



Triple Jump Acceleration for the EM Algorithm and Its Extrapolation-based Variants

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Motivation

- ◆ Given an incomplete data set, the EM [Dempster et al. 1977] algorithm iteratively searches for the maximum likelihood estimate of a probabilistic model. *However, the search usually converges slowly under these conditions because more iterations or time for each iteration are required:*
 - High missing rate
 - Large training data set
 - Large parameter vector
- ◆ Therefore, accelerating EM is desired for training probabilistic models.



Brief Summary of Our Work

◆ Accelerates the following:

- EM
- Parameterized EM (pEM) [Bauer et al. 1997]
- Adaptive overrelaxed EM (aEM) [Salakhutdinov & Roweis 2003]

◆ Should be able to accelerate:

- GIS for conditional random field
- Those can be formulated as fixed-point iteration methods: $\theta = M(\theta)$



Parameter Estimation Problem

- ◆ **Goal: find θ^* that maximizes $L(\theta)$**
 - θ : parameter vector of a probabilistic model
 - $L(\theta)$: log-likelihood with the training data
 - θ^* : maximum likelihood estimate

- ◆ **Influence of incomplete data**
 - $L(\theta)$ contains many local maxima
 - Search for local maxima



The EM Algorithm

Repeat (in iteration t)

$$\theta^{(t)} = M(\theta^{(t-1)})$$

Until $L(\theta^{(t)}) - L(\theta^{(t-1)}) < \delta$

◆ M : an EM mapping, E-step + M-step

◆ Likelihood increases monotonically:

$$L(\theta^{(t)}) \geq L(\theta^{(t-1)})$$

◆ Local maximum: $\theta^* = M(\theta^*)$



Taylor Expansion of M

- ◆ In the neighbor of θ^* , we apply Taylor expansion to M [Dempster et al. 1977]:

$$\theta^{(t+1)} = M(\theta^{(t)}) \approx \theta^* + M'(\theta^*)(\theta^{(t)} - \theta^*) = \theta^* + J(\theta^{(t)} - \theta^*)$$

where J is the Jacobian of M .

- ◆ Applying M to $\theta^{(t)}$ for h times, we have:

$$\theta^{(t+h)} = \theta^* + J^h(\theta^{(t)} - \theta^*)$$

Eigenvalues of J

- ◆ The eigen decomposition of J is:

$$J = Q \begin{pmatrix} \lambda_1 & \dots & 0 \\ 0 & \ddots & 0 \\ 0 & \dots & \lambda_n \end{pmatrix} Q^{-1} = Q \Lambda Q^{-1}$$

- ◆ The eigenvalues of J are expected to lie in $[0, 1)$ [Dempster et al. 1977].



Convergence Rate of EM

◆ Since $0 \leq \lambda_i < 1$, we have

$$\lim_{h \rightarrow \infty} J^h = 0$$

$$J^h = Q \begin{pmatrix} \lambda_1^h & \dots & 0 \\ 0 & \ddots & 0 \\ 0 & \dots & \lambda_n^h \end{pmatrix} Q^{-1} = Q \Lambda^h Q^{-1}$$

$$\theta^{(t+h)} = \theta^* + J^h (\theta^{(t)} - \theta^*)$$

◆ Therefore, the convergence rate is determined by λ_{max} [Dempster et al. 1977].



Parameterized EM (pEM)

Repeat (in iteration t)

$$\theta^{(t)} = M_{\eta}(\theta^{(t-1)})$$

Until $L(\theta^{(t)}) - L(\theta^{(t-1)}) < \delta$

- ◆ $M_{\eta}(\theta^{(t-1)}) = \theta^{(t-1)} + \eta(M(\theta^{(t-1)}) - \theta^{(t-1)})$
- ◆ Likelihood increases monotonically in the neighborhood of θ^* if $0 < \eta < 2$ [Bauer et al. 1997]. pEM with $\eta = 1$ is EM.
- ◆ Local maximum: $\theta^* = M(\theta^*) = M_{\eta}(\theta^*)$



Convergence Rate of pEM (1)

◆ The eigenvalues of the Jacobian of M are: $\lambda_{\eta i} = (1 - \eta) * 1.0 + \eta \lambda_i$

◆ Convergence rate is determined by $\max\{|\lambda_{\eta max}|, |\lambda_{\eta min}|\}$ because $\lambda_{\eta i} < 0$ is possible.

◆ pEM is faster than EM if $\max\{|\lambda_{\eta max}|, |\lambda_{\eta min}|\} < \lambda_{max}$



Convergence Rate of pEM (2)

◆ Optimal learning rate η^* is:

$$\eta^* = \frac{2}{2 - \lambda_{max} - \lambda_{min}}$$

which minimizes $\max\{|\lambda_{\eta max}|, |\lambda_{\eta min}|\}$

◆ η^* is obtained by solving $\lambda_{\eta max} = -\lambda_{\eta min}$

◆ pEM with η^* is faster than EM



Adaptive Overrelaxed EM (aEM)

[Salakhutdinov & Roweis 2003]

- ◆ pEM with dynamic η .
- ◆ If $L(\theta^{(t)}) - L(\theta^{(t-1)}) \geq \delta$, use $\eta = 1.1 * \eta$ in the next iteration.
- ◆ If $L(\theta^{(t)}) - L(\theta^{(t-1)}) < \delta$, discard the update and use $\eta = 1.0$ in the next iteration.



Aitken's Acceleration for EM (1)

[McLachlan & Krishnan, 1997]

◆ In the neighborhood of θ^* , we have

$$\theta^* = \theta^{(t)} + \sum_{h=0}^{\infty} (\theta^{(t+h+1)} - \theta^{(t+h)}).$$

$$\theta^* \approx \theta^{(t)} + \sum_{h=0}^{\infty} J^h (\theta^{(t+1)} - \theta^{(t)})$$

$$= \theta^{(t)} + (I - J)^{-1} (\theta_{EM}^{(t)} - \theta^{(t)})$$

where $\theta_{EM}^{(t)} = M(\theta^{(t)})$.



Aitken's Acceleration for EM (2)

$$\begin{aligned}(I - J)^{-1} &= [Q [I - \Lambda] Q^{-1}]^{-1} \\ &= Q [I - \Lambda]^{-1} Q^{-1} \\ &= Q \begin{pmatrix} \frac{1}{1-\lambda_1} & \cdots & 0 \\ 0 & \ddots & 0 \\ 0 & \cdots & \frac{1}{1-\lambda_n} \end{pmatrix} Q^{-1}\end{aligned}$$

$$\frac{1}{1-\lambda_i} = 1 + \lambda_i + \lambda_i^2 + \cdots$$

- ◆ However, exact estimation of J might be intractable for complicated models so that Aitken's acceleration is hard to use [Hesterberg 2005].



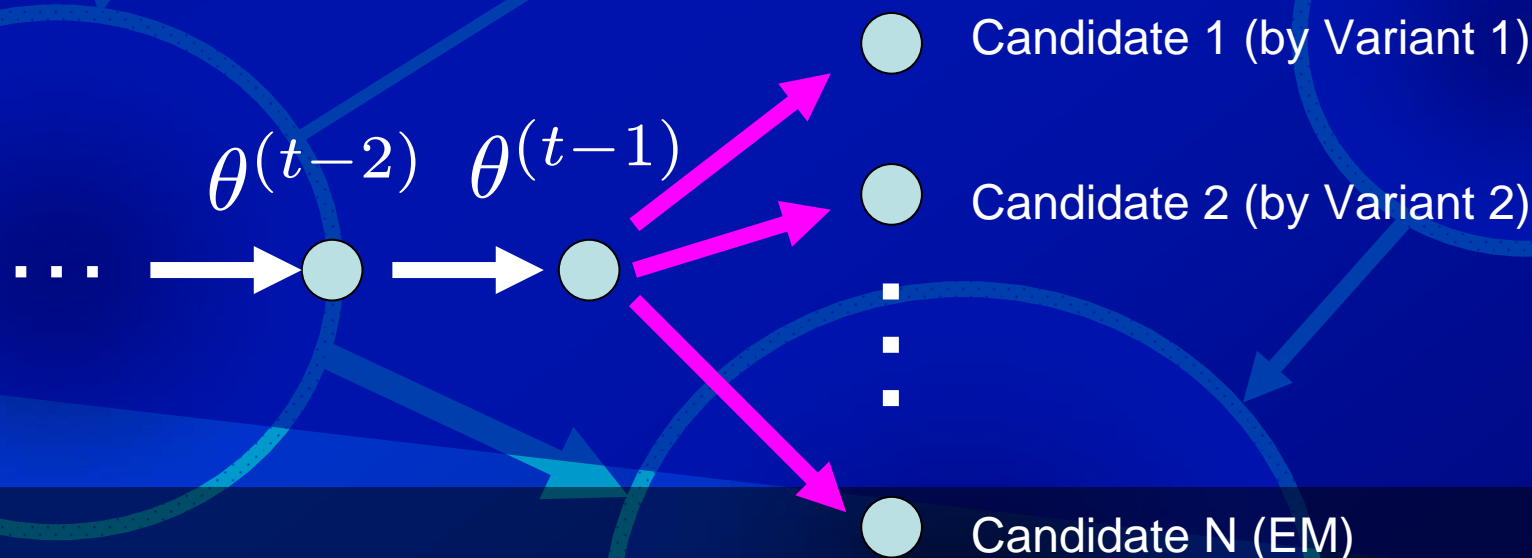
Our Solution to Accelerate EM

- ◆ Triple jump framework to integrate previous algorithms.
- ◆ Simple approximation of J to accelerate the slowest direction (along the eigenvector corresponding to $\max\{|\lambda_{\eta max}|, |\lambda_{\eta min}|\}$).
- ◆ Theoretical and empirical verification



Triple Jump Framework (1)

- ◆ In iteration t , TJ selects the first candidate as $\theta^{(t)}$ that satisfies $L(\theta^{(t)}) - L(\theta^{(t-1)}) \geq \delta$.

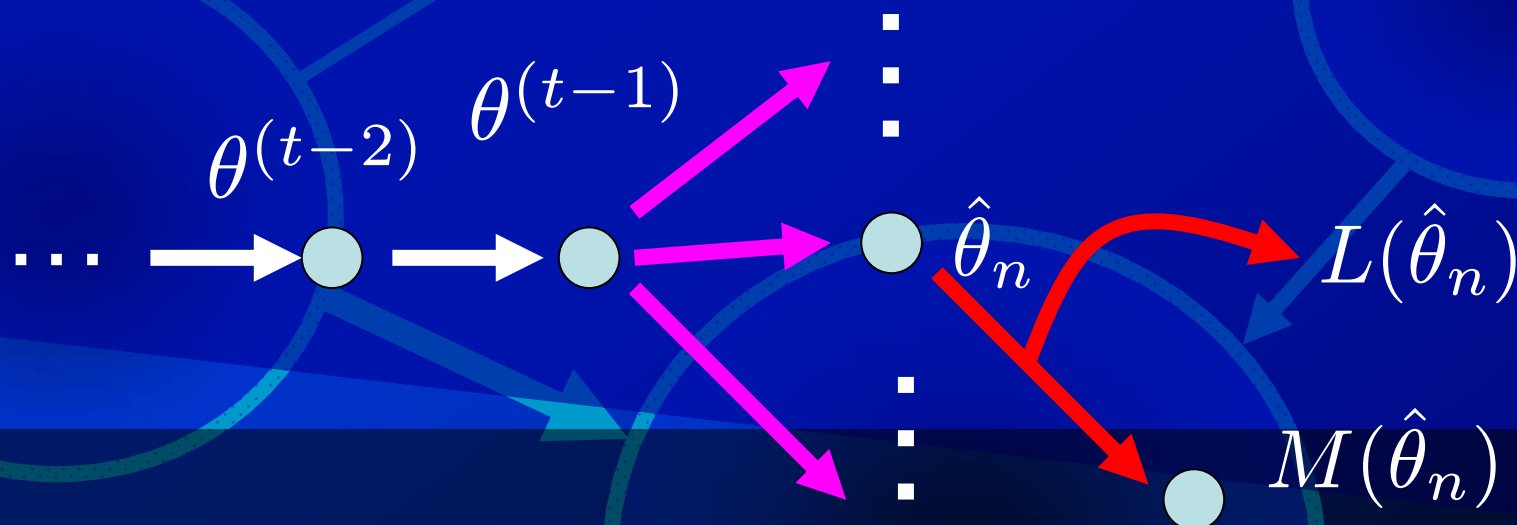


Triple Jump Framework (2)

