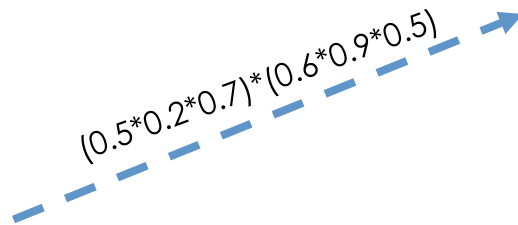
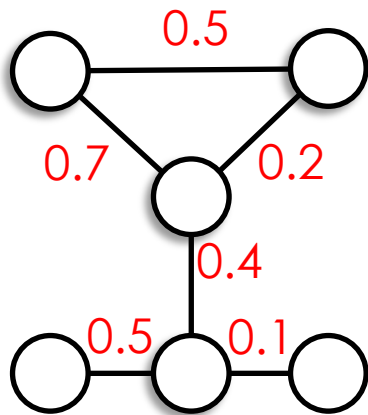


- **Uncertain graph** is a generative model for deterministic graphs

# Uncertain graphs

- $\mathcal{G} = (V, E, p)$  be **an uncertain graph**:

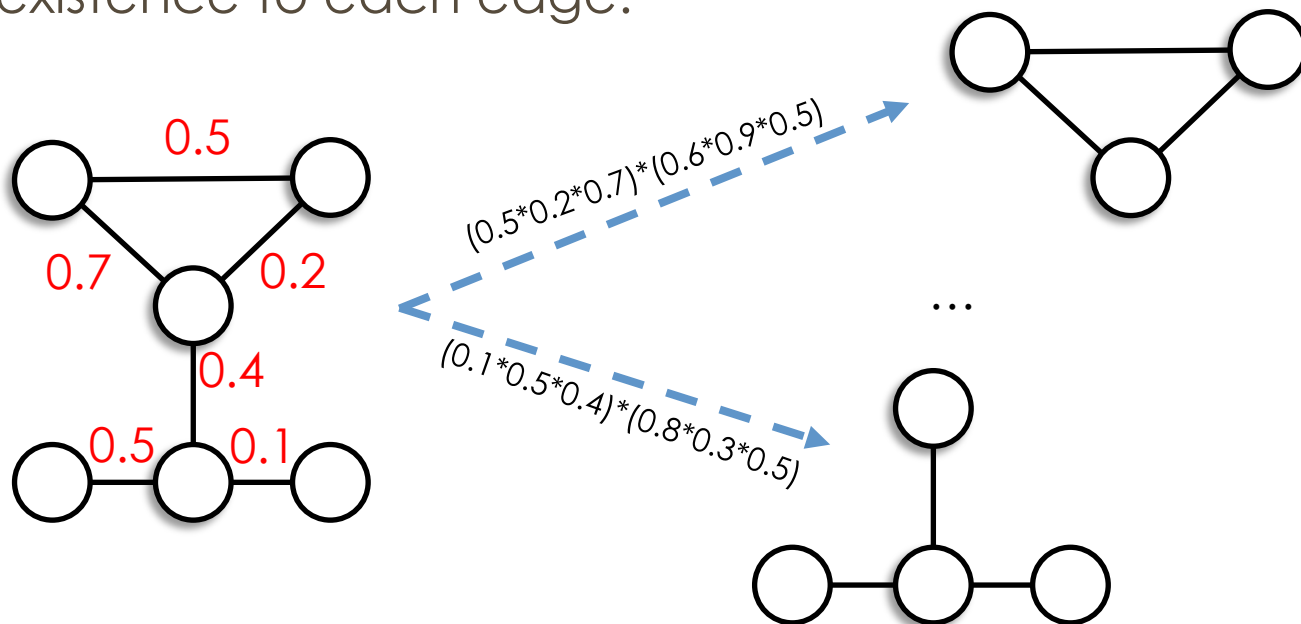
$p : E \rightarrow (0, 1]$  is a function that assigns a probability of existence to each edge.



