

Towards Programmable Infrastructures: the Steps made by Cloud Computing and their Technical Support

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- ▶ Programmable Services of the Cloud
- ▶ Automatic Clouds
- ▶ Particular solutions for Automatic Clouds
- ▶ Conclusions

Programmable Infrastructures?

- ▶ Programmatic access
to the devices connected to the Internet
- ▶ Identified until recently with programmable networks
- ▶ Should involve:
 - ▶ network switches (Cloud networking),
 - ▶ simple gadgets or instruments (Internet-of-Things)
 - ▶ data center resources (Cluster, Grid, Cloud computing)
- ▶ Problem:
 - ▶ Manually intervention is still required in several processes involving e-infras settings

Grids and Clouds

▶ **Steps made by Grids:**

- ▶ Globus - marriage with Web services
- ▶ SAGA – Simple API for Grid Applications
 - ▶ job handling and monitoring, file transfer and management, distributed orchestration mechanisms.
 - ▶ Python and C++
 - ▶ Uniform Access-layer to DCI (EGI, XSEDE, DATAONE, UK NGS, NAREGI/RENEKI) and Clouds (recent)
- ▶ gEclipse
 - ▶ an integrated, Grid enabled workbench tool for Grid appl users, developers and operators based on the Eclipse platform

▶ **Steps made by Clouds:**

- ▶ (programmatic) elasticity in term of resources
- ▶ uniform treatment of infrastructure, software, networking as (programmable) services

Status of programming services for Clouds

- ▶ **Software-as-a-service**
 - ▶ hide completely the e-infrastructure from the user
- ▶ **Infrastructure-as-a-service**
 - ▶ still requires a manual intervention of the application deployers to set the execution environments,
- ▶ **Platform-as-a-service**
 - ▶ allows to reach a certain level of programmability.
 - ▶ elasticity promised as main characteristic of the Cloud computing is even not supported as feature by all PaaS
 - ▶ proprietary tools and APIs lead to a vendor lock-in problem hardly accepted by the users of PaaS

Requirements for programmability

1. To establish an **abstract model** of the resources that is sufficiently general
 - ▶ to catch the characteristics of a large variety of resources
 - ▶ to be able to be instantiated as unique resource representative by using the model parameters
2. A proper **programming paradigm** should be used to express the actions applied to these models.
3. Proper **tools** should support the resource models and programming paradigm.

Two perspectives of the programmability

1. The application developer

- ▶ interested to control programmatically the resources that are used for a particular applications
 - ▶ basic requirements need to be fulfilled, like
 - one point of access
 - immediate reaction in case of a resource fault
 - the control of the number of resources that are used

2. The infrastructure provider

- ▶ interested to reach a certain level of automatization by programmatic
 - ▶ self-management,
 - ▶ self-tuning,
 - ▶ self-configuration,
 - ▶ self-diagnosis, and
 - ▶ self-healing of the resource provisioning system.

mOSAIC's proposal for the appl developer

- ▶ Abstraction of the Cloud services that:
 - ▶ Ensures vendor agnosticity
 - ▶ Use the common denominator of several similar services
 - ▶ Implemented in the form of 'Connectors' and 'Drivers'
- ▶ Few points of entry:
 - ▶ From Eclipse when developing
 - ▶ Using the web interfaces when deploying and controlling
 - ▶ Assisted by a multi-agent system, semantic engine, cloud ontology and SLA mechanism to find the proper Cloud (i.e. multiple Clouds through a broker)
- ▶ The platform ensures:
 - ▶ Built-in fault tolerance mechanism
 - ▶ Web interface for controlling of the processes and resources that are consumed

Automatic Clouds: for the providers

- ▶ Represent the highest target of a programmable Cloud
 - ▶ Introducing automatic computing techniques in Clouds expected to reduce of the human intervention at the Cloud provider sites
- ▶ Particular suited for when rapid elasticity is requested
 - ▶ for adaptation to a variable number of requests
 - ▶ or to ensure the high level of reliability despite the potential massive failures.
- ▶ Existing proof-of-the-concept
 - ▶ are based on known methods from AI, like multi-agents systems, genetic algorithms, neural networks, multiobjective optimization heuristics, semantic engines etc
- ▶ mOSAIC PaaS
 - ▶ intends to be a deployable middleware for Cloud service providers
 - ▶ includes incipient form of support for Automatic Cloud