◆ Candidate n is checked by

$$[M(\theta), L(\theta)] = M1(\theta)$$

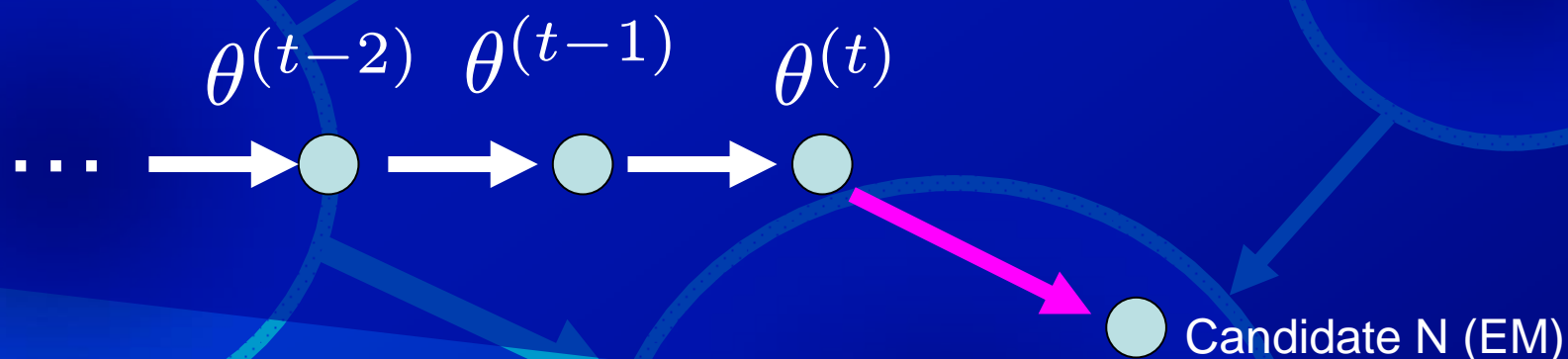
which is the EM mapping plus few additional cost to compute the likelihood of the input.





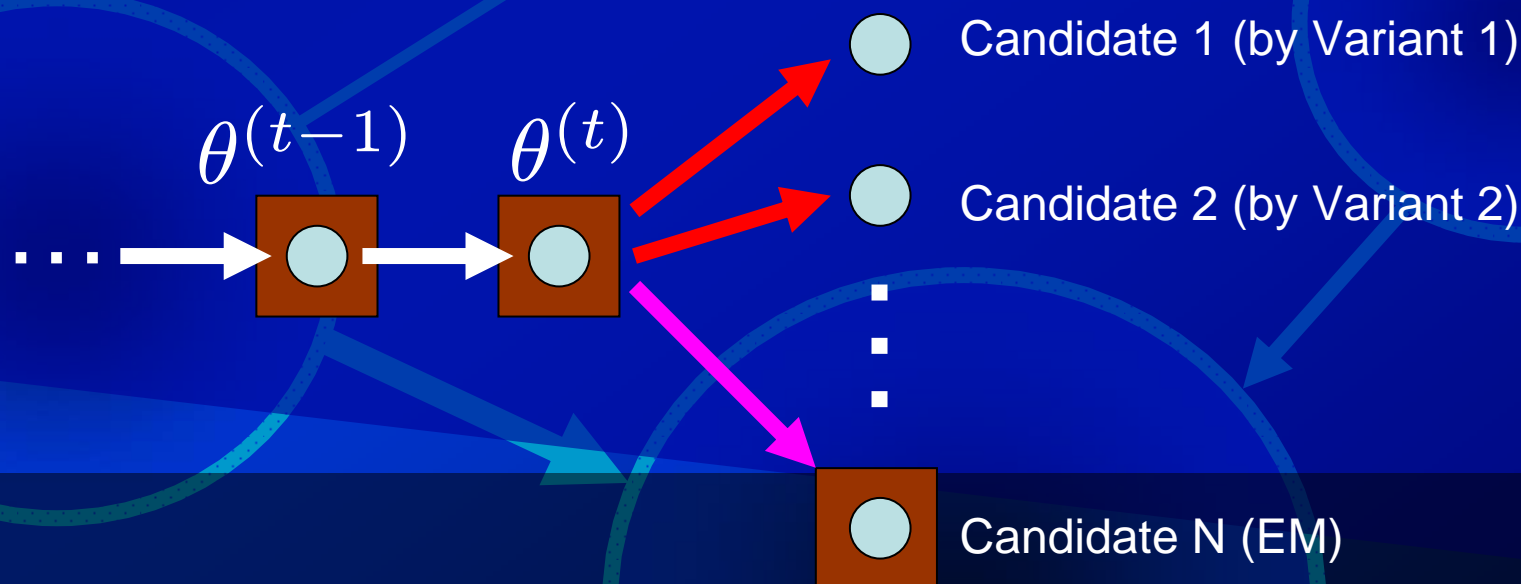
Triple Jump Framework (3)

- ◆ If $L(\hat{\theta}_n) - L(\theta^{(t-1)}) \geq \delta$, unchecked candidates are discarded. $\hat{\theta}_n$ becomes $\theta^{(t)}$, and $M(\hat{\theta}_n)$ becomes Candidate N for iteration $t+1$.



Triple Jump Framework (4)

- ◆ Other candidates are generated by candidate N and previous parameter vectors by extrapolation.





Advantages of TJ Framework

- ◆ **Easy to achieve acceleration by using EM directly as a subroutine**
- ◆ **Easy to integrate many EM variants**
- ◆ **Needless to handle the failure of extrapolation (naturally handled by EM, the last candidate)**



TJEM Extrapolation (1)

- ◆ Estimate largest eigenvalue with:

$$\gamma^{(t)} \equiv \frac{\|\theta_{EM}^{(t)} - \theta^{(t)}\|}{\|\theta^{(t)} - \theta^{(t-1)}\|}$$

where $\theta^{(t)} = M(\theta^{(t-1)})$ based on the requirement of the Aitken's acceleration. Therefore, the cycle of a TJEM extrapolation is two EM operations and a far jump, like hop, step, and jump in a triple jump.



TJEM Extrapolation (2)

- ◆ Assign $J = \gamma^{(t)}$ and perform the Aitken's acceleration. That is,

$$J = Q \begin{pmatrix} \gamma^{(t)} & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \gamma^{(t)} \end{pmatrix} Q^{-1}$$



TJEM Algorithm

- ◆ Triple Jump Framework
- ◆ Candidate 1: by TJEM Extrapolation
- ◆ Candidate 2: by EM



TJpEM Extrapolation

- ◆ Use M_η instead of M in the Aitken's acceleration.

$$\gamma_\eta^{(t)} \equiv \frac{\|\theta_\eta^{(t)} - \theta^{(t)}\|}{\|\theta^{(t)} - \theta^{(t-1)}\|}$$

where $\theta^{(t)} = M_\eta(\theta^{(t-1)})$.



TJpEM Algorithm

- ◆ Triple Jump Framework
- ◆ Candidate 1: TJpEM Extrapolation
- ◆ Candidate 2: pEM Extrapolation
- ◆ Candidate 3: EM



Convergence Properties of TIpEM Algorithm

◆ Suppose that

- TIpEM extrapolation is successful
- $\max\{|\lambda_{\eta max}|, |\lambda_{\eta min}|\}$ is estimated accurately

◆ The i -th eigenvalue of the Jacobian of the composition of pEM + TIpEM extrapolation is:

$$\alpha_{\eta i} = \lambda_{\eta i} (1 - \eta' + \eta' \lambda_{\eta i}) = \lambda_{\eta i} \frac{\lambda_{\eta i} - \gamma_{\eta}^{(t)}}{1 - \gamma_{\eta}^{(t)}}$$

$$\alpha_{\eta i} = \lambda_{\eta i} \frac{\eta(\lambda_i - \lambda_{max})}{\eta(1 - \lambda_{max})} = \lambda_{\eta i} \frac{\lambda_i - \lambda_{max}}{1 - \lambda_{max}}$$



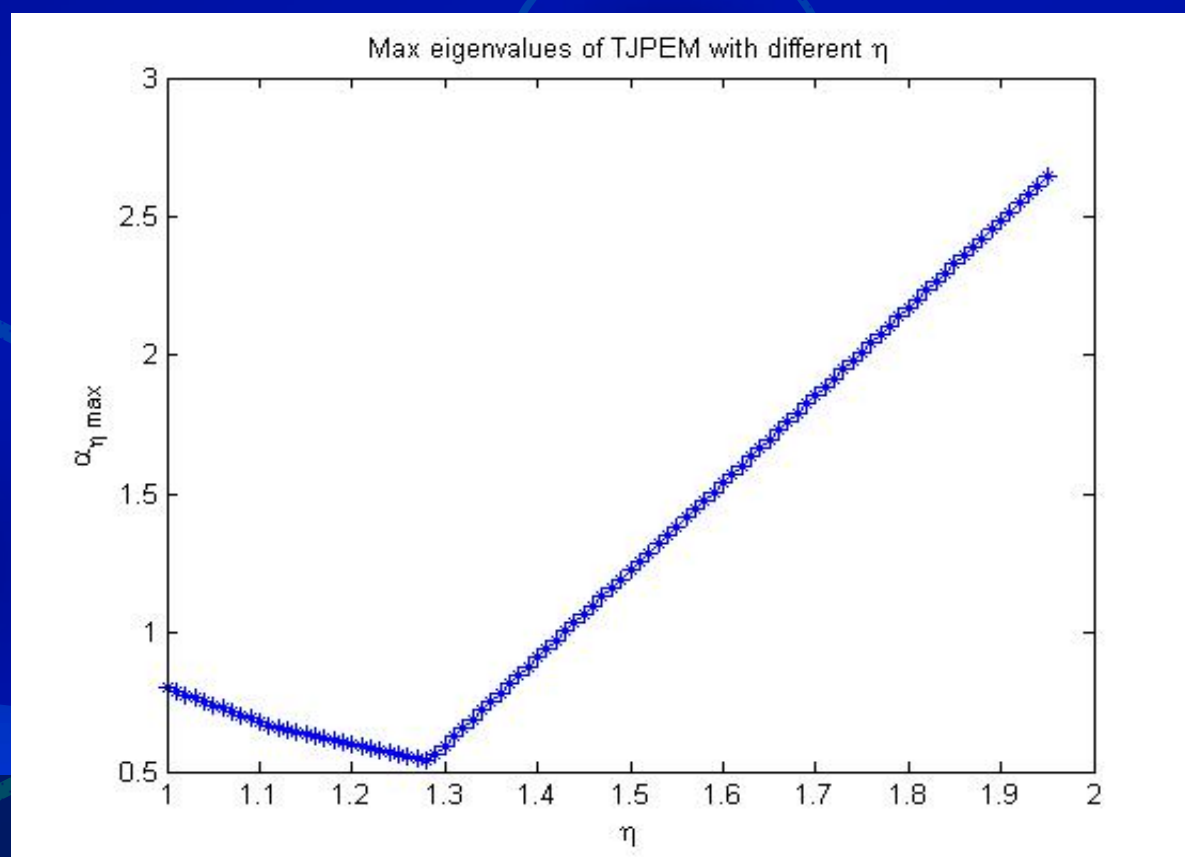
Convergence Rates of TJEM and TJpEM

- ◆ **Theorem** : *The TJpEM algorithm with a proper learning rate converges faster than the TJEM algorithm.*



Convergence Rates of TJpEM with Different Learning Rates

◆ Eigenvalues are 0.1, 0.2, ... 0.9.