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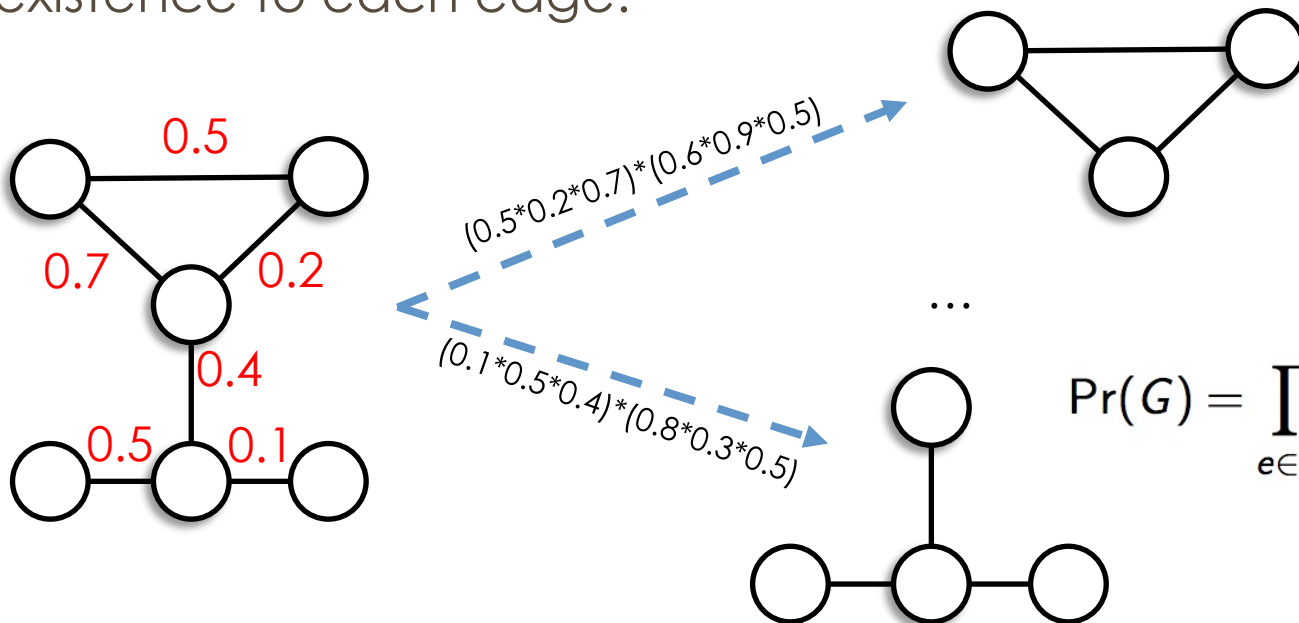
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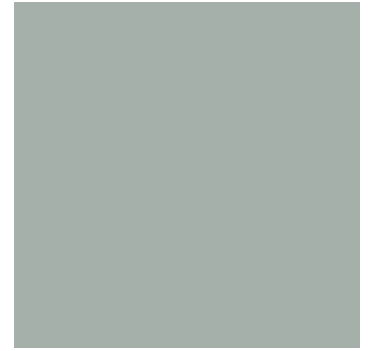
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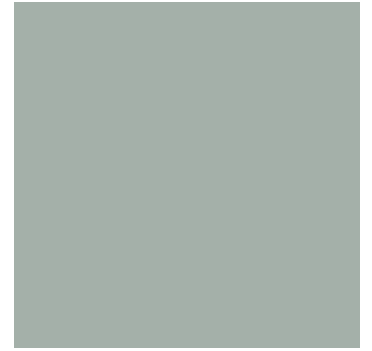
$$\Pr(G) = \prod_{e \in E_G} p_e \prod_{e \in E \setminus E_G} (1 - p_e)$$

# Introduction

Core Decomposition of Uncertain Graphs



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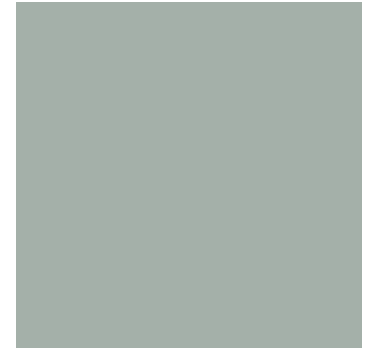


## Core Decomposition of Uncertain Graphs

We want to extend the graph tool of core decomposition to the context of uncertain graphs.

