

Discriminative Experimental Design

Yu Zhang and Dit-Yan Yeung

Department of Computer Science and Engineering
The Hong Kong University of Science and Technology

ECML PKDD 2011

Outline

- 1 Introduction
- 2 Notations
- 3 Discriminative Experimental Design
- 4 Experiments
- 5 Conclusion

Active Learning

Active Learning

- Active learning **selects** unlabeled data points to query some **oracle**.

Active Learning

- Active learning **selects** unlabeled data points to query some **oracle**.
- Existing active learning methods: uncertainty sampling (**SVM Active Learning**), query-by-committee, representative sampling (**Transductive Experimental Design**).

Active Learning

- Active learning **selects** unlabeled data points to query some **oracle**.
- Existing active learning methods: uncertainty sampling (**SVM Active Learning**), query-by-committee, representative sampling (**Transductive Experimental Design**).

Input: Labeled data set \mathcal{L} ; Unlabeled data set \mathcal{U}

Output: Learning model

Step 1: Train a learning model based on \mathcal{L} ;

Step 2:

For $t = 1, \dots, t_{\max}$

2.1: Select an unlabeled data set \mathcal{S} from \mathcal{U} based on some **unlabeled data selection criterion**;

2.2: Query an oracle to label \mathcal{S} ;

2.3: $\mathcal{L} \leftarrow \mathcal{L} \cup \mathcal{S}, \mathcal{U} \leftarrow \mathcal{U} \setminus \mathcal{S}$;

2.4: Re-train the learning model based on \mathcal{L} ;

Our Contribution

Our Contribution

- Some methods are **complementary**.

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration
 - TED: Use of data **distribution** information; Selection of **multiple** points in an iteration

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration
 - TED: Use of data **distribution** information; Selection of **multiple** points in an iteration

- Our Contributions:

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration
 - TED: Use of data **distribution** information; Selection of **multiple** points in an iteration
- Our Contributions:
 - The proposal of discriminative experimental design (DED), **combining** the strengths of both SVM active learning and TED.

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration
 - TED: Use of data **distribution** information; Selection of **multiple** points in an iteration

- Our Contributions:
 - The proposal of discriminative experimental design (DED), **combining** the strengths of both SVM active learning and TED.
 - A **projection** method to solve the optimization problem.

Our Contribution

- Some methods are **complementary**.
 - SVM Active Learning: Use of **discriminative** information; Selection of **one** point in an iteration
 - TED: Use of data **distribution** information; Selection of **multiple** points in an iteration

- Our Contributions:
 - The proposal of discriminative experimental design (DED), **combining** the strengths of both SVM active learning and TED.
 - A **projection** method to solve the optimization problem.
 - The **good performance** on some benchmark datasets.

Outline

- 1 Introduction
- 2 Notations**
- 3 Discriminative Experimental Design
- 4 Experiments
- 5 Conclusion

Notations

Notations

- $\mathbf{V} \in \mathbb{R}^{d \times n}$: The matrix for the unlabeled data currently **available**

Notations

- $\mathbf{V} \in \mathbb{R}^{d \times n}$: The matrix for the unlabeled data currently **available**
- $\mathbf{X} \in \mathbb{R}^{d \times t}$: The **selected** subset of unlabeled data

Notations

- $\mathbf{V} \in \mathbb{R}^{d \times n}$: The matrix for the unlabeled data currently **available**
- $\mathbf{X} \in \mathbb{R}^{d \times t}$: The **selected** subset of unlabeled data
- t : The **number** of selected data points

Notations

- $\mathbf{V} \in \mathbb{R}^{d \times n}$: The matrix for the unlabeled data currently **available**
- $\mathbf{X} \in \mathbb{R}^{d \times t}$: The **selected** subset of unlabeled data
- t : The **number** of selected data points
- $\phi(\cdot)$: The **feature mapping** corresponding to some **kernel function**
 $k(\cdot, \cdot)$

Outline

- 1 Introduction
- 2 Notations
- 3 Discriminative Experimental Design**
- 4 Experiments
- 5 Conclusion

Least-Square SVM Revisited

Least-Square SVM Revisited

- The **objective function** of least-square SVM is formulated as:

$$\min_{\mathbf{w}} \sum_{i=1}^l (\mathbf{w}^T \phi(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}\|_2^2. \quad (1)$$