TJ²pEM Extrapolation

- ◆ The goal of TJ²pEM is to reduce the impact of negative eigenvalues.
- ◆ Conceptually, we combine two pEM operations into one (M_{η}^2) so that the all eigenvalues (λ_{η}^2) become positive.

$$\begin{aligned}\theta^* &= \theta^{(t-1)} + \sum_{h=0}^{\infty} J_{\eta}^h (\theta_{\eta}^{(t-1)} - \theta^{(t-1)}) \\ &= \theta^{(t-1)} + (I - J_{\eta}^2)^{-1} (\theta_{\eta}^{(t)} - \theta^{(t-1)}).\end{aligned}$$



Comparison of TJ^2pEM & $TJpEM$

$$\theta^{(t+1)} = \theta^{(t-1)} + \frac{1}{1 - (\gamma_{\eta}^{(t)})^2} (\theta_{\eta}^{(t)} - \theta^{(t-1)}) \quad (TJ^2pEM)$$

$$\theta^{(t+1)} = \theta^{(t)} + (1 - \gamma_{\eta}^{(t)})^{-1} (\theta_{\eta}^{(t)} - \theta^{(t)}) \quad (TJpEM)$$

◆ $\gamma_{\eta}^{(t)}$'s are identical.

◆ $TJpEM$ extrapolates from $\theta^{(t)}$, while TJ^2pEM from $\theta^{(t-1)}$.



TJ²pEM Algorithm

- ◆ Triple Jump Framework
- ◆ Candidate 1: TJ²pEM Extrapolation
- ◆ Candidate 2: pEM Extrapolation
- ◆ Candidate 3: EM



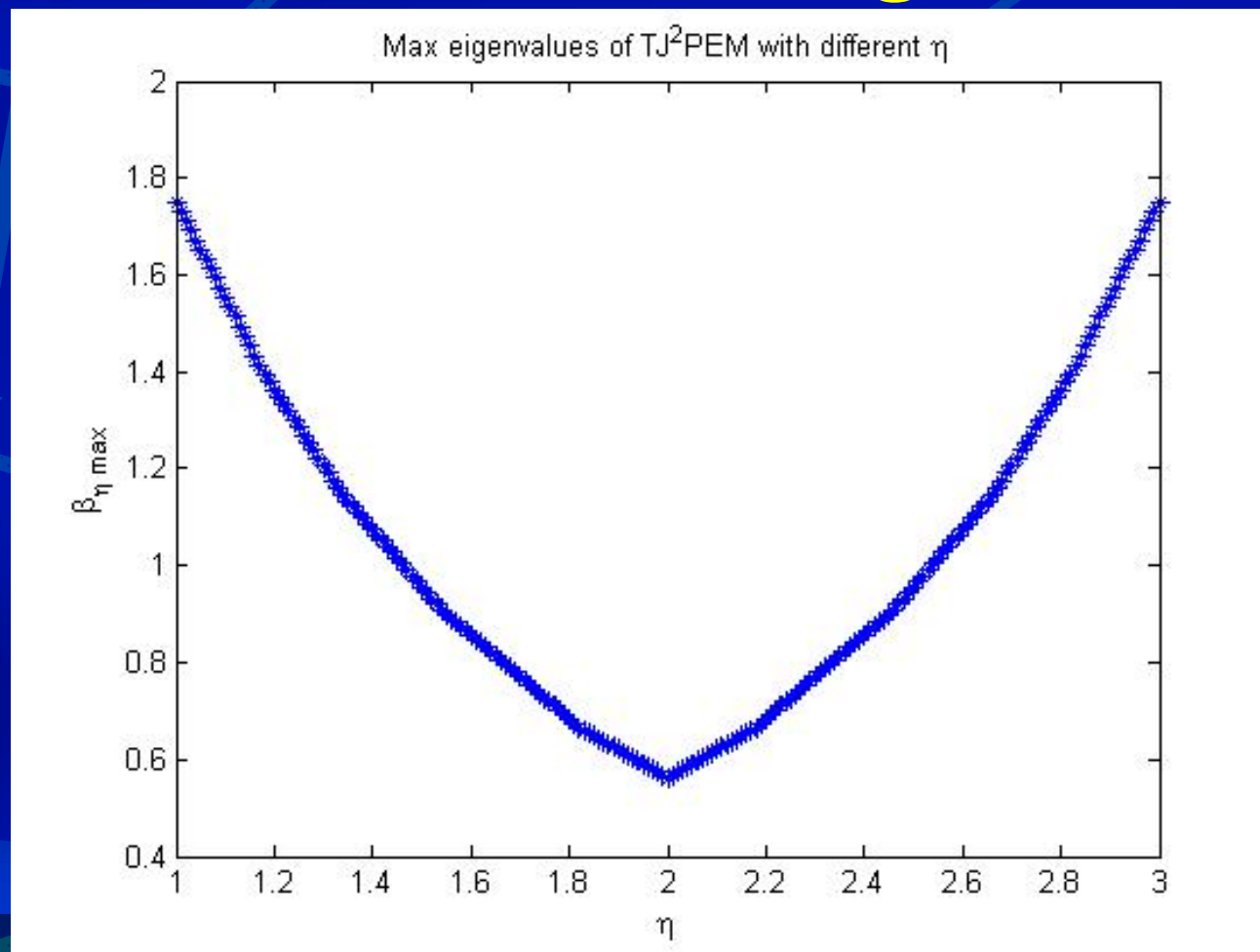
Convergence Rate of TJ^2pEM

◆ The i -th eigenvalue of TJ^2pEM is:

$$\beta_{\eta i} = 1 - \frac{1}{1 - (\gamma_{\eta}^{(t)})^2} + \frac{1}{1 - (\gamma_{\eta}^{(t)})^2} (\lambda_{\eta i})^2 = \frac{(\lambda_{\eta i})^2 - (\gamma_{\eta}^{(t)})^2}{1 - (\gamma_{\eta}^{(t)})^2}.$$



Convergence Rates of TJ^2pEM with Different Learning Rates





TJ²aEM Algorithm

- ◆ TJ²pEM with dynamic learning rates (similar to aEM)
- ◆ η iterates among 1.2, 1.4, 1.6 and 1.8.



Why Dynamic Learning Rates

- ◆ From our experiments, we found that aEM outperforms pEM with the optimal learning rate.
- ◆ We can prove that pEM with dynamic learning rates can accelerate pEM with the optimal learning rate.



Proof Sketch

- ◆ Assume that we use two learning rates:

$$\eta^{(1)} = \eta^* + \Delta \text{ and } \eta^{(2)} = \eta^* - \Delta$$

- ◆ The eigenvalues of dynamic learning rates are smaller than their counterparts of the optimal learning rate

$$\begin{aligned} & (1 - \eta^{(1)} + \eta^{(1)} \lambda_i)(1 - \eta^{(2)} + \eta^{(2)} \lambda_i) \\ = & (1 - \eta^* + \eta^* \lambda_i - \Delta(1 - \lambda_i))(1 - \eta^* + \eta^* \lambda_i + \Delta(1 - \lambda_i)) \\ = & (\lambda_{\eta^* i} - \Delta(1 - \lambda_i))(\lambda_{\eta^* i} + \Delta(1 - \lambda_i)) \\ = & (\lambda_{\eta^* i})^2 - (\Delta(1 - \lambda_i))^2 \\ \leq & (\lambda_{\eta^* i})^2. \end{aligned}$$



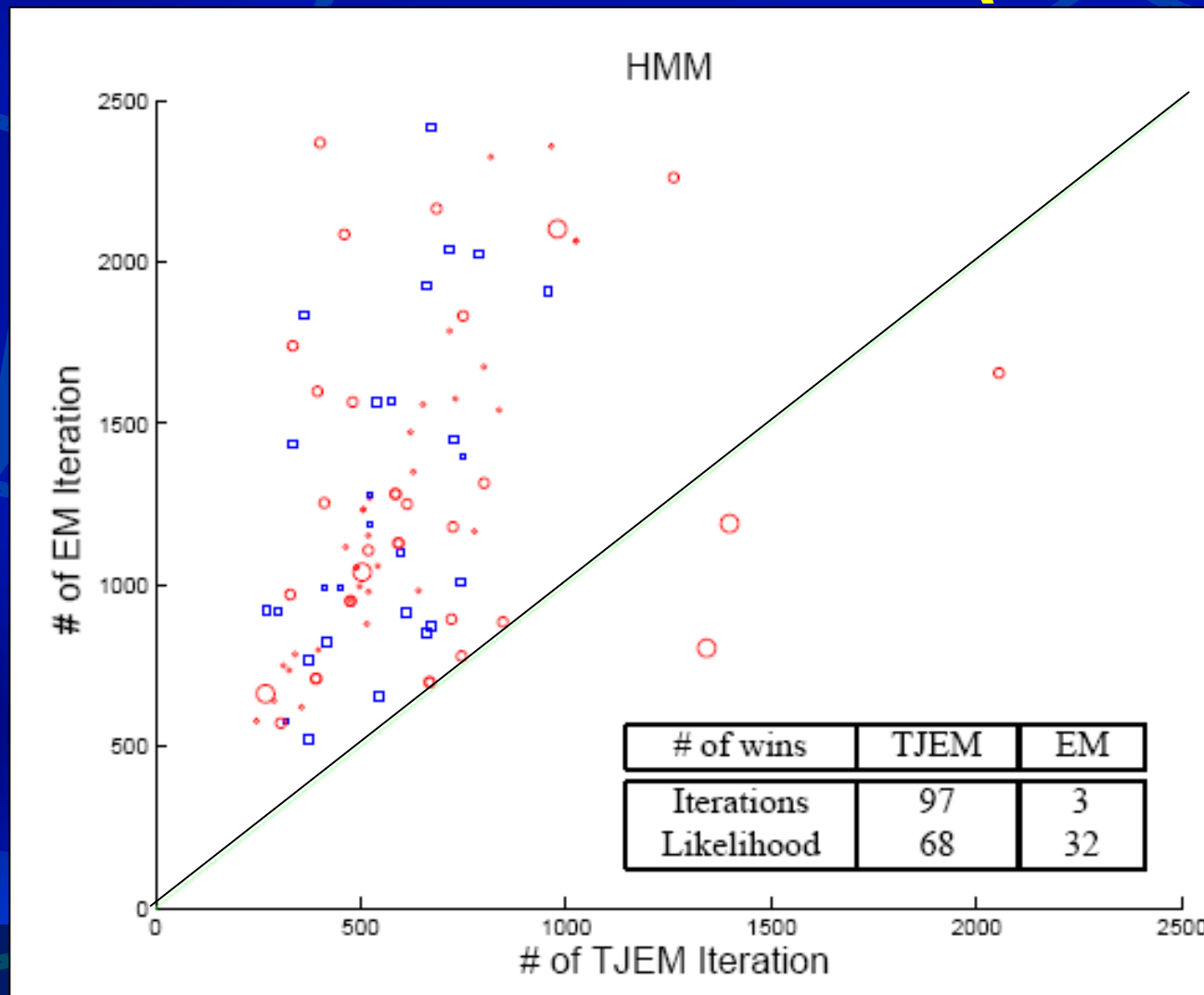
Data sets

◆ 100 synthesized data sets for each model

- HMM: 5-state, 20-symbol, 500 sequences with length 100
- Bayesian net (ALARM) [Cooper & Herskovitz]: 2,000 cases with different missing rates for all random variables
- GMM: 5 equal-weight Gaussian of means = $\{(0,0), (1,0), (-1,0), (0,1), (0,-1)\}$ and var = 0.8. 2,000 cases.
- Semisupervised Bayesian classifier: 5-class, 100 10-state features, 3,000 cases with unequal missing rates