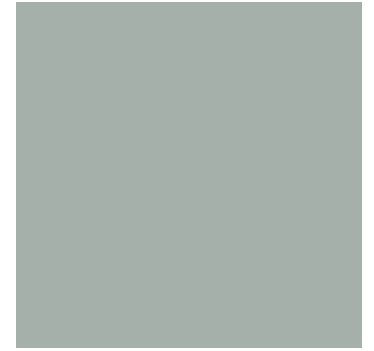
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- The fact that core decomposition can be performed in linear time in deterministic graphs does not guarantee efficiency in uncertain graphs.



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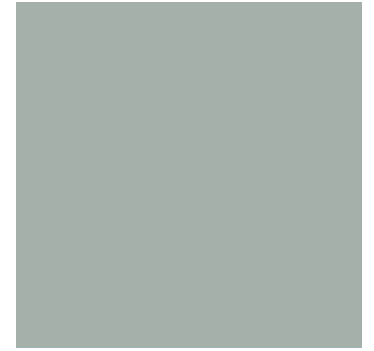
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- Are any two vertices connected?





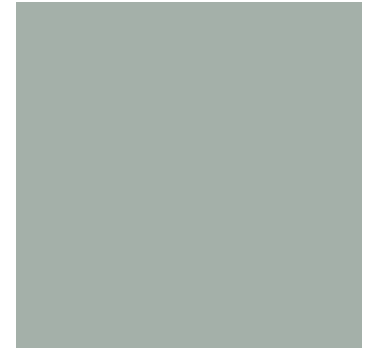
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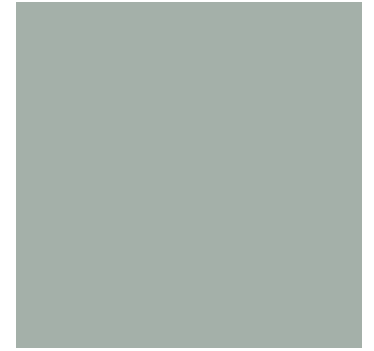
- The fact that core decomposition can be performed in linear time in deterministic graphs does not guarantee efficiency in uncertain graphs.
- Are any two vertices connected?
  - in deterministic graph: a simple scan of the graph
  - in uncertain graph: computing the probability that two vertices are connected is a #P-complete problem



# Probabilistic $(k, \eta)$ -cores

- uncertain graph  $\mathcal{G} = (V, E, p)$
- threshold of uncertainty  $\eta \in [0, 1]$

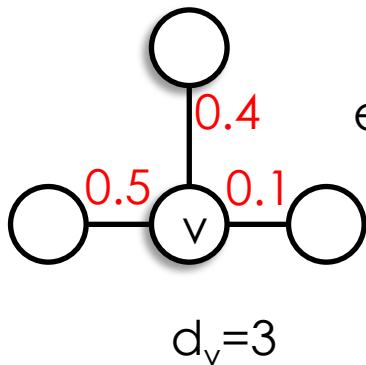
**Probabilistic  $(k, \eta)$ -core** of  $\mathcal{G}$  is a maximal subgraph  $H = (C, E | C, p)$  such that  $\forall v \in C : \Pr[\deg_H(v) \geq k] \geq \eta$



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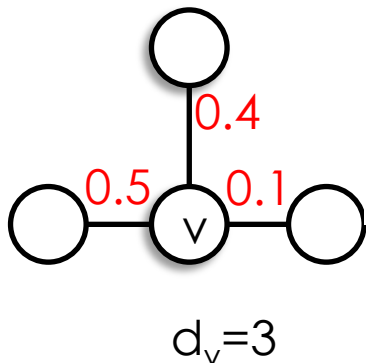


e.g.  $\Pr[\deg(v) \geq 2] = \Pr[\deg(v) = 2] + \Pr[\deg(v) = 3] =$   
 $= (0.1 * 0.5 * 0.6 + 0.1 * 0.4 * 0.5 + 0.5 * 0.4 * 0.9) + (0.5 * 0.1 * 0.4)$