Least-Square SVM Revisited

- The **objective function** of least-square SVM is formulated as:

$$\min_{\mathbf{w}} \sum_{i=1}^l (\mathbf{w}^T \phi(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}\|_2^2. \quad (1)$$

- Its **equivalent** form:

$$\min_{\mathbf{w}} J(\mathbf{w}) = \sum_{i=1}^l (1 - y_i \mathbf{w}^T \phi(\mathbf{x}_i))^2 + \lambda \|\mathbf{w}\|_2^2. \quad (2)$$

Least-Square SVM Revisited

- The **objective function** of least-square SVM is formulated as:

$$\min_{\mathbf{w}} \sum_{i=1}^l (\mathbf{w}^T \phi(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}\|_2^2. \quad (1)$$

- Its **equivalent** form:

$$\min_{\mathbf{w}} J(\mathbf{w}) = \sum_{i=1}^l (1 - y_i \mathbf{w}^T \phi(\mathbf{x}_i))^2 + \lambda \|\mathbf{w}\|_2^2. \quad (2)$$

- Here the square loss is similar to the **square hinge loss**
 $L'(s, t) = \max(0, 1 - st)^2$.

Least-Square SVM Revisited

- The **objective function** of least-square SVM is formulated as:

$$\min_{\mathbf{w}} \sum_{i=1}^l (\mathbf{w}^T \phi(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}\|_2^2. \quad (1)$$

- Its **equivalent** form:

$$\min_{\mathbf{w}} J(\mathbf{w}) = \sum_{i=1}^l (1 - y_i \mathbf{w}^T \phi(\mathbf{x}_i))^2 + \lambda \|\mathbf{w}\|_2^2. \quad (2)$$

- Here the square loss is similar to the **square hinge loss**
 $L'(s, t) = \max(0, 1 - st)^2$.
- The **function score** for a data point is defined as:

$$y = \frac{1}{\mathbf{w}^T \phi(\mathbf{x})},$$

The Objective Function

The Objective Function

- According to the analysis in TED, the **estimation error** satisfies

$$\text{cov}(\mathbf{w} - \mathbf{w}^*) \propto \mathbf{C}_{\mathbf{w}} = \left(\frac{\partial^2 J(\mathbf{w})}{\partial \mathbf{w} \partial \mathbf{w}^T} \right)^{-1} = (\phi(\mathbf{X}) \mathbf{Y}_{\mathbf{x}}^2 \phi(\mathbf{X})^T + \lambda \mathbf{I}_{d'})^{-1}$$

The Objective Function

- According to the analysis in TED, the **estimation error** satisfies

$$\text{cov}(\mathbf{w} - \mathbf{w}^*) \propto \mathbf{C}_{\mathbf{w}} = \left(\frac{\partial^2 J(\mathbf{w})}{\partial \mathbf{w} \partial \mathbf{w}^T} \right)^{-1} = (\phi(\mathbf{X}) \mathbf{Y}_{\mathbf{X}}^2 \phi(\mathbf{X})^T + \lambda \mathbf{I}_{d'})^{-1}$$

- The **predictive error** on the whole unlabeled data set satisfies

$$\mathbf{C}_{\mathbf{f}} = \mathbf{Y}_{\mathbf{V}} \phi(\mathbf{V})^T \mathbf{C}_{\mathbf{w}} \phi(\mathbf{V}) \mathbf{Y}_{\mathbf{V}}$$

The Objective Function

- According to the analysis in TED, the **estimation error** satisfies

$$\text{cov}(\mathbf{w} - \mathbf{w}^*) \propto \mathbf{C}_{\mathbf{w}} = \left(\frac{\partial^2 J(\mathbf{w})}{\partial \mathbf{w} \partial \mathbf{w}^T} \right)^{-1} = (\phi(\mathbf{X}) \mathbf{Y}_{\mathbf{X}}^2 \phi(\mathbf{X})^T + \lambda \mathbf{I}_{d'})^{-1}$$

- The **predictive error** on the whole unlabeled data set satisfies

$$\mathbf{C}_{\mathbf{f}} = \mathbf{Y}_{\mathbf{V}} \phi(\mathbf{V})^T \mathbf{C}_{\mathbf{w}} \phi(\mathbf{V}) \mathbf{Y}_{\mathbf{V}}$$