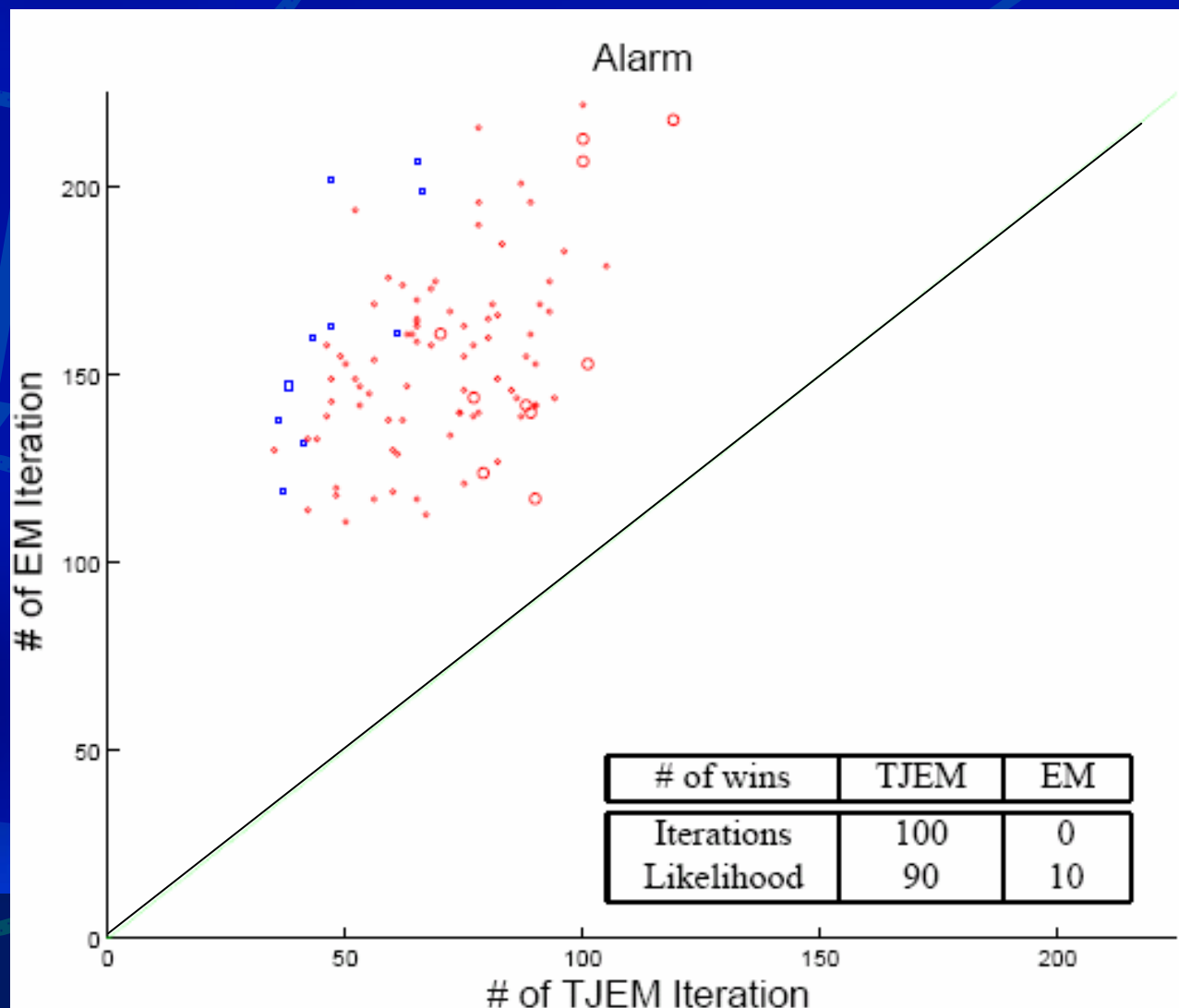


TJEM Faster than EM (HMM)



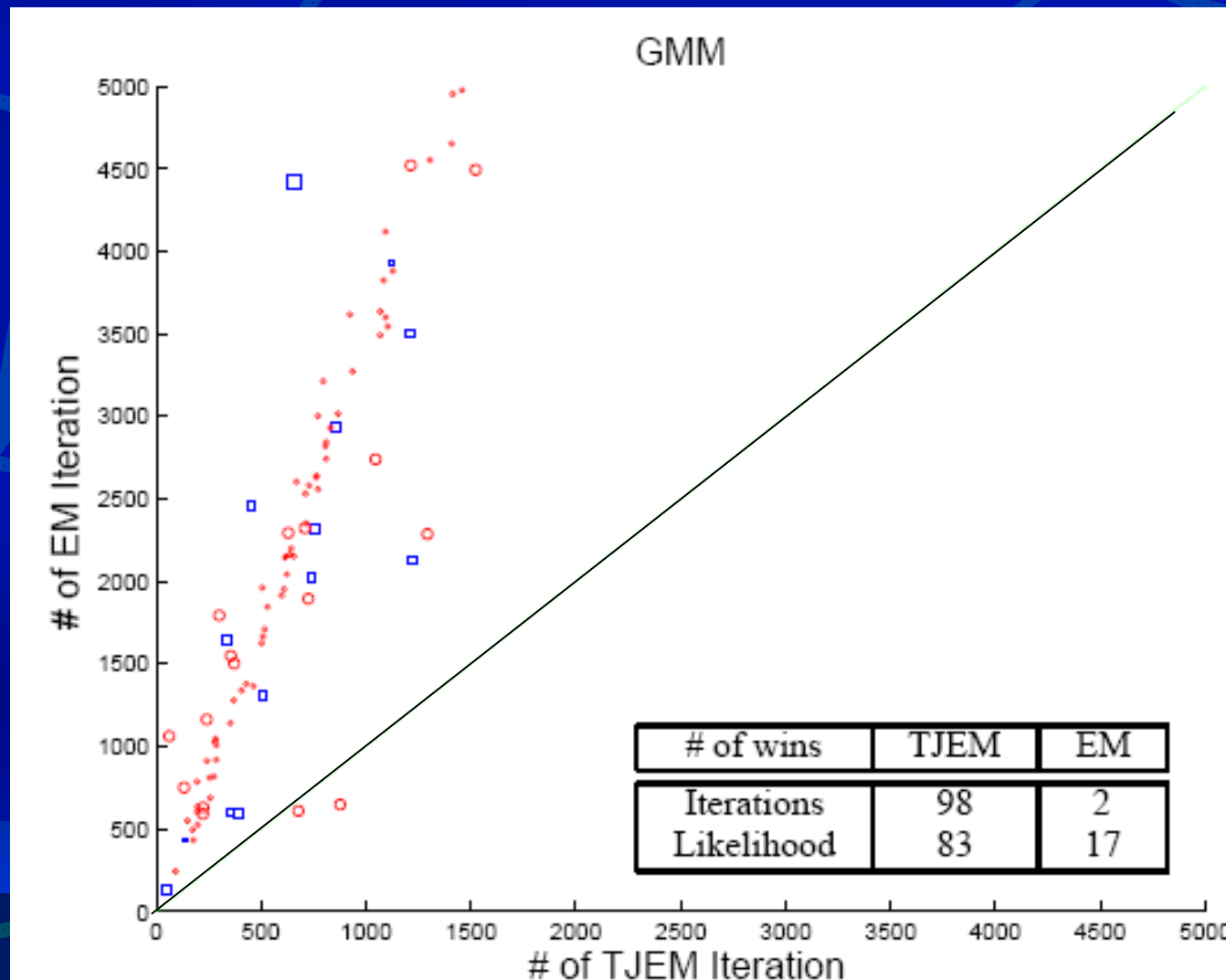


TJEM Faster than EM (Alarm)



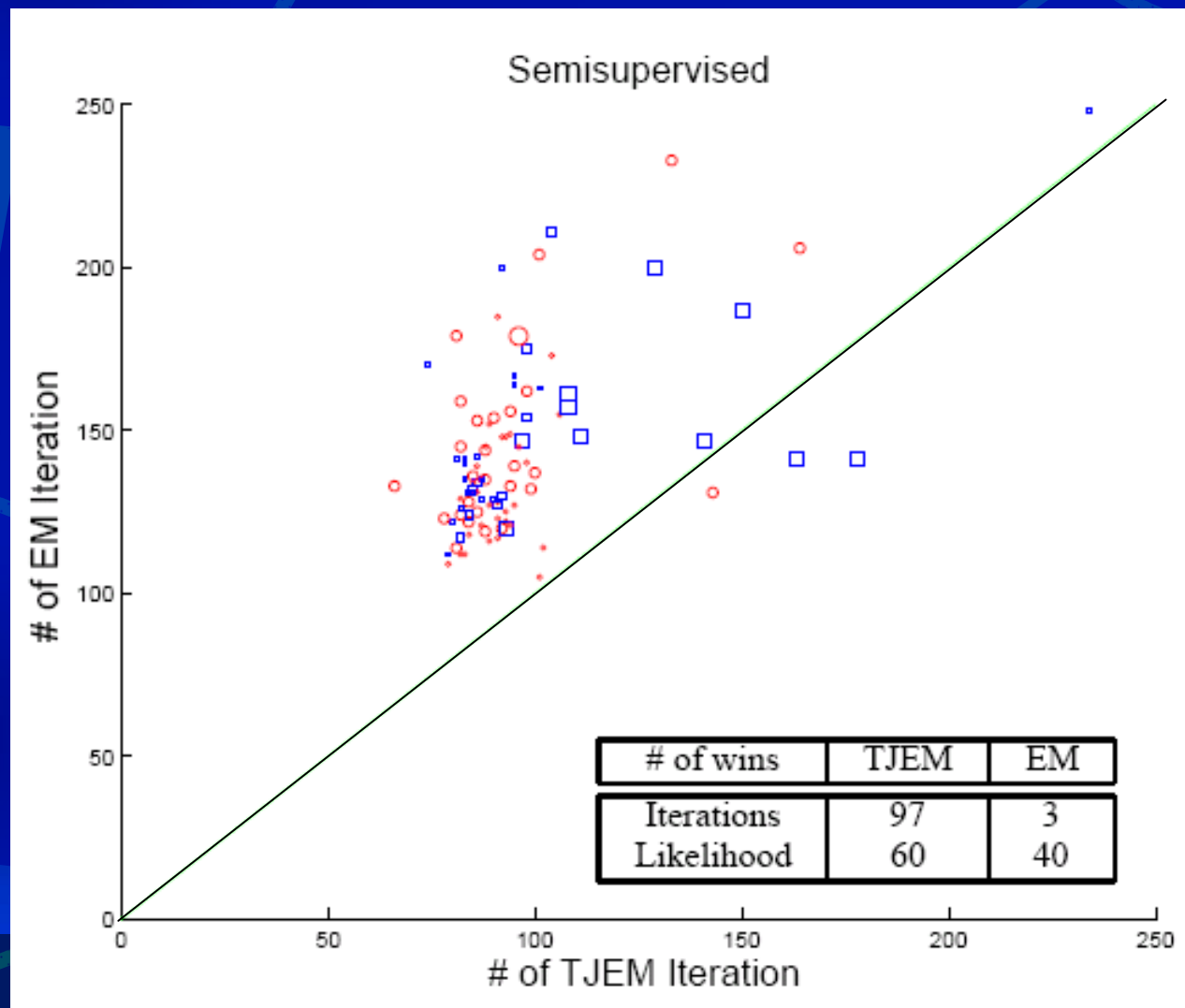


TJEM Faster than EM (GMM)