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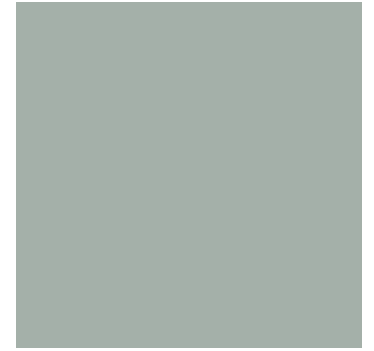


$$\Pr[\deg(v) \geq k] = \sum_{i=k}^{d_v} \Pr[\deg(v) = i] = 1 - \sum_{i=0}^{k-1} \Pr[\deg(v) = i]$$

This probability is monotonically non-increasing with  $k$

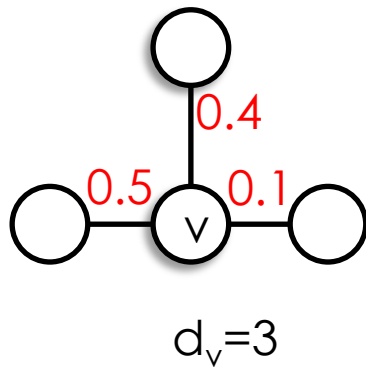
# Probabilistic $(k, \eta)$ -cores

- **$\eta$ -degree** of any vertex  $v \in V$  is defined as  
 $\eta\text{-deg}(v) = \max \{ k \in [0..d_v] \mid \Pr[\text{deg}(v) \geq k] \geq \eta \}$



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$$\eta = 0.02 \quad \eta\text{-deg} = 3$$

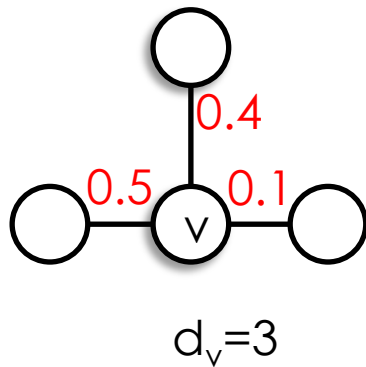
$$\eta = 0.25 \quad \eta\text{-deg} = 2$$

$$\eta = 0.73 \quad \eta\text{-deg} = 1$$

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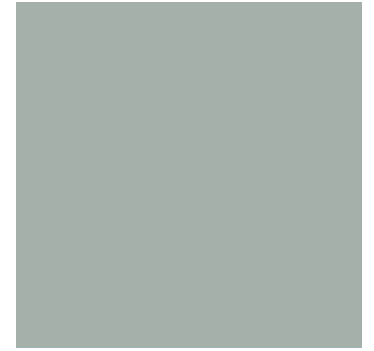
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- We use  $\eta$ -degree to define  **$(k, \eta)$ -core decomposition** in a similar manner as degree in deterministic case.



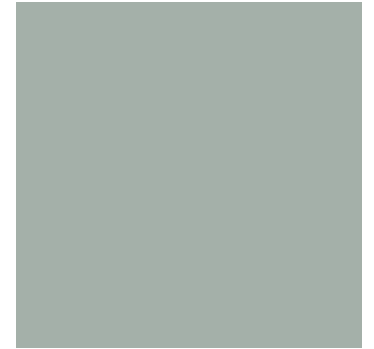
# Computing probabilistic cores

- We have proven uniqueness and existence of  $(k, \eta)$ -core decomposition of  $\mathcal{G}$ .



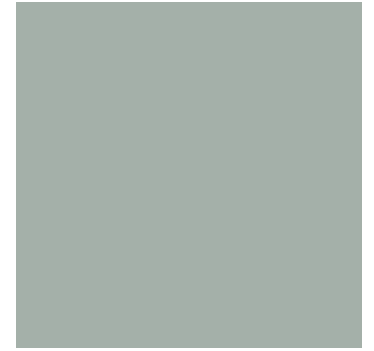
# Computing probabilistic cores

- Since naive computation of  $\eta$ -degrees leads to exponential time complexity, we defined a dynamic-programming method for  $(k, \eta)$ -core decomposition.