- The **A-optimal design** is used to minimize the predictive variance:

$$\min \text{tr}(\mathbf{C}_{\mathbf{f}}).$$

The Objective Function

- According to the analysis in TED, the **estimation error** satisfies

$$\text{cov}(\mathbf{w} - \mathbf{w}^*) \propto \mathbf{C}_w = \left(\frac{\partial^2 J(\mathbf{w})}{\partial \mathbf{w} \partial \mathbf{w}^T} \right)^{-1} = (\phi(\mathbf{X}) \mathbf{Y}_X^2 \phi(\mathbf{X})^T + \lambda \mathbf{I}_{d'})^{-1}$$

- The **predictive error** on the whole unlabeled data set satisfies

$$\mathbf{C}_f = \mathbf{Y}_V \phi(\mathbf{V})^T \mathbf{C}_w \phi(\mathbf{V}) \mathbf{Y}_V$$

- The **A-optimal design** is used to minimize the predictive variance:

$$\min \text{tr}(\mathbf{C}_f).$$

Definition

Discriminative Experimental Design:

$$\begin{aligned} \max_{\mathbf{X}, \mathbf{Y}_X} \quad & \text{tr} \left[\mathbf{Y}_V \mathbf{K}_{VX} \mathbf{Y}_X (\lambda \mathbf{I}_t + \mathbf{Y}_X \mathbf{K}_X \mathbf{Y}_X)^{-1} \mathbf{Y}_X \mathbf{K}_{XV} \mathbf{Y}_V \right] \\ \text{s.t.} \quad & \mathbf{X} \subset \mathbf{V}, |\mathbf{X}| = t, \mathbf{Y}_X \subset \mathbf{Y}_V. \end{aligned} \quad (3)$$

The Relationship between DED and TED

The Relationship between DED and TED

- The optimization problem of **linear** DED:

$$\begin{aligned}
 \max_{\tilde{\mathbf{X}}} \quad & \text{tr} \left[\tilde{\mathbf{V}}^T \tilde{\mathbf{X}} (\lambda \mathbf{I}_t + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{V}} \right] \\
 \text{s.t.} \quad & \tilde{\mathbf{X}} \subset \tilde{\mathbf{V}}, |\tilde{\mathbf{X}}| = t.
 \end{aligned} \tag{4}$$

The Relationship between DED and TED

- The optimization problem of **linear** DED:

$$\begin{aligned} \max_{\tilde{\mathbf{X}}} \quad & \text{tr} \left[\tilde{\mathbf{V}}^T \tilde{\mathbf{X}} (\lambda \mathbf{I}_t + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{V}} \right] \\ \text{s.t.} \quad & \tilde{\mathbf{X}} \subset \tilde{\mathbf{V}}, |\tilde{\mathbf{X}}| = t. \end{aligned} \quad (4)$$

- This is **identical** to the optimization problem of TED.

The Relationship between DED and TED

- The optimization problem of **linear** DED:

$$\begin{aligned} \max_{\tilde{\mathbf{X}}} \quad & \text{tr} \left[\tilde{\mathbf{V}}^T \tilde{\mathbf{X}} (\lambda \mathbf{I}_t + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{V}} \right] \\ \text{s.t.} \quad & \tilde{\mathbf{X}} \subset \tilde{\mathbf{V}}, |\tilde{\mathbf{X}}| = t. \end{aligned} \quad (4)$$

- This is **identical** to the optimization problem of TED.
- TED can be seen as a **special case** of DED.

The Relationship between DED and TED

- The optimization problem of **linear** DED:

$$\begin{aligned} \max_{\tilde{\mathbf{X}}} \quad & \text{tr} \left[\tilde{\mathbf{V}}^T \tilde{\mathbf{X}} (\lambda \mathbf{I}_t + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{V}} \right] \\ \text{s.t.} \quad & \tilde{\mathbf{X}} \subset \tilde{\mathbf{V}}, |\tilde{\mathbf{X}}| = t. \end{aligned} \tag{4}$$

- This is **identical** to the optimization problem of TED.
- TED can be seen as a **special case** of DED.
- DED is a **weighted** version of TED.

