



Information Theoretic Model Validation by Approximate Optimization

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- Motivation of information theory for optimization
- Approximation capacity of a cost function
- Examples
 - Binary symmetric channel
 - Cluster validation
 - Role based access control
 - Robust SVD
- Conclusion and outlook

What is the central challenge of pattern recognition?

- I) Finding the "right" model? II) Validating a model?
- Hypothesis: Validation of pattern recognition models is the fundamental challenge!
- ⇒Algorithmic search for PR models should prefer noise tolerant and expressive models over brittle, simplistic ones! (stability vs informativeness)
- Information theory enables us to measure the context sensitive information content of models!

Information Theory & Pattern Recognition

IT-Components

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- Code vectors ⊊ {strings}
 - = hypothesis class
- Noisy channel
- Decoder: minimize
 Hamming distance
- Criterion for error free communication

=> mutual information

- Pattern Recognition elements
 - Approximation sets ⊊
 hypothesis class
 - Noisy optimization problem
 - Decoding by approximate optimization of test instance
- model validation based on guaranteed approximations
 mutual information

 Partitions of sis sterings: compactness/colossis tivity costs
 Trees or dendrogram. Uch partitions with ultrametricity. The depth? # leaves?
 '-'s: **Examples of hypothesis classes**



- IT: Space of strings is partitioned by code vectors
 - PR: Hypothesis class is partitioned by code problems



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Pattern recognition as optimization

- Given: data $\mathbf{X} \in \mathcal{X}$ in data (input) space \mathcal{X}
- Goal: Learn structure from data, i.e., interpret data relative to a hypothesis class
- Hypothesis class C with hypotheses (solutions)

$$egin{array}{rcl} c & \colon \mathcal{X} & o & \mathbb{K} & ext{(e.g., } \mathbb{B}^n ext{ or } \{1, \dots, k\}^n) \ & \mathbf{X} & \mapsto & c(\mathbf{X}) \end{array}$$

• Cost function to define a partial order on ${\cal C}$

Symmetries of the Learning Problem

 Assume (!) that the cost function R is equivariant under the transformations

$$\Sigma = \{ \sigma : R(c, \mathbf{X}) = R(\sigma \circ c, \sigma \circ \mathbf{X}) \}$$

- Minimizer: $c^{\perp}(\mathbf{X}) = \arg\min_{c \in \mathcal{C}} R(c, \mathbf{X})$ $c^{\perp}(\sigma \circ \mathbf{X}) = \sigma \circ c^{\perp}(\mathbf{X})$
- Approximation set:

$$c \in \mathcal{C}_{\gamma}(\mathbf{X}) \equiv \left\{ c : R\left(c, \mathbf{X}\right) \leq R\left(c^{\perp}, \mathbf{X}\right) + \gamma \right\}$$

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How to generate code problems?

- Combinatorial optimization problems: permutation of combinatorial components, e.g., vertices in graphs
- 2. Localization problems: **shifts** of data
- 3. Orientation problems (PCA, SVD): rotations



Ex.: Graph Cut - Clustering in two groups

Graph representation: vertices denote objects

edges express (dis)similarities

Hypothesis class: a

all **cuts** of a graph





Code problem generation for Graph Cut

graph cut code problems

graph cut test problem

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Coding with Graph Cut approximation sets



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Communication by approximation sets



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- Receiver has to compare sets of hypotheses $C_{\gamma}(\mathbf{X}^{(1)})$ of training instance (code problem) with approximate clusterings $C_{\gamma}(\mathbf{X}^{(2)})$ of the test data.
- Define a mapping $\psi : \mathcal{C}(\mathbf{X}^{(1)}) \to \mathcal{C}(\mathbf{X}^{(2)})$
- Decoding by overlap maximization $(\tilde{\mathbf{X}}^{(2)} := \sigma_s \circ \mathbf{X}^{(2)})$

$$\hat{\sigma} = \arg \max_{\sigma} \left| \psi \circ \mathcal{C}_{\gamma}(\sigma \circ \mathbf{X}^{(1)}) \cap \mathcal{C}_{\gamma}(\tilde{\mathbf{X}}^{(2)}) \right|$$