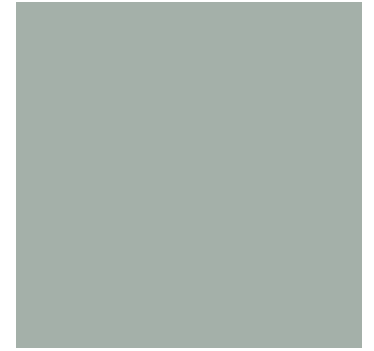
# Computing probabilistic cores

- We have shown the running time of  $(k, \eta)$ -core decomposition is  $\mathbf{O(m\Delta)}$ , where
  - $m$  is the number of edges
  - $\Delta$  is the maximum  $\eta$ -degree over all vertices



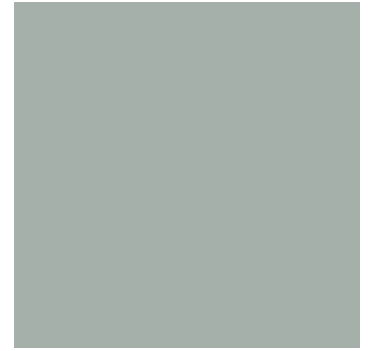
# Computing probabilistic cores

- We have derived a fast-to-compute lower bound on the  $\eta$ -degree to speed up  $(k, \eta)$ -core computations.



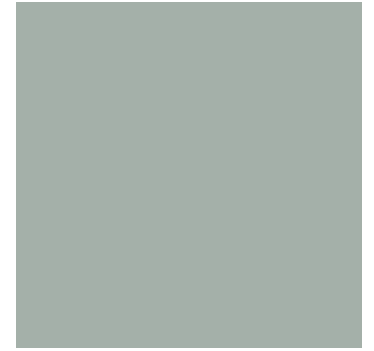
# Applications

1. Task-driven team formation
2. Influence-maximization problem



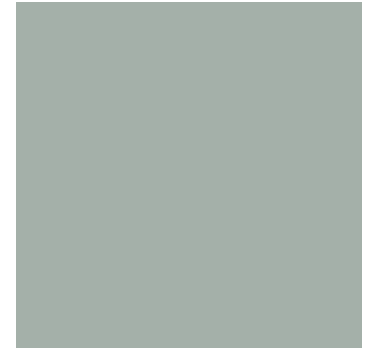
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- A collaboration graph:
  - vertices are individuals
  - edges exhibit a probabilistic topic model representing the topic(s) of past collaborations



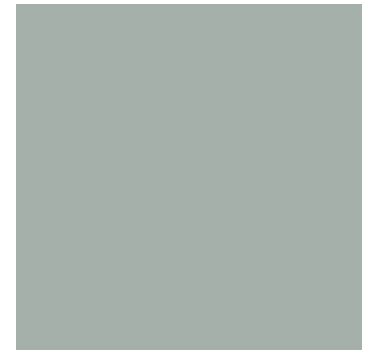
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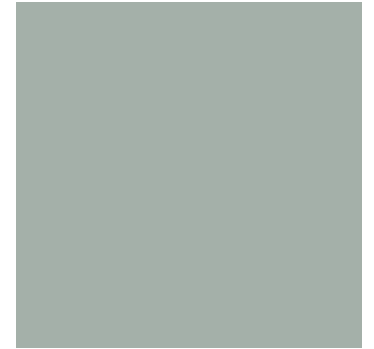
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- A query is a pair  $\langle T, Q \rangle$ :
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  - Q is a set of vertices
- The goal is to find an answer set of vertices A, such that  $A \supseteq Q$  is a good team for the task described by T.