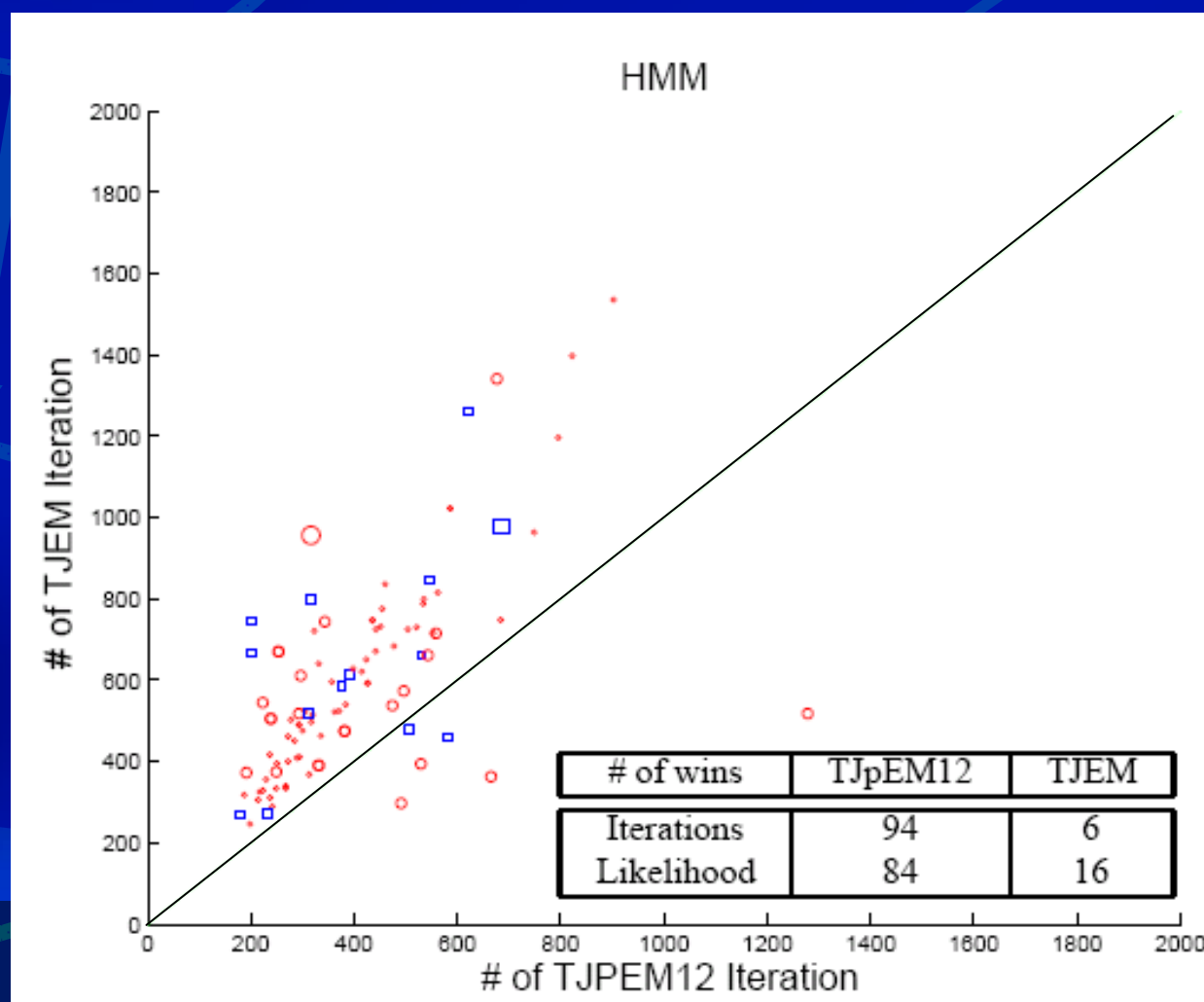


TJEM Faster than EM (Bayesian Classifier)