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Error Events and Approximation Capacity

- Sender selects transformation $\sigma_s \Rightarrow C_{\gamma}(\sigma_s \circ \mathbf{X}^{(1)})$
- Joint approximation sets

$$\Delta \mathcal{C}_j = \psi \circ \mathcal{C}_\gamma(\sigma_j \circ \mathbf{X}^{(1)}) \cap \mathcal{C}_\gamma(\sigma_s \circ \mathbf{X}^{(2)})$$

for $1 \le j \le 2^{n\rho}, \ j \ne s$

Error events :

$$|\Delta C_j| \ge |\Delta C_s|$$
 for $1 \le j \le 2^{n\rho}, \ j \ne s$

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Error Probability

• Conditional error $P(\hat{\sigma} \neq \sigma_s | \sigma_s) = P(\max_{j \neq s} |\Delta C_j| > |\Delta C_s| | \sigma_s)$ Union bound $\leq \sum_{j \neq s} P(|\Delta C_j| > |\Delta C_s| | \sigma_s)$

Assume random transformations $\sigma \in \Sigma$

$$\leq 2^{n\rho} P\left(\left| \Delta C_{\neq s} \right| > \left| \Delta C_{s} \right| \left| \sigma_{s} \right) \right. \\ = 2^{n\rho} \mathbb{E}_{\mathbf{X}^{(1,2)}} \mathbb{E}_{\sigma_{\neq s}} \left[\mathbb{I}_{\left\{ \left| \Delta C_{\neq s} \right| \ge \left| \Delta C_{s} \right| \right\}} \left| \sigma_{s} \right] \right]$$

The random transformation statistically decouples the two approximation sets in $\Delta C_{\neq s}$

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Bounding of error

$$\mathbb{E}_{\sigma_{\neq s}} \left[\mathbb{I}_{\{|\Delta \mathcal{C}_{\neq s}| \ge |\Delta \mathcal{C}_{s}|\}} \right]$$

$$\stackrel{a)}{\leq} \quad \frac{1}{|\{\sigma_{\neq s}\}|} \sum_{\{\sigma_{\neq s}\}} \frac{|\Delta C_{\neq s}|}{|\Delta C_{s}|}$$

$$\stackrel{b)}{\leq} \quad \frac{|C_{\gamma}(\mathbf{X}^{(1)})||C_{\gamma}(\mathbf{X}^{(2)})|}{|\{\sigma_{\neq s}\}||\Delta C_{s}|}$$

$$\stackrel{c)}{=} \quad \exp\left(-n\mathcal{I}_{\gamma}(\sigma_{\neq s},\hat{\sigma})\right)$$

- a) Bound on indicator function $\mathbb{I}_{\{x \ge a\}} \le x/a$
- b) Averaging over random transformation
- c) Definition of mutual information

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Condition of vanishing total error

$$\lim_{n \to \infty} P(\hat{\sigma} \neq \sigma_s | \sigma_s) = 0 \quad \text{yields}$$

Rate is bounded by mutual information

$$\rho \log 2 < \frac{1}{n} \log \frac{|\{\sigma_{\neq s}\}| |\Delta \mathcal{C}_s|}{|\mathcal{C}_{\gamma}^{(1)}| |\mathcal{C}_{\gamma}^{(2)}|}$$

$$= \frac{1}{n} \left(\log \frac{|\{\sigma_{\neq s}\}|}{|\mathcal{C}_{\gamma}^{(1)}|} + \log \frac{|\mathcal{C}^{(2)}|}{|\mathcal{C}_{\gamma}^{(2)}|} - \log \frac{|\mathcal{C}^{(2)}|}{|\Delta \mathcal{C}_s|} \right)$$

$$\equiv \mathcal{I}_{\gamma}(\sigma_{\neq s}, \hat{\sigma})$$

 Lower bound: generalize Fano's inequality to ASC (work in progress)

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Model Selection by Maximization of Approximation Capacity



