





# A decision procedure for $\mathcal{SHOIQ}$ with Transitive Closure of Roles

#### Chan LE DUC, Myriam LAMOLLE and Olivier $\operatorname{CURE}$

Université Paris 8 - IUT de Montreuil, Université Marne La Vallée

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## Why transitive closure of roles is needed?

• Example 1 :



- $O_1$ : Trans(reachable)
  - $\mathsf{click}\sqsubseteq\mathsf{reachable}$
  - $\begin{array}{l} \mathsf{A} \sqcup \mathsf{B} \sqcup \mathsf{C} \sqsubseteq \exists \mathsf{reachable}^-.\{\mathsf{start}\} \\ \mathsf{C} \sqsubseteq \forall \mathsf{click}^-.\bot \end{array}$

 $\Rightarrow {\sf Consistent}\,!$ 

 $\begin{array}{l} \textbf{O}_2 : \ \textbf{A} \sqcup \textbf{B} \sqcup \textbf{C} \sqsubseteq \exists (\mathsf{click}^-)^+. \{\mathsf{start}\} \\ \textbf{C} \sqsubseteq \forall \mathsf{click}^-. \bot \end{array}$ 

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 Example 2 : Human ⊑ ∃hasParent<sup>+</sup>.{Eva} versus Human ⊑ ∃hasAncestor.{Eva} where "hasAncestor" transitive

## SHOIQ and Transitive Closure of Roles

- The logic *SHOIQ* :
  - Finite sets of concept, role and (nominals) individual names
  - Concept descriptions :
     C □ D, C □ D, ¬C, ∃R.C, ∀R.C, ≤ nS.C, ≥ nS.C where C, D are concepts; R is a role (possibly inverse and transitive); S is a simple role
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- Transitive closure of roles :  $(Q^+)^{\mathcal{I}} = \bigcup_{n>0} (Q^n)^{\mathcal{I}}$  with an

interpretation  $\ensuremath{\mathcal{I}}$ 

In SHOIQ<sub>(+)</sub> (SHOIQ with transitive closure), one can say : ∃R<sup>+</sup>.C or ∀R<sup>+</sup>.C but not

 $\leq nS^+$ . *C* [Horrocks, Sattler and Tobies, 1999], or  $R \sqsubseteq S^+$  [Le Duc and Lamolle, 2010]

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# Why is $SHOIQ_{(+)}$ tricky?

- *SHOIQ* has a forest-like model whose the infinite part is tree-like [Horrocks and Sattler, 2005]
- SHIQ<sub>(+)</sub> has a tree-like model [Le Duc, Lamolle and Curé, 2011]
- There exists a consistent ontology in SHOIQ<sub>(+)</sub> whose all models are non-tree-like
  {o} ⊆ A; A □ B ⊆ ⊥; A ⊑ ∃R.A □ ∃R'.B; B ⊑ ∃S<sup>+</sup>.{o}
  {o} ⊑ ∀X<sup>-</sup>.⊥; X is functional with X ∈ {R, R', S}



## Overview of the algorithm

#### • Goal : constructing a model of a $\mathcal{SHOIQ}_{(+)}$ ontology

- Key structures :
  - A star-type for representing a set of individuals
  - A frame and sections for representing a model
  - A new blocking condition based on sections
- Algorithm :

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# Star-type



# Star-types and linking



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### Frame and sections



## Frame and sections (2)



With sections, one can say that a concept  $\exists Q^+.C$  is satisfied :

- in the past
- in the future
- somewhere from the future
- somewhere from the past

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## Blocking condition



- Each ray r in the blocking (blocked) section blocks (is blocked by) a ray r' in the blocked (blocking) section such that (i) L(r) = L(r'), and (ii) each ∃Q<sup>+</sup>.C in both r and r' is satisfied in "the same way"
- Each concept  $\exists Q^+.C$  in the blocking section is satisfied

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Termination is a consequence of the following facts :

- The algorithm never removes a star-type
- The number of sections from nominal to blocked one is bounded by  $\mathcal{O}(2^{2^{|(\mathcal{T},\mathcal{R})|}})$
- Checking satisfaction of a concept ∃Q<sup>+</sup>.D over a frame is bounded by a polynomial function in the size of the frame

#### Soundness : from a valid frame to a model

- A frame is valid if
  - all star-types are valid
  - each nominal star-type is not duplicated
  - each concept  $\exists Q^+.C$ ,
    - either it is directly satisfied in the frame
    - or there is a  $Q\mbox{-sequence}$  leading to the blocked section containing a  $\exists Q^+.C$

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    - or there is a Q-sequence leading to the blocked section containing a  $\exists Q^+.C$
- Adapting the unravelling technique for frames :
  - defining a set of paths over the frame
  - extending infinitely the set of defined paths through blocked and blocking sections
  - satisfying a concept ∃Q<sup>+</sup>.C (extended path) by a Q-sequence leading to an extended path or to an initial path containing ∃Q.C

#### Main ideas :

• A model can be reduced to a frame with valid star-types :

The first section contains only nominal star-types It contains a section whose all concepts  $\exists Q^+.D$  are satisfied (blocking section) Parts between two "blockable" sections can be removed until a blocked section is detected

• The reduced model can guide the algorithm to build a valid frame.

## Conclusion and Future Work

#### Conclusion :

- A first decision procedure for  $SHOIQ_{(+)}$
- A structure, namely frame, with a new blocking condition for representing infinite non-tree-like parts of a model
- The complexity of the algorithm is high (triply nondeterministic exponential)

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- A first decision procedure for  $\mathcal{SHOIQ}_{(+)}$
- A structure, namely frame, with a new blocking condition for representing infinite non-tree-like parts of a model
- The complexity of the algorithm is high (triply nondeterministic exponential)
- Future work :
  - Reducing the size of frames
  - A more goal-oriented algorithm (tableau algorithm)
  - An implementation in progress
  - Hardness of SHOIQ(+)
  - The technique could be used for other logics (ZOIQ?)