The Relationship between DED and TED

- The optimization problem of **linear** DED:

$$\begin{aligned} \max_{\tilde{\mathbf{X}}} \quad & \text{tr} \left[\tilde{\mathbf{V}}^T \tilde{\mathbf{X}} (\lambda \mathbf{I}_t + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{V}} \right] \\ \text{s.t.} \quad & \tilde{\mathbf{X}} \subset \tilde{\mathbf{V}}, |\tilde{\mathbf{X}}| = t. \end{aligned} \quad (4)$$

- This is **identical** to the optimization problem of TED.
- TED can be seen as a **special case** of DED.
- DED is a **weighted** version of TED.
 - The weights are related to **function scores** of the data points.

Reformulation of DED

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_\mathbf{X})_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_\mathbf{V})_{,i} \\ 0 & \text{otherwise} \end{cases}$$

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_\mathbf{X})_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_\mathbf{V})_{,i} \\ 0 & \text{otherwise} \end{cases}$$

- The **constraint set** for \mathbf{S} is $C_S = \{\mathbf{S} \mid \mathbf{S} \in \{0, 1\}^{n \times t}, \mathbf{S}^T \mathbf{S} = \mathbf{I}_t\}$.

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_\mathbf{X})_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_\mathbf{V})_{,i} \\ 0 & \text{otherwise} \end{cases}$$

- The **constraint set** for \mathbf{S} is $C_S = \{\mathbf{S} \mid \mathbf{S} \in \{0, 1\}^{n \times t}, \mathbf{S}^T \mathbf{S} = \mathbf{I}_t\}$.
- The objective function of DED can be **reformulated** as

$$\begin{aligned} \max_{\mathbf{S}} \quad & \text{tr} \left[(\mathbf{S}^T (\lambda \mathbf{I}_n + \tilde{\mathbf{K}}_V) \mathbf{S})^{-1} \mathbf{S}^T \tilde{\mathbf{K}}_V^2 \mathbf{S} \right] \\ \text{s.t.} \quad & \mathbf{S} \in C_S, \end{aligned} \tag{5}$$

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_\mathbf{X})_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_\mathbf{V})_{,i} \\ 0 & \text{otherwise} \end{cases}$$

- The **constraint set** for \mathbf{S} is $C_S = \{\mathbf{S} \mid \mathbf{S} \in \{0, 1\}^{n \times t}, \mathbf{S}^T \mathbf{S} = \mathbf{I}_t\}$.
- The objective function of DED can be **reformulated** as

$$\begin{aligned} \max_{\mathbf{S}} \quad & \text{tr} \left[(\mathbf{S}^T (\lambda \mathbf{I}_n + \tilde{\mathbf{K}}_V) \mathbf{S})^{-1} \mathbf{S}^T \tilde{\mathbf{K}}_V^2 \mathbf{S} \right] \\ \text{s.t.} \quad & \mathbf{S} \in C_S, \end{aligned} \tag{5}$$

- If there is **no** constraint, the optimal solution has the form of $\mathbf{S}^* \mathbf{P}$.

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_X)_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_V)_{,i} \\ 0 & \text{otherwise} \end{cases}$$

- The **constraint set** for \mathbf{S} is $C_S = \{\mathbf{S} \mid \mathbf{S} \in \{0, 1\}^{n \times t}, \mathbf{S}^T \mathbf{S} = \mathbf{I}_t\}$.
- The objective function of DED can be **reformulated** as

$$\begin{aligned} \max_{\mathbf{S}} \quad & \text{tr} \left[(\mathbf{S}^T (\lambda \mathbf{I}_n + \tilde{\mathbf{K}}_V) \mathbf{S})^{-1} \mathbf{S}^T \tilde{\mathbf{K}}_V^2 \mathbf{S} \right] \\ \text{s.t.} \quad & \mathbf{S} \in C_S, \end{aligned} \tag{5}$$

- If there is **no** constraint, the optimal solution has the form of $\mathbf{S}^* \mathbf{P}$.
 - \mathbf{S}^* consists of the **top** t eigenvectors of $\tilde{\mathbf{K}}_V$.