 Optimize the communication channel w.r.t. approximation quality γ (β), topology and metric of solution space, cost function *R*(.,.), transfer function ψ

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Ex.: Binary Coding

• Hypothesis class: set of binary strings $\xi^{(1)} = (\xi_1^{(1)}, \xi_2^{(1)}, \dots, \xi_n^{(1)}), \xi^{(2)} \in \{-1, 1\}^n$

- Costs: $R(s,\xi^{(1)}) = \sum_{i=1}^{n} \mathbb{I}_{\{s_i \neq \xi_i^{(1)}\}}$
- Mutual information: $\left(\delta = \frac{1}{n} |\{i : \xi_i^{(1)} \neq \xi_i^{(2)}\}|\right)$

$$\begin{aligned} \mathcal{I}_{\beta} &= \ln 2 + (1 - \delta) \ln \cosh \beta - \ln(\cosh \beta + 1) \\ \stackrel{(*)}{=} &\ln 2 + (1 - \delta) \ln(1 - \delta) + \delta \ln \delta \\ &\text{if} \quad (*) \frac{d\mathcal{I}_{\beta}}{d\beta} = 0 \text{ holds} \end{aligned}$$

 ASC for Hamming distance yield capacity of binary symmetric channel!

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Gibbs sampling with 4 clusters

Experimental Setting:

n=500, d=100, 2 source Gaussians ordered phase, up to 4 estimated Gaussians



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n=500; d=100, 500, 3000; α := n/d

RANDOM

Denoising Binary Matrices by rank-k approximation continuous rank-k approximation

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Maximum of approximation capacity selects optimal rank *k*

Integrate over variations of the signal matrix U.

$$\mathcal{I}_{\beta}(\sigma_{j}, \hat{\sigma}) = \frac{1}{n} \log \frac{|\{\sigma_{j}\}| |\Delta \mathcal{C}_{\beta}(\mathbf{X}^{(1)}, \mathbf{X}^{(2)})|}{|\mathcal{C}_{\beta}(\mathbf{X}^{(1)})| |\mathcal{C}_{\beta}(\mathbf{X}^{(2)})|}$$

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Role-Based Access Control

- Given: Binary user teach students
 permission matrix change group web-page
- spend >5000\$

 Discretional

 supervise master thesis

 Access-Control:

 use coffee machine

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Direct Assignments of users to permissions

 Role-Based Access Control (RBAC): Permissions are granted via roles

Role-Mining for RBAC

- Role-Mining: Given a user-permission assignment matrix X, find a set of roles U and assignments Z such that
 - $\mathbf{X} \approx \mathbf{U} \otimes \mathbf{Z}$
- Multi Assignment Clustering: generative approach including noise model, inference with DA

Synthetic Data: Parameter Accuracy vs. Approximation Capacity

MAC: More accurate estimators for centroids, it yields higher approximation capacity than SAC.

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Real-World Data: Prediction Error vs. Approximation Capacity

- Generalization: Can roles predict permissions of new users? 3.5
 - Use few permissions (20%) 1.
- Juen/missing Juen/

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Conclusion

- Quantization: Noise quantizes mathematical structures (hypothesis classes) => symbols
- These symbols can be used for coding!
- Optimal error free coding scheme determines approximation capacity of a model class.
- \Rightarrow Bounds for robust optimization.
- ⇒Quantization of hypothesis class measures structure specific information in data.

Future Work

- Generalization: replace approximation sets based on cost functions by smoothed outputs of algorithms ("smoothed generalization")
- Model reduction in dynamical systems: quantize sets of ODEs or PDEs (systems biology)
- Relate statistical complexity, i.e. the approximation capacity, to algorithmic or computational complexity.

Philosophical speculations

- We experience a paradigm shift from model driven reasoning to algorithm dominated reasoning (Bernard Chazelle "The Algorithm: Idiom of Modern Science")
- => model validation more essential than modeling since modeling can be algorithmically formulated as exploration of model space.
- Ceterum censeo: The coupling of statistical complexity and algorithmic complexity should be reconsidered in the light of statistical learning theory and information theory.