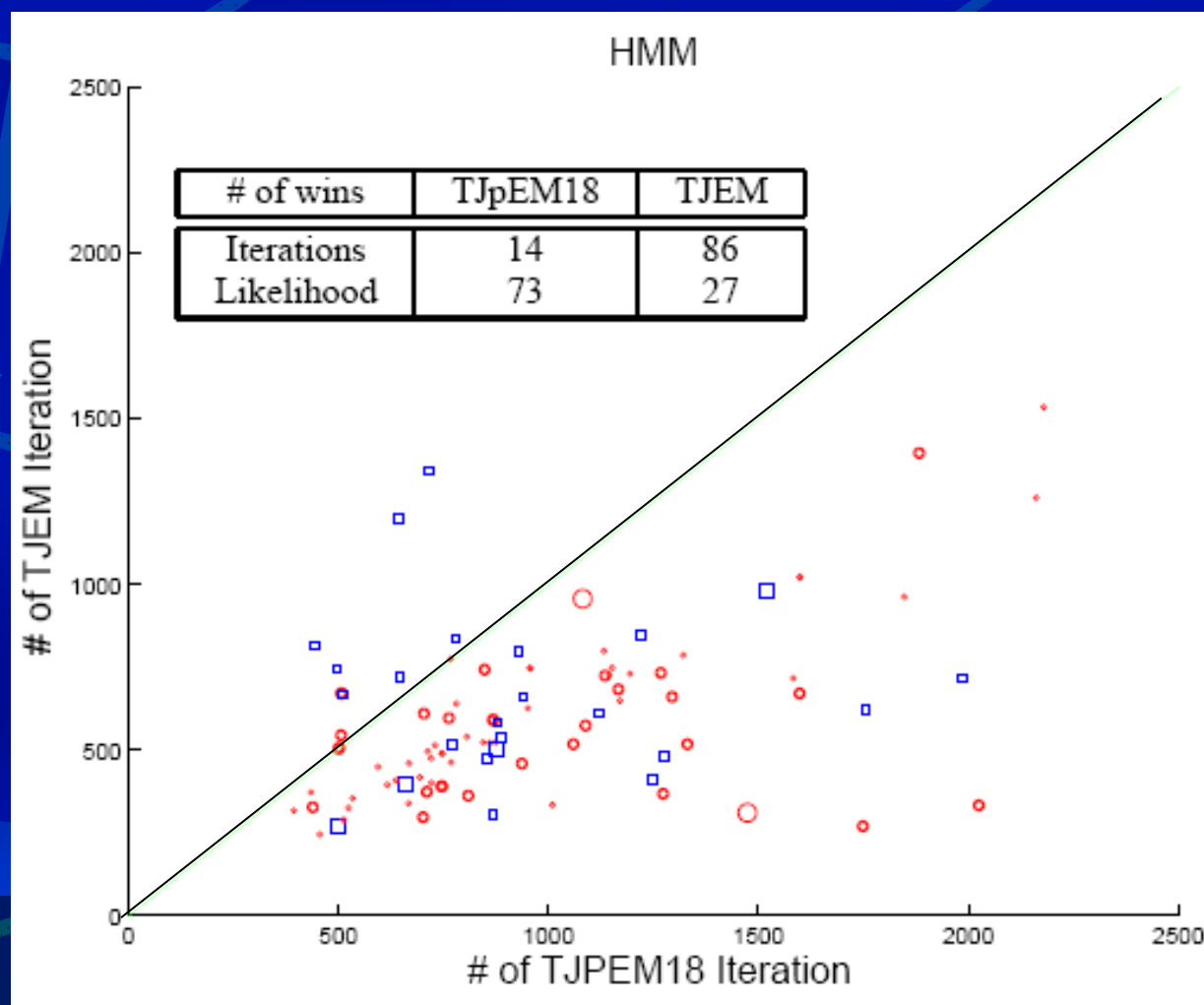


TJpEM with Proper Learning Rate Faster than TJEM



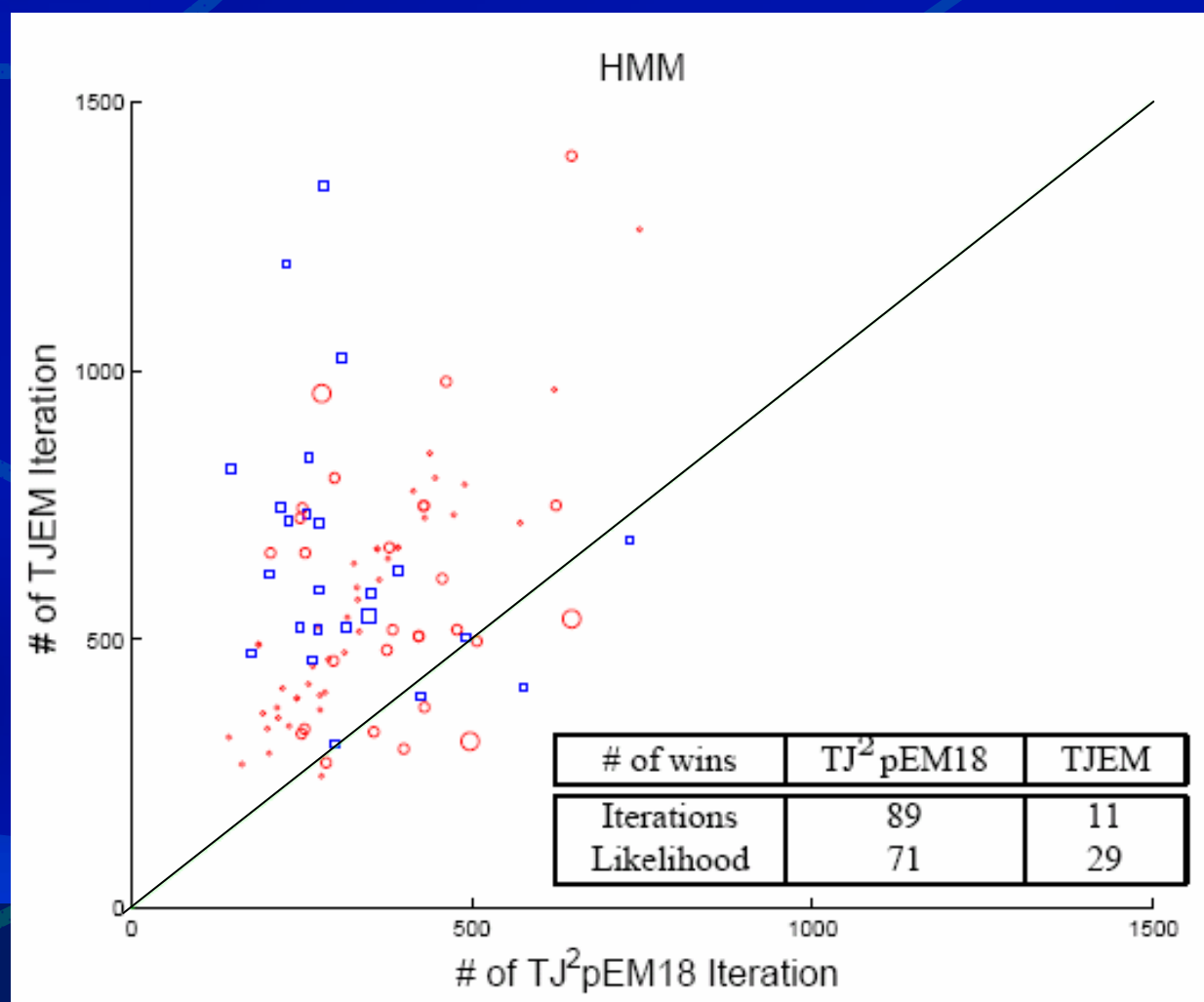


TJpEM with Large Learning Rates Slower than TJEM





TJ^2pEM Overcomes the Impact of Large Learning Rates





aEM Faster than pEM

◆ **GMM**

◆ **Empirically find that $\eta^* = 1.96$**

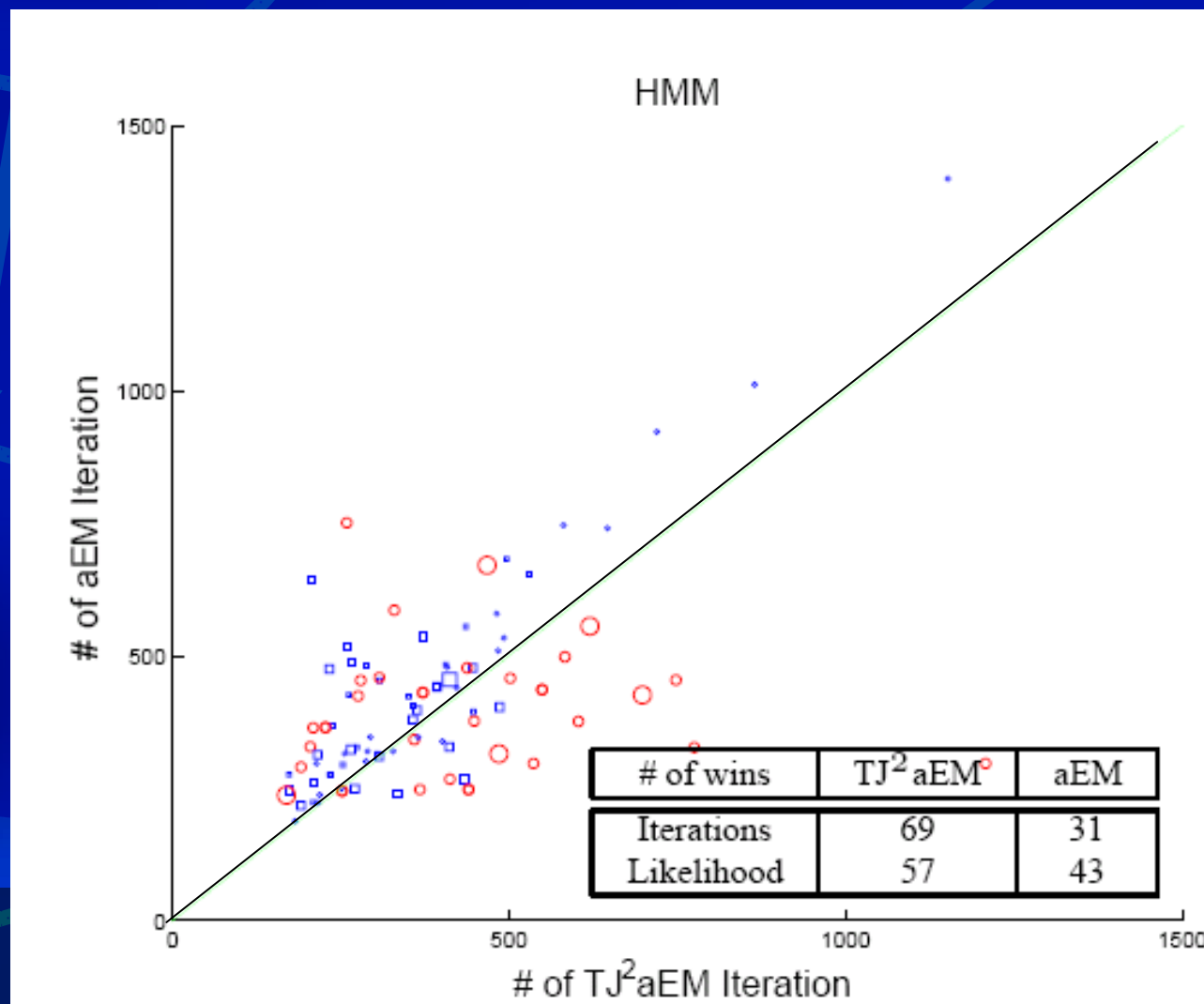
◆ **pEM with η^* converged in 1,327 iterations.**

◆ **aEM in 766 iterations**

◆ **TJ²aEM in 527 iterations**

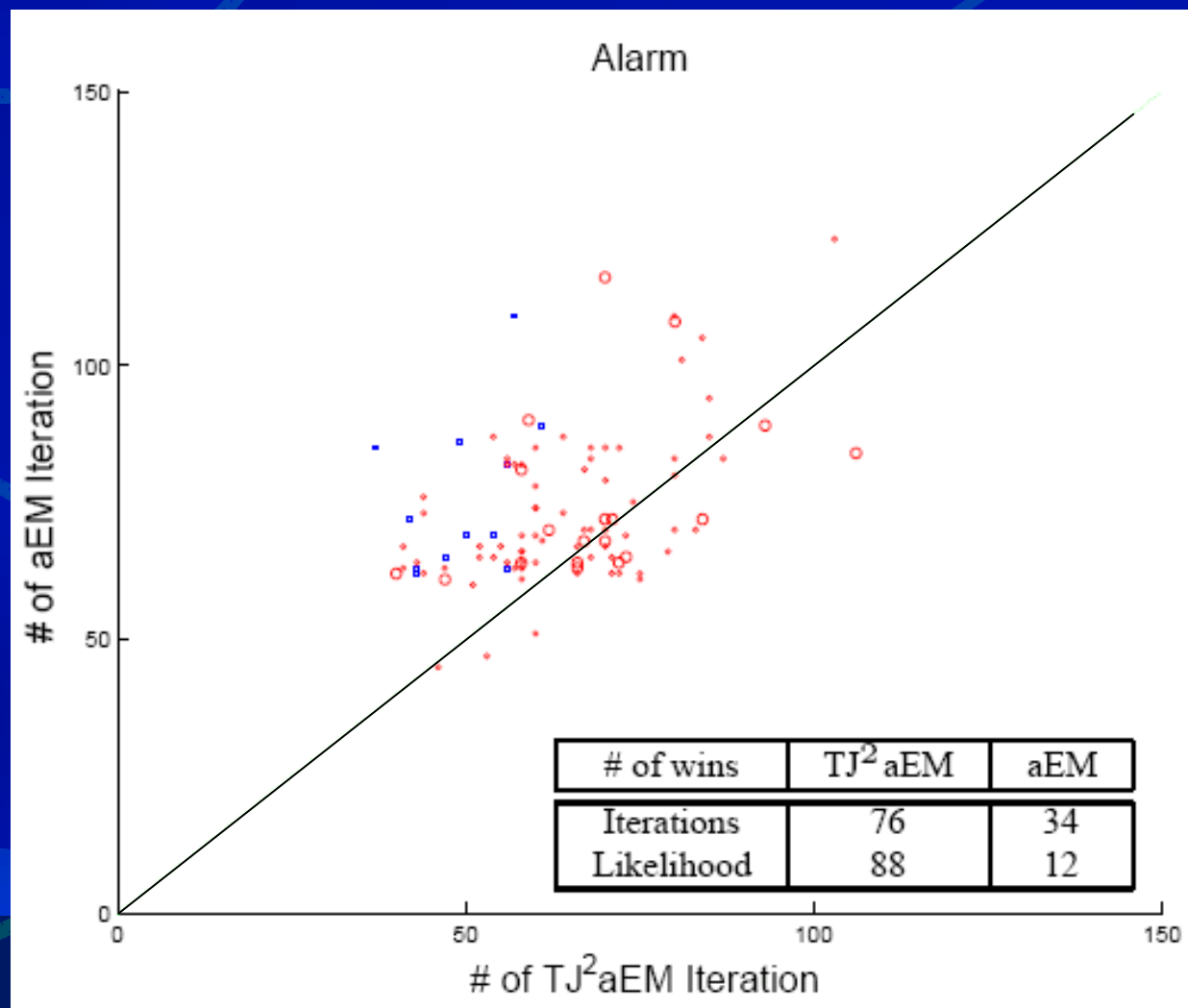


TJ²aEM Faster than aEM (HMM)



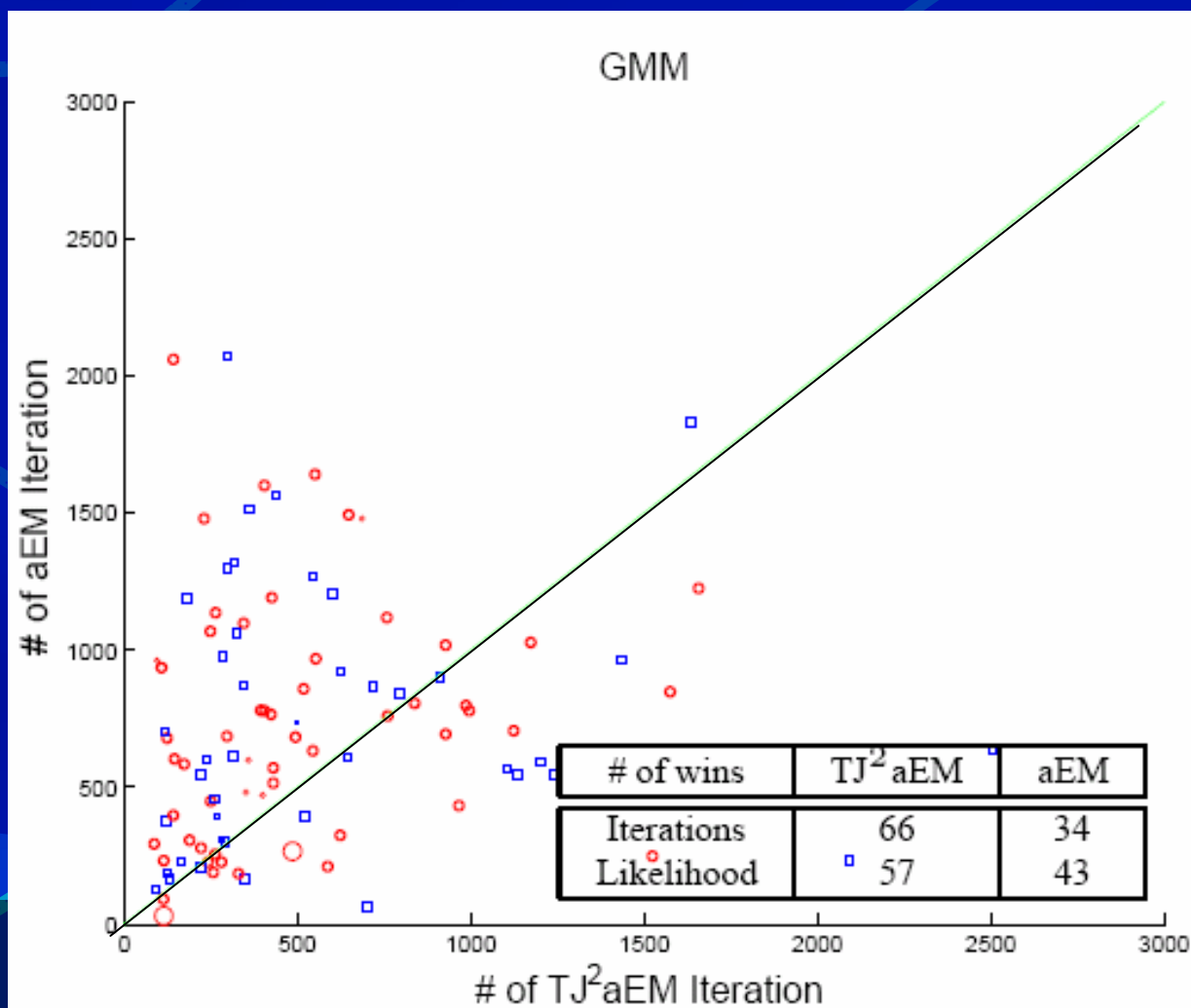


TJ²aEM Faster than aEM (Alarm)