Reformulation of DED

- A **selection indicator** matrix $\mathbf{S} \in \{0, 1\}^{n \times t}$ is defined as

$$s_{ij} = \begin{cases} 1 & \text{if } (\phi(\mathbf{X})\mathbf{Y}_X)_{,j} \text{ is from } (\phi(\mathbf{V})\mathbf{Y}_V)_{,i} \\ 0 & \text{otherwise} \end{cases}$$

- The **constraint set** for \mathbf{S} is $C_S = \{\mathbf{S} \mid \mathbf{S} \in \{0, 1\}^{n \times t}, \mathbf{S}^T \mathbf{S} = \mathbf{I}_t\}$.
- The objective function of DED can be **reformulated** as

$$\begin{aligned} \max_{\mathbf{S}} \quad & \text{tr} \left[(\mathbf{S}^T (\lambda \mathbf{I}_n + \tilde{\mathbf{K}}_V) \mathbf{S})^{-1} \mathbf{S}^T \tilde{\mathbf{K}}_V^2 \mathbf{S} \right] \\ \text{s.t.} \quad & \mathbf{S} \in C_S, \end{aligned} \tag{5}$$

- If there is **no** constraint, the optimal solution has the form of $\mathbf{S}^* \mathbf{P}$.
 - \mathbf{S}^* consists of the **top** t eigenvectors of $\tilde{\mathbf{K}}_V$.
 - $\mathbf{P} \in \mathbb{R}^{t \times t}$ is an **orthogonal** matrix.

The Projection Method

The Projection Method

- The optimal solution $\mathbf{S}^*\mathbf{P}$ is **projected** to the set C_S :

$$\begin{aligned}
 \min_{\mathbf{P}, \mathbf{Q}} \quad & \|\mathbf{S}^*\mathbf{P} - \mathbf{Q}\|_F^2 \\
 \text{s.t.} \quad & \mathbf{Q} \in C_S, \mathbf{P}\mathbf{P}^T = \mathbf{I}_t,
 \end{aligned} \tag{6}$$

The Projection Method

- The optimal solution $\mathbf{S}^*\mathbf{P}$ is **projected** to the set C_S :

$$\begin{aligned} \min_{\mathbf{P}, \mathbf{Q}} \quad & \|\mathbf{S}^*\mathbf{P} - \mathbf{Q}\|_F^2 \\ \text{s.t.} \quad & \mathbf{Q} \in C_S, \mathbf{P}\mathbf{P}^T = \mathbf{I}_t, \end{aligned} \quad (6)$$

- Its **equivalent** form:

$$\begin{aligned} \max_{\mathbf{P}, \mathbf{Q}} \quad & \text{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{Q} \in C_S, \mathbf{P}\mathbf{P}^T = \mathbf{I}_t. \end{aligned} \quad (7)$$

The Projection Method

- The optimal solution $\mathbf{S}^*\mathbf{P}$ is **projected** to the set C_S :

$$\begin{aligned} \min_{\mathbf{P}, \mathbf{Q}} \quad & \|\mathbf{S}^*\mathbf{P} - \mathbf{Q}\|_F^2 \\ \text{s.t.} \quad & \mathbf{Q} \in C_S, \mathbf{P}\mathbf{P}^T = \mathbf{I}_t, \end{aligned} \quad (6)$$

- Its **equivalent** form:

$$\begin{aligned} \max_{\mathbf{P}, \mathbf{Q}} \quad & \text{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{Q} \in C_S, \mathbf{P}\mathbf{P}^T = \mathbf{I}_t. \end{aligned} \quad (7)$$

- An **alternating** optimization method is used to solve this problem.

Subproblem 1

Subproblem 1

- When \mathbf{P} is fixed, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

Subproblem 1

- When \mathbf{P} is fixed, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

- This is an integer programming problem with no efficient solution.

Subproblem 1

- When \mathbf{P} is **fixed**, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

- This is an **integer** programming problem with **no** efficient solution.
- This problem is to find the t **largest** elements in $\mathbf{S}^* \mathbf{P}$

Subproblem 1

- When \mathbf{P} is fixed, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

- This is an integer programming problem with no efficient solution.
- This problem is to find the t largest elements in $\mathbf{S}^* \mathbf{P}$
 - No two elements can be in the same column or the same row.

Subproblem 1

- When \mathbf{P} is **fixed**, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

- This is an **integer** programming problem with **no** efficient solution.
- This problem is to find the t **largest** elements in $\mathbf{S}^* \mathbf{P}$
 - No** two elements can be in the same column or the same row.
- Observation**: the largest elements of different columns in $\mathbf{S}^* \mathbf{P}$ usually lie in different rows.