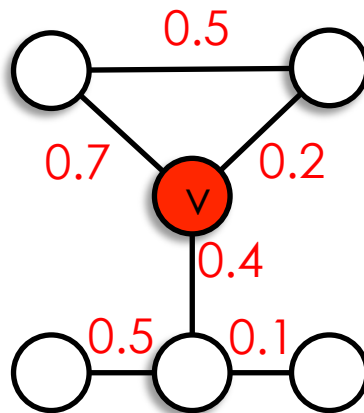
## 2. Influence-maximization problem

- **Independent cascade (IC) model:**
  - Links have associated probability;
  - Every active node  $v$  has a single chance of activating each currently inactive neighbor  $w$  with probability  $p_{vw}$



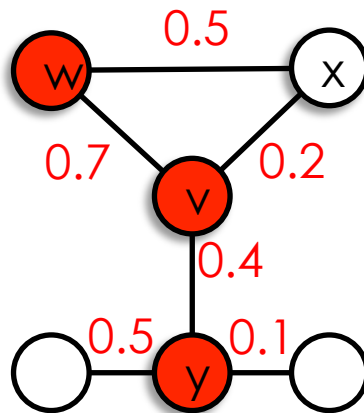
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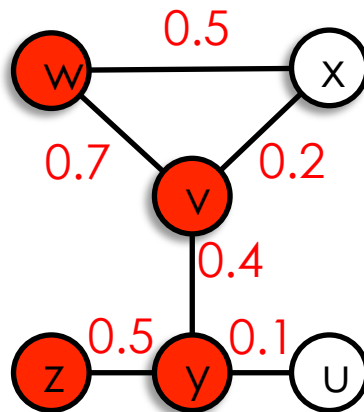
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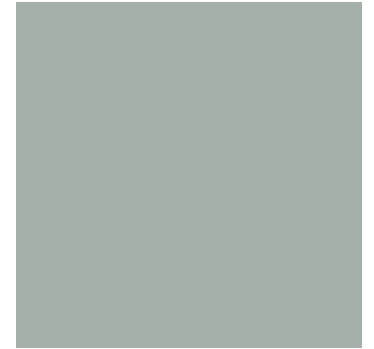
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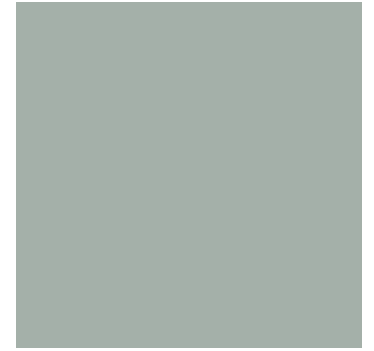
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- Finding a set  $S$ ,  $|S| = s$ , of vertices that maximizes the expected spread  $\sigma(S)$  is a **NP-hard** problem