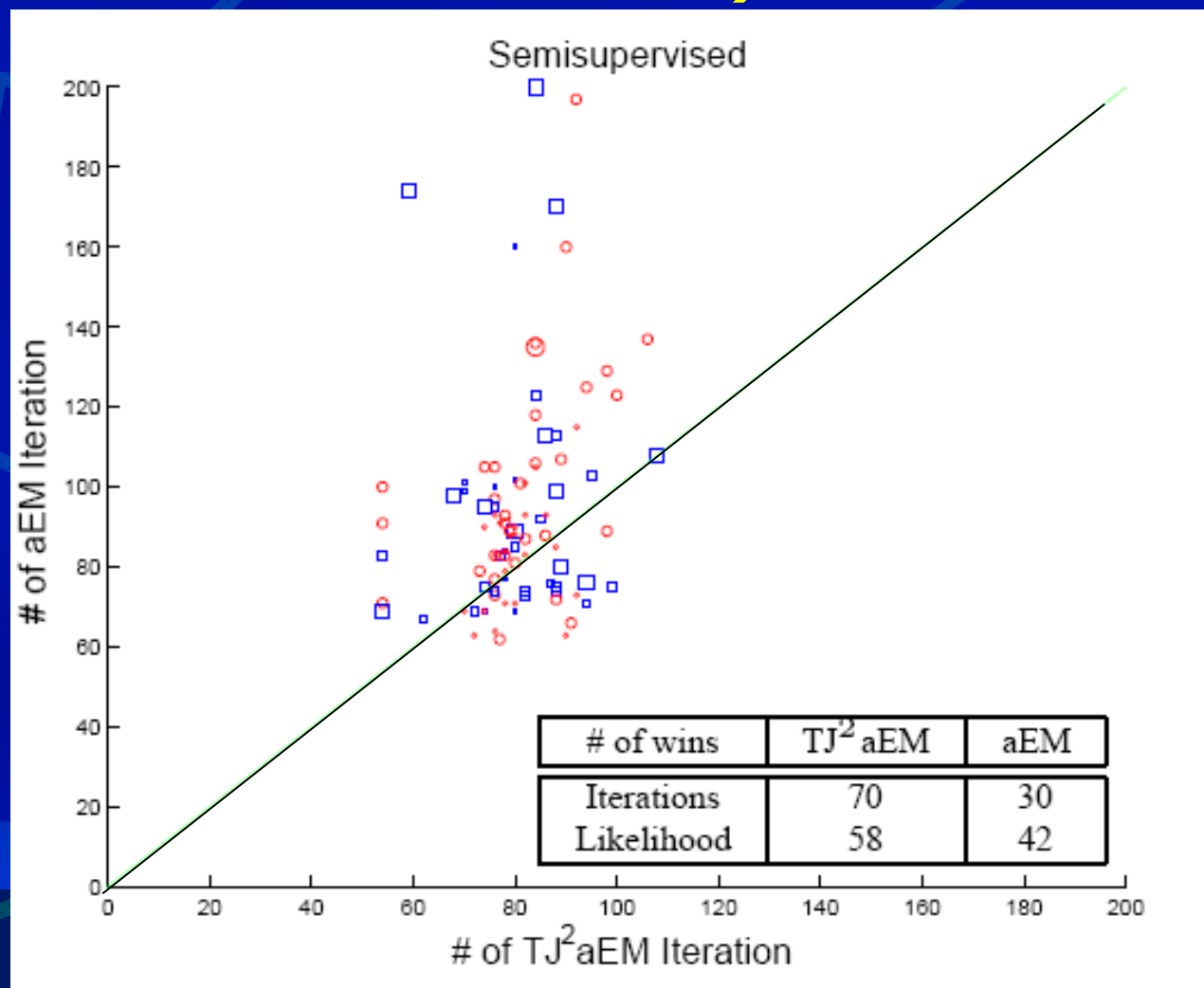


TJ²aEM Faster than aEM (GMM)





TJ²aEM Faster than aEM (Bayesian Classifier)





Componentwise TJEM

- ◆ We can further accelerate previous TJ algorithms when the Jacobian of M is close to a diagonal or block diagonal matrix by using different approximation for each block.

$$\begin{pmatrix} B_{11} & 0 & \dots & 0 \\ 0 & B_{12} & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \dots & 0 & B_{ij} \end{pmatrix}$$

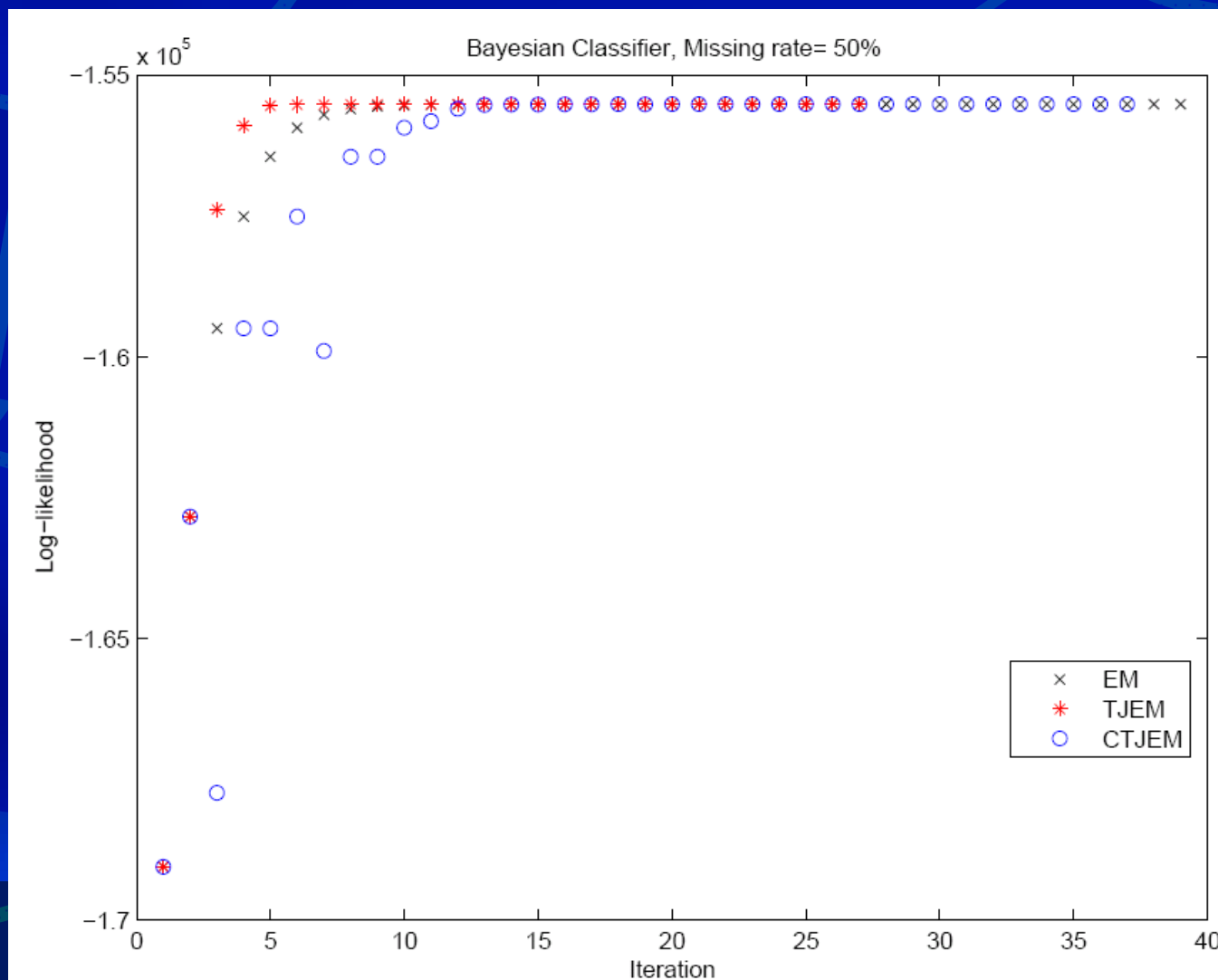


Case Study: Bayesian Classifier

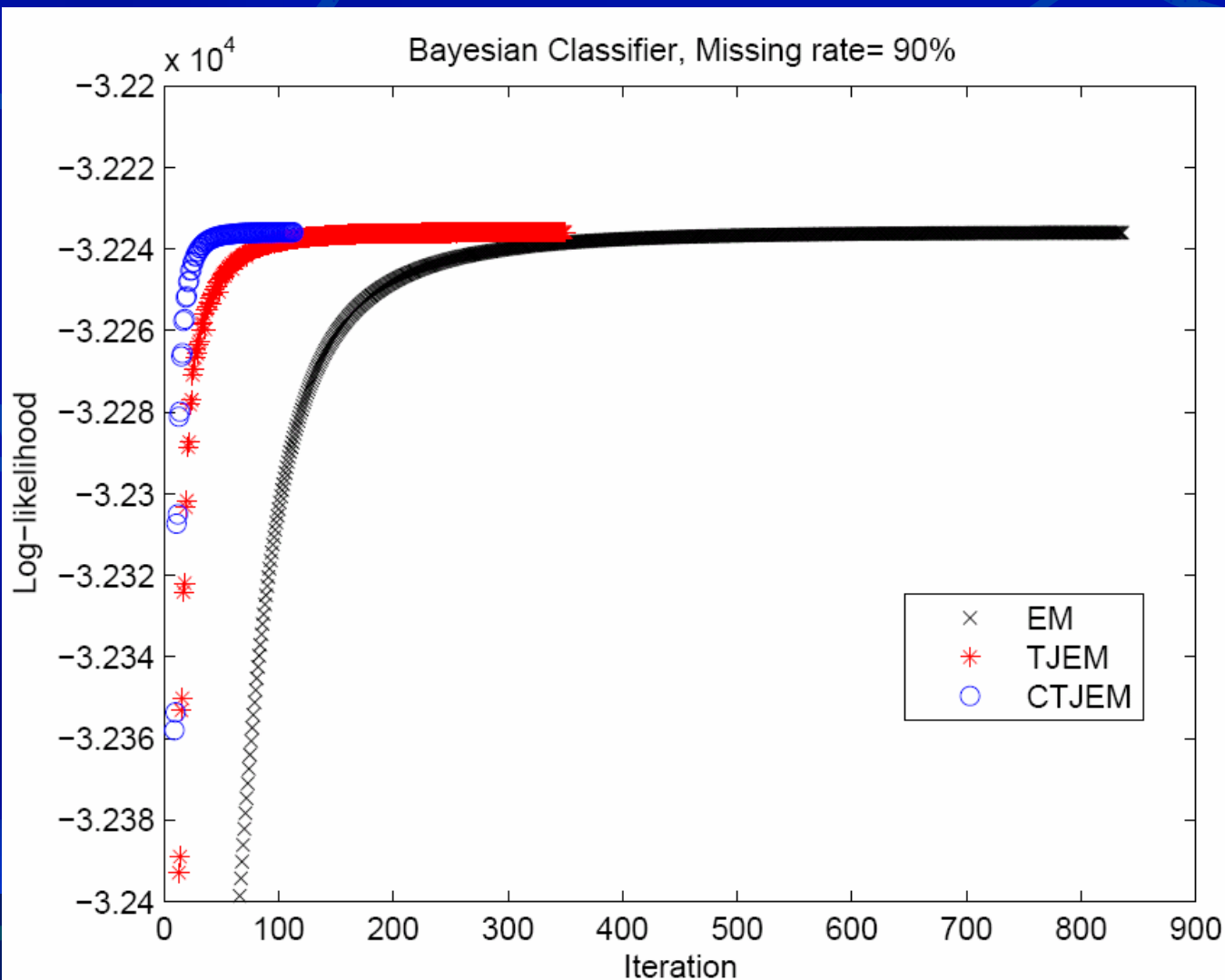
- ◆ With the increase of missing values, the Jacobian of EM for a semisupervised Bayesian classifier is closer to block diagonal matrix.



Missing Rate = 50%



Missing Rate = 90%





Summary

- ◆ Triple jump framework to integrate EM and its extrapolation-based variants
- ◆ Improving convergence rate from TJEM, TJpEM, TJ²pEM, to TJ²aEM
- ◆ CTJEM for sparse data sets where the Jacobian might be close to block diagonal.