Research issues related to Automated Clouds in AMICAS supporting the mOSAIC extension

❖ Auto-scaler

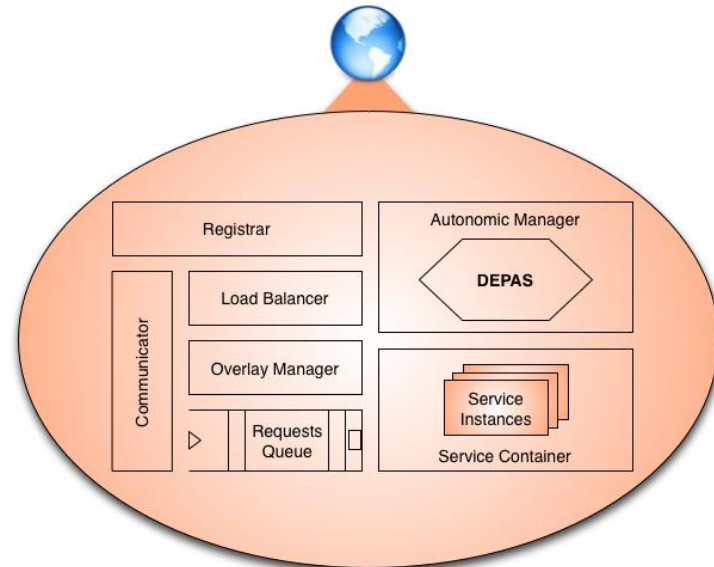
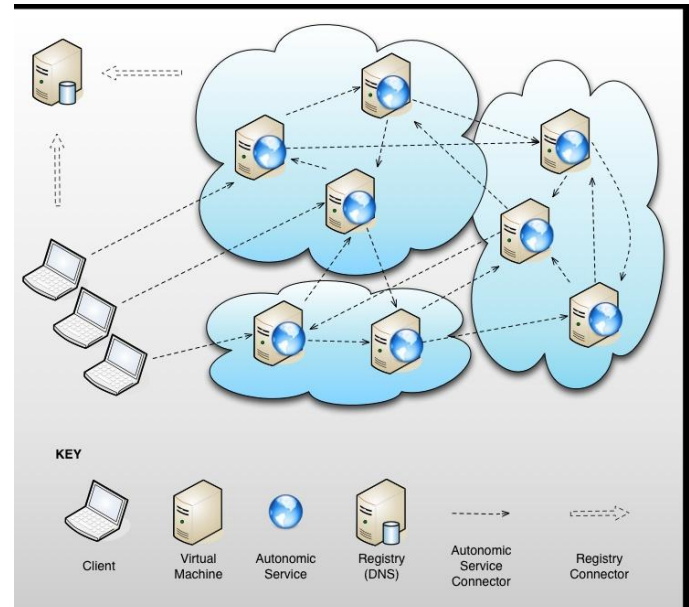
- N.M. Calcavecchia, B.A.Caprarescu, E. Di Nitto, D. J. Dubois, D. Petcu, *DEPAS: A Decentralized Probabilistic Algorithm for Auto-Scaling*, Computing, Springer, doi: 10.1007/s00607-012-0198-8, June 2012, available at <http://arxiv.org/abs/1202.2509>
- B. A. Caprarescu, D. Petcu. *Decentralized Probabilistic Auto-Scaling for Heterogeneous Systems*, ADAPTIVE 2012 – July 28, available at <http://arxiv.org/abs/1203.3885>

❖ Scheduler

- M. Frincu, *Scheduling Highly Available Applications on Cloud Environments*, Future Generation Computer Systems, May 2012, doi:10.1016/j.future.2012.05.017