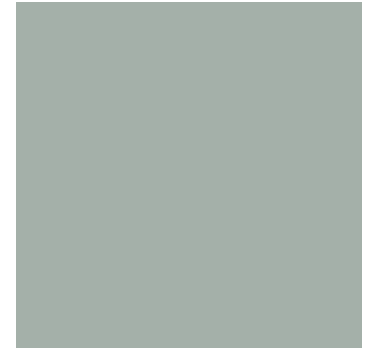
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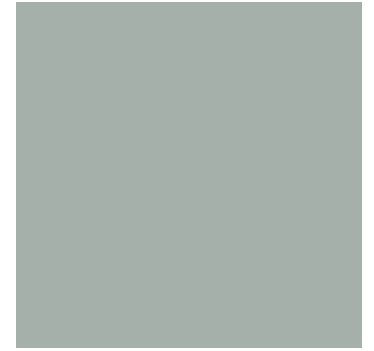
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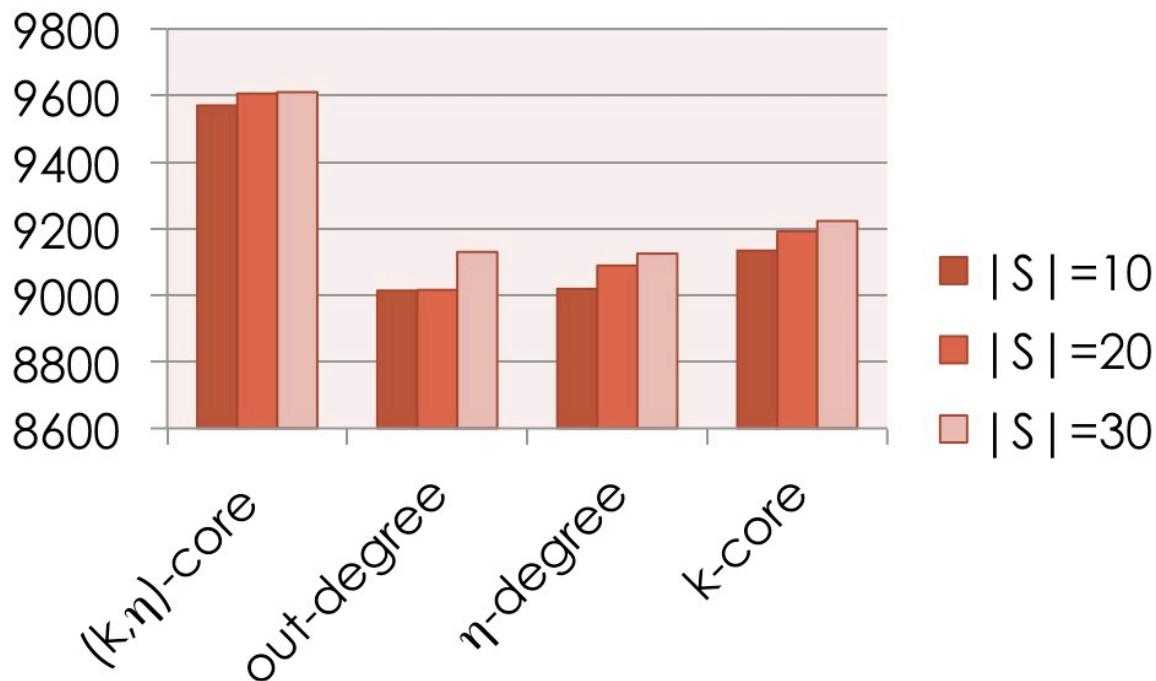
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- GREEDY algorithm adds the vertex bringing the largest marginal gain in the objective function.
- We reduce the input graph  $G$  by some rule and run the GREEDY algorithm.
- On deterministic graph  $k$ -core index is a direct indicator of the expected spread of any vertex (experimentally observed).





