

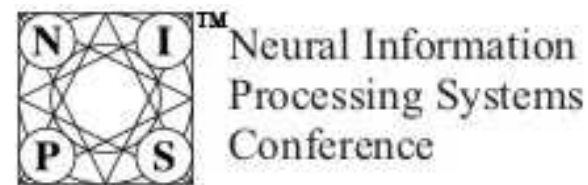
# Thanks!

◆ **The other organisers:** David Hoon, Gayle Leen, Simon Rogers, Barbara Caputo, Francesco Orabona, Nicolò Cesa-Bianchi

◆ **The programme committee:** Cedric Archambeau, Andreas Argyriou, Claudio Gentile, Mark Girolami, Samuel Kaski, Arto Klami, John Shawe-Taylor, Giorgio Valentini

◆ PASCAL2, NIPS

◆ You!



# Discussion

Robotics application:

- ❖ generic vs. domain-specific methods
- ❖ computational bottlenecks in the robotics domain
- ❖ could time information be used more?

Theory/methods:

- ❖ what level (features, classifications etc.) should sources be integrated at?
- ❖ estimating source reliability: do assumptions hold?
- ❖ different assumptions of task similarity
- ❖ complexity tradeoff between observation model and task interaction model

Organization:

- ❖ combined theory+application workshop, or separately?
- ❖ overlapping related workshops?
- ❖ challenges/benchmarks