Subproblem 1

- When \mathbf{P} is **fixed**, the optimization problem with respect to \mathbf{Q} is

$$\begin{aligned} \max_{\mathbf{Q}} \operatorname{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t. } \mathbf{Q} \in \{0, 1\}^{n \times t}, \mathbf{Q}^T \mathbf{1}_n = \mathbf{1}_t, \mathbf{Q} \mathbf{1}_t \leq \mathbf{1}_n. \end{aligned} \quad (8)$$

- This is an **integer** programming problem with **no** efficient solution.
- This problem is to find the t **largest** elements in $\mathbf{S}^* \mathbf{P}$
 - No** two elements can be in the same column or the same row.
- Observation**: the largest elements of different columns in $\mathbf{S}^* \mathbf{P}$ usually lie in different rows.
- We propose a **greedy** method to select multiple largest elements in different rows.

Subproblem 2

Subproblem 2

- When \mathbf{Q} is fixed, the optimization problem with respect to \mathbf{P} is

$$\begin{aligned} \max_{\mathbf{P}} \quad & \text{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{P} \mathbf{P}^T = \mathbf{I}_t. \end{aligned} \tag{9}$$

Subproblem 2

- When \mathbf{Q} is **fixed**, the optimization problem with respect to \mathbf{P} is

$$\begin{aligned} \max_{\mathbf{P}} \quad & \text{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{P} \mathbf{P}^T = \mathbf{I}_t. \end{aligned} \quad (9)$$

- By using **Lagrangian multiplier** method, we can get the **analytical** solution as

$$\mathbf{P}^* = \mathbf{U} \mathbf{R}^T.$$

Subproblem 2

- When \mathbf{Q} is **fixed**, the optimization problem with respect to \mathbf{P} is

$$\begin{aligned} \max_{\mathbf{P}} \quad & \text{tr}(\mathbf{Q}^T \mathbf{S}^* \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{P} \mathbf{P}^T = \mathbf{I}_t. \end{aligned} \quad (9)$$

- By using **Lagrangian multiplier** method, we can get the **analytical** solution as

$$\mathbf{P}^* = \mathbf{U} \mathbf{R}^T.$$

- $(\mathbf{S}^*)^T \mathbf{Q} = \mathbf{U} \mathbf{\Sigma} \mathbf{R}^T$ be the **singular value decomposition**.

Properties of Our Optimization Method

Properties of Our Optimization Method

- The computational **complexity** of our method is $O(n^2t)$.

Properties of Our Optimization Method

- The computational **complexity** of our method is $O(n^2t)$.
- DED is **insensitive** to the regularization parameter.

Outline

- 1 Introduction
- 2 Notations
- 3 Discriminative Experimental Design
- 4 Experiments**
- 5 Conclusion

Experimental Setup

Experimental Setup

- The **method** compared: DED, SVM active learning, TED, batch mode active learning.

Experimental Setup

- The **method** compared: DED, SVM active learning, TED, batch mode active learning.
- Two public **benchmark** data sets used: Newsgroups and Reuters.

Experimental Setup

- The **method** compared: DED, SVM active learning, TED, batch mode active learning.
- Two public **benchmark** data sets used: Newsgroups and Reuters.
- Performance measure: The area under the ROC curve (**AUC**).

Experimental Setup

- The **method** compared: DED, SVM active learning, TED, batch mode active learning.
- Two public **benchmark** data sets used: Newsgroups and Reuters.
- Performance measure: The area under the ROC curve (**AUC**).
- The **size** of queries t : 5

Experimental Setup

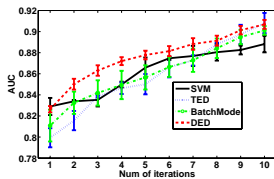
- The **method** compared: DED, SVM active learning, TED, batch mode active learning.
- Two public **benchmark** data sets used: Newsgroups and Reuters.
- Performance measure: The area under the ROC curve (**AUC**).
- The **size** of queries t : 5
- The **regularization parameters**: 0.01.