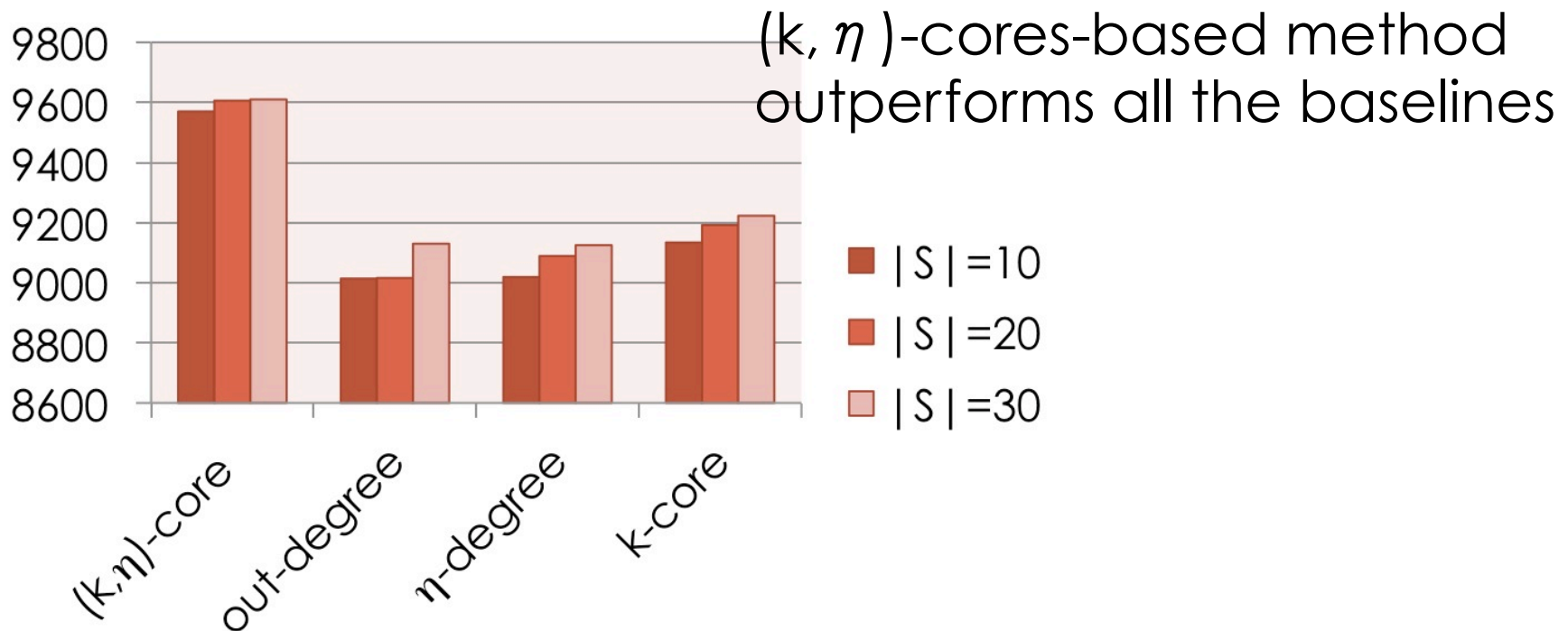
# Influence-maximization experiment

- Small directed graph from Twitter with influence probabilities learned from past propagations of URLs ( $|V| = 21882$ ,  $|E| = 372005$ ).



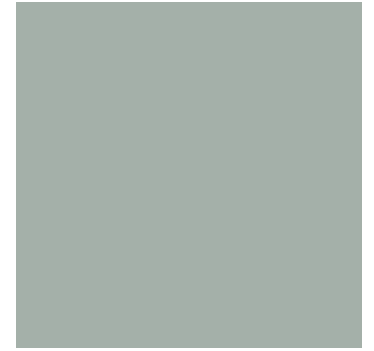
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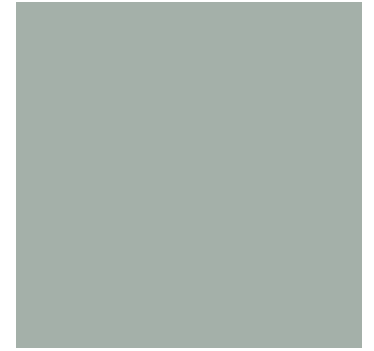
# Conclusions

- We have extended the graph tool of core decomposition to the context of uncertain graphs.



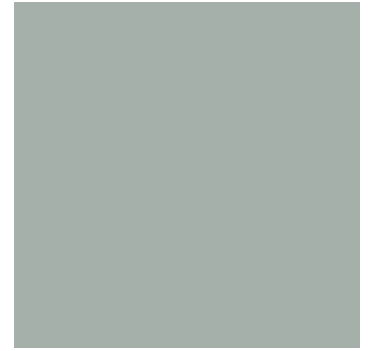
# Conclusions

- We have defined the  $(k, \eta)$ -core concept, and devised efficient algorithms for computing a  $(k, \eta)$ -core decomposition.



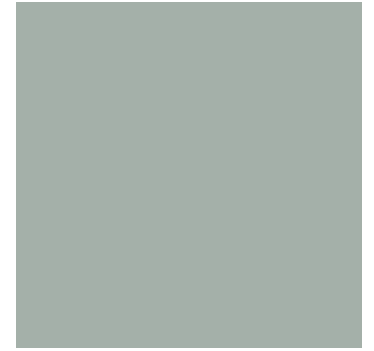
# Conclusions

- We have extensively evaluated our definitions and methods on a number of real-world datasets and applications.



# Conclusions

- We plan to investigate the relationship between  $(k, \eta)$ -cores and other definitions of (probabilistic) dense subgraphs.



Questions?