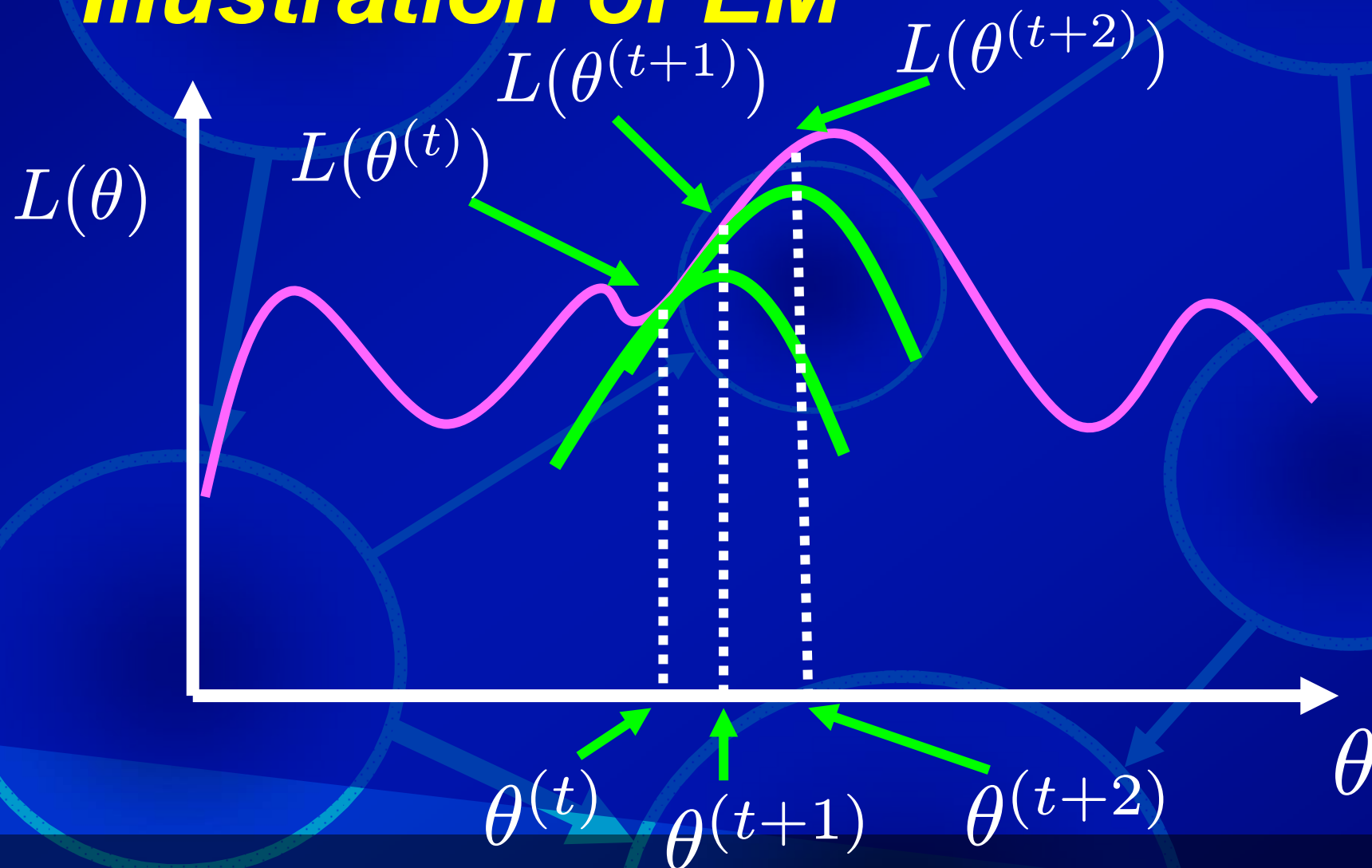
Thank You



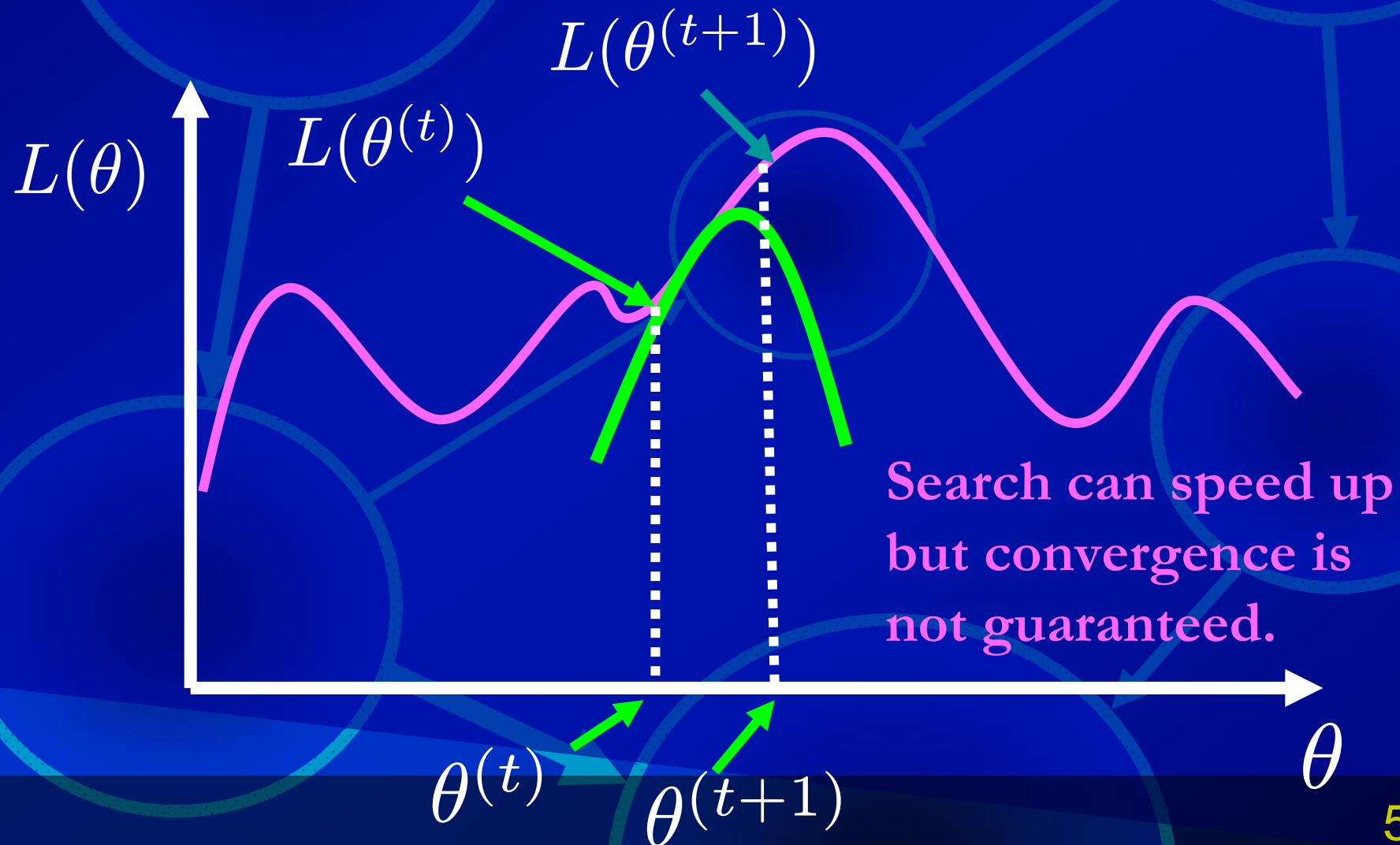
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Illustration of EM



Extrapolation-based Variants

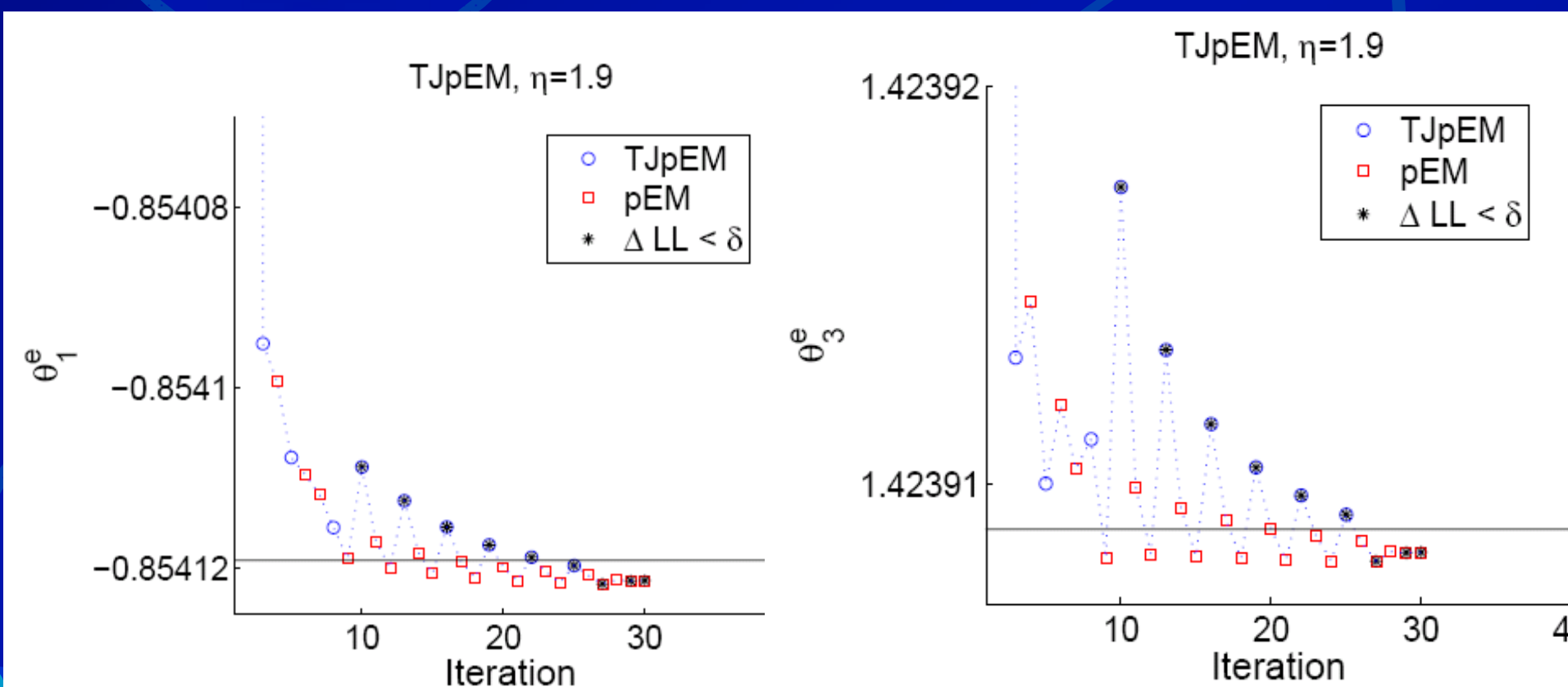




Advantage of TJ^2pEM with Large Learning Rates

- ◆ Toy model: Mixture of two 1-dimensional Gaussian with fixed variance.
- ◆ 500 training examples
- ◆ Parameter vector: (p_0, μ_1, μ_2)
- ◆ J can be estimated [Louis 1982].
- ◆ Eigenvalues: (0.78, 0.31, 0.26)
- ◆ Apply $\hat{\lambda} = 1.9$: (0.58, -0.31, -0.41)

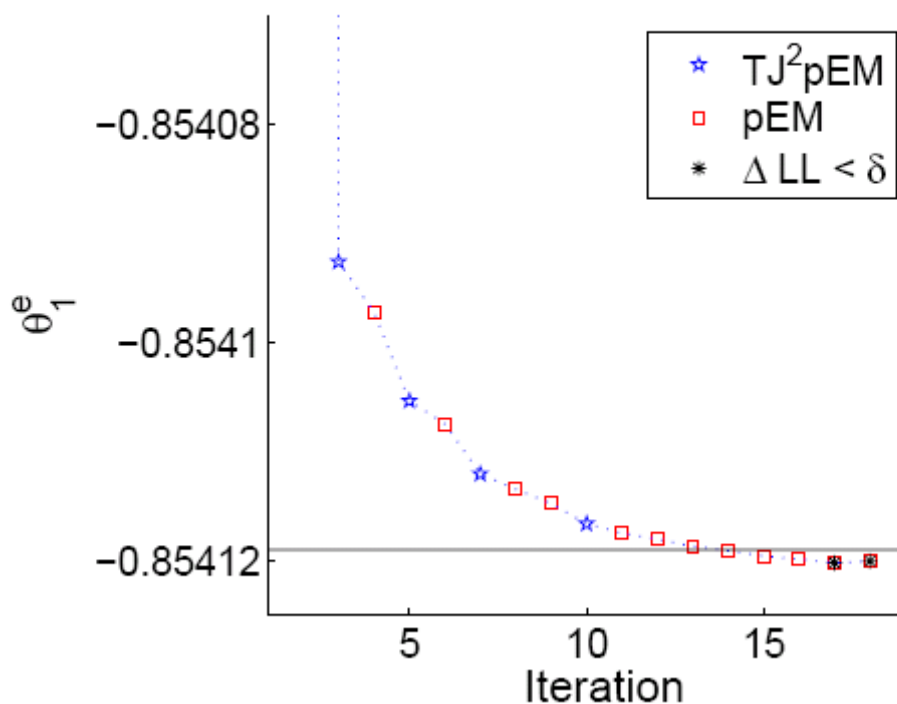
Parameter Vector on the Eigenspace by TjEM





Parameter Vector on the Eigenspace by TJ^2pEM

$TJ^2pEM, \eta=1.9$



$TJ^2pEM, \eta=1.9$