Experimental Setup

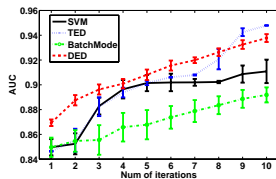
- The **method** compared: DED, SVM active learning, TED, batch mode active learning.
- Two public **benchmark** data sets used: Newsgroups and Reuters.
- Performance measure: The area under the ROC curve (**AUC**).
- The **size** of queries t : 5
- The **regularization parameters**: 0.01.
- **Five** labeled data points are provided for each class **before** active learning starts.

Results on Newsgroups Data

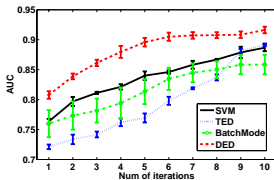
Results on Newsgroups Data



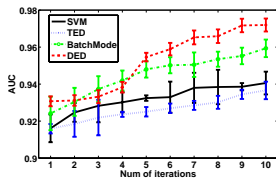
(e) Autos



(f) Motorcycles

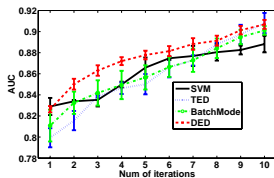


(g) Baseball

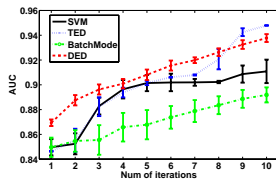


(h) Hockey

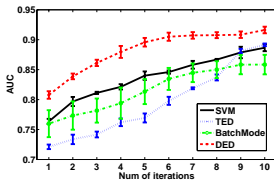
Results on Newsgroups Data



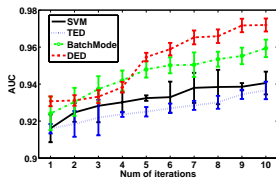
(i) Autos



(j) Motorcycles



(k) Baseball

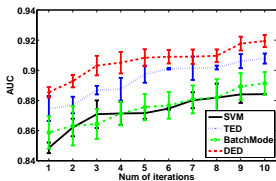


(l) Hockey

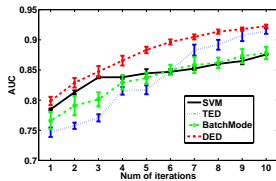
- When the labeled data is **scarce**, data distribution information is very **important**.

Results on Reuters Data

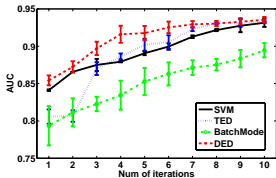
Results on Reuters Data



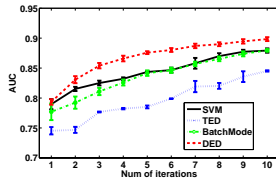
(q) CCAT



(r) ECAT



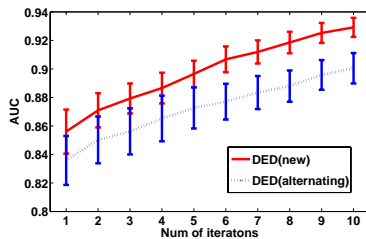
(s) GCAT



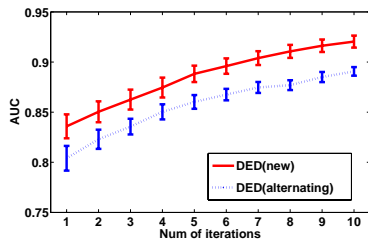
(t) MCAT

Comparison on Two Optimization Techniques

Comparison on Two Optimization Techniques



(w) Newsgroups data



(x) Reuters data

Outline

- 1 Introduction
- 2 Notations
- 3 Discriminative Experimental Design
- 4 Experiments
- 5 Conclusion**

Conclusion

Conclusion

- A **novel** active learning method has been proposed.

Conclusion

- A **novel** active learning method has been proposed.
- The data selection criterion utilizes **discriminative** information and data **distribution** information.

Conclusion

- A **novel** active learning method has been proposed.
- The data selection criterion utilizes **discriminative** information and data **distribution** information.

Future Work:

Conclusion

- A **novel** active learning method has been proposed.
- The data selection criterion utilizes **discriminative** information and data **distribution** information.

Future Work:

- The **integration** of active learning and semi-supervised learning

Thanks very much for your
attention!