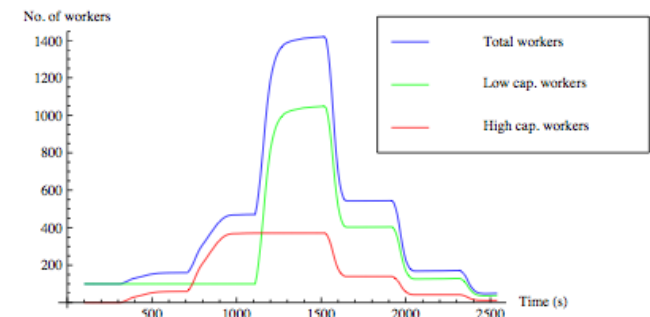
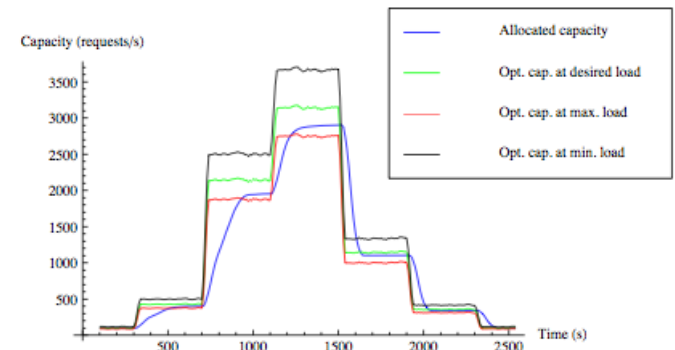
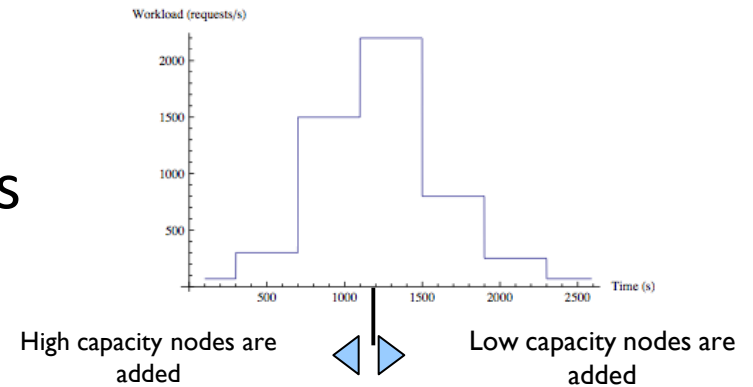
Auto-scaler (PhD stud. B. Caprarescu)

- ❖ Problem:
 - ❖ Most existing auto-scaling solutions are **centralized**
- ❖ Solution:
 - based on a P2P architecture
 - one autonomic service is deployed on each VM
- ❖ DEPAS algorithm:
 - each VM probabilistically decides to add new nodes or remove itself.
 - probability is computed based on an estimation of the average system load
 - the average system load is approximated by each node with the average load of itself and its neighbors



Auto-scaler (PhD stud. B. Caprarescu)

- ❖ Simulation results: ADAPTIVE procs
- ❖ On Amazon EC2: COMPUTING j.
- ❖ Test conclusions:
 - After a period of adaption, DEPAS allocates a right capacity (between the optimum capacity at max load and optimum capacity at min load)
 - The delay in adaptation is caused by the relatively high duration of load monitoring timeframe and cycle duration
 - The benefit comes in the high stability (no oscillations) which is impressive for a decentralized algorithm



Scheduler (PostDoc Marc Frincu)

❖ Problem:

- component-based apps can encounter failures of components
- a scaled application can span its components on several nodes
- finding the optimal no. component types needed on nodes so that every type is present on every allocated node
- cost restrictions and threshold for no. nodes

❖ Application to:

- Highly available Web 2.0 applications

❖ Novelty:

- Most of the approaches schedule VMs not components

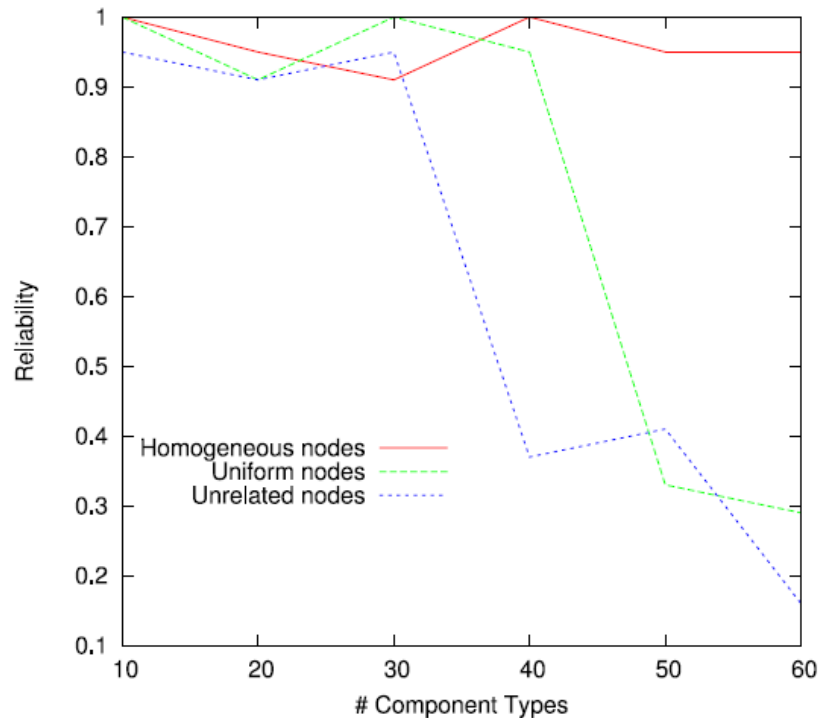
❖ Scheduling algorithms:

- One that produces an optimal solution in case when the load of every component is known
- One that produces a sub-optimal solution and relies on a GA to allocate components in case the component load is unknown

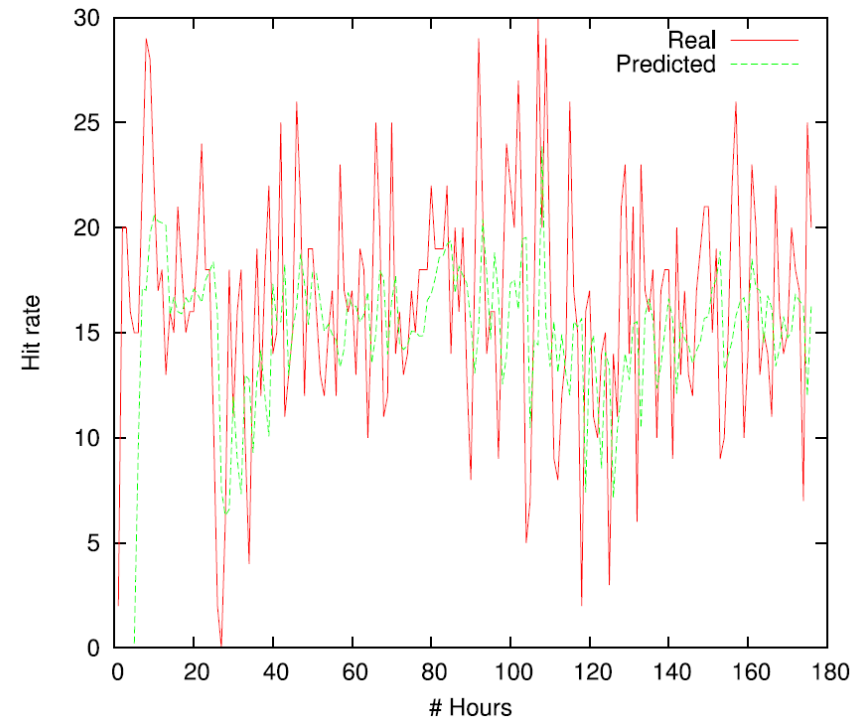
Scheduler (PostDoc Marc Frincu)

❖ Test goals:

- Ability to achieve high availability measured through reliability indicator
- Heterogeneity of the load on every node; expect load close to max of resource capacity



(a) Reliability.



Predicted vs. real traffic using neural networks

Conclusions

- ▶ **Programming infrastructure**
 - ▶ Is far from being well-supported, even in Clouds
 - ▶ Network, storage and computing are seen as pay-as-you-go services but still not integrated and collaborating sufficiently
- ▶ **Automatic Cloud**
 - ▶ Highest target of programmability that is emerging
 - ▶ Requires complex solutions involving SE and AI techniques
- ▶ **mOSAIC**
 - ▶ Has target until now the appl developer perspective
 - ▶ In one of its extension, **AMICAS**, first steps were made to support automatization, i.e. scheduler & auto-scaler