

# Provable Matrix Completion using Alternating Minimization

Praneeth Netrapalli

The University of Texas at Austin

Joint work with Prateek Jain and Sujay Sanghavi

Dec 8, 2012

# Alternating Minimization (AltMin)

- A popular empirical approach to solve low rank matrix problems eg. matrix completion, clustering etc.
- **Challenge:** good empirical performance; few theoretical guarantees

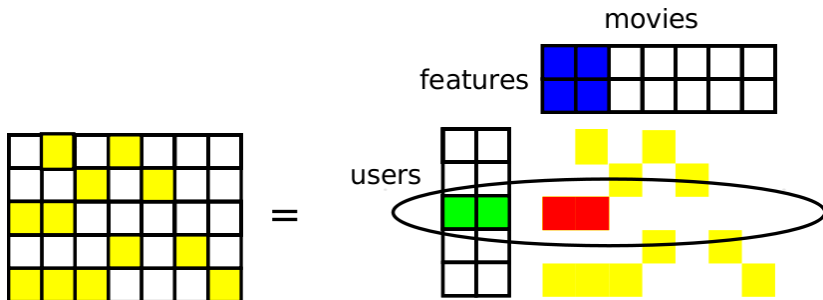
$$\begin{array}{ccc}
 \text{M} & = & \text{U} \quad \text{V}' \\
 \begin{array}{|c|c|c|c|c|c|c|} \hline \square & \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square & \square \\ \hline \end{array} & & \begin{array}{|c|c|c|c|c|c|} \hline \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square & \square \\ \hline \end{array} \\
 m \times n & & m \times k \quad k \times n
 \end{array}$$

## General Algorithm

To minimize  $f(X)$  over rank- $k$  matrices  $X$ , repeat the following:

- fix  $U$  and minimize  $f(UV^\dagger)$  over  $V$
- fix  $V$  and minimize  $f(UV^\dagger)$  over  $U$

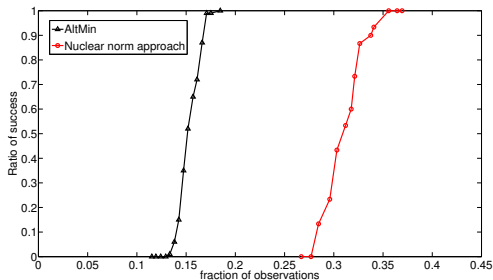
# Matrix Completion



Natural decoupling:

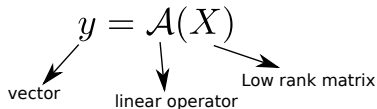
- no need to store large matrices
- easily parallelizable:  $m$  least squares problems over  $k$  variables

# A Comparison



- Nuclear norm approach : a leading theoretical approach.
- Empirically, AltMin has
  - similar sample complexity and
  - better computational complexity.

# Matrix Sensing



**Problem:** Given  $y$  and  $\mathcal{A}$ , recover  $X$ .

## Natural Algorithm (AltMinSense)

- 1 (Initialization)  $\hat{U}^0 \leftarrow$  top  $k$ -left s.v. of  $\sum y_i A_i$
- 2 In iteration  $t$ :
  - $\hat{V}^t \leftarrow \operatorname{argmin}_{V \in \mathbb{R}^{n \times k}} \left\| y - \mathcal{A}(\hat{U}^{t-1} V^\dagger) \right\|_2$
  - $\hat{U}^t \leftarrow \operatorname{argmin}_{U \in \mathbb{R}^{m \times k}} \left\| y - \mathcal{A}(U(\hat{V}^t)^\dagger) \right\|_2$

Solving a non-convex problem

- no known analysis for convergence.

# Existing Results

Existing results require RIP assumptions.

## Restricted Isometry Property (RIP) [RFP10]

A linear operator  $\mathcal{A}(\cdot) : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}^d$  is said to satisfy  $k$ -RIP, with RIP constant  $\delta_k$ , if for all  $X \in \mathbb{R}^{m \times n}$  s.t.  $\text{rank}(X) \leq k$ , the following holds:

$$(1 - \delta_k) \|X\|_F^2 \leq \|\mathcal{A}(X)\|_2^2 \leq (1 + \delta_k) \|X\|_F^2.$$

- [RFP10] (Nuclear norm approach):  $\delta_{5k} < \frac{1}{10}$
- [JMD10] (Projected gradient descent):  $\delta_{2k} < \frac{1}{3}$
- **Drawback:** Need to compute many SVDs during execution - very slow in practice

# Our Results

## Theorem

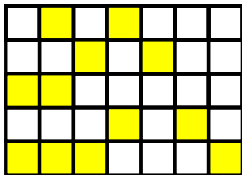
Let  $\sigma_1^* \geq \sigma_2^* \cdots \geq \sigma_k^*$  be the singular values of  $M$ . If  $\mathcal{A}(\cdot)$  satisfies  $2k$ -RIP with constant  $\delta_{2k} < \left(\frac{\sigma_k^*}{\sigma_1^*}\right)^2 \frac{1}{100k}$ , then after  $T > 2 \log \frac{\|M\|_F}{\epsilon}$  iterations of AltMinSense, we have:

$$\left\| M - \hat{U}^T (\hat{V}^T)^\dagger \right\|_F < \epsilon.$$

## Remarks

- 1  $\delta_{2k}$  depends on the condition number unlike in existing work
  - modified algorithm:  $\delta_{2k} < \frac{1}{3200k^2}$
- 2 Linear convergence:  $\log \frac{1}{\epsilon}$  iterations for  $\epsilon$  error.

# Matrix Completion



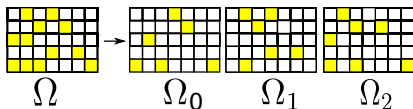
## Problem

Given elements in  $\Omega$ , find the low rank matrix  $M$ .

- **Natural approach:** do AltMin on  $\|P_{\Omega}(M) - P_{\Omega}(UV^{\dagger})\|_F$ .
- Major component of [Kor09] (winning entry of the Netflix prize).
- Analysis is harder:  $\Omega$  does not in general satisfy RIP.



# Our Algorithm



- Divide  $\Omega$  into  $2T + 1$  subsets  $\Omega_0, \dots, \Omega_{2T}$  by uniform sampling.
- Use  $\Omega_i$  for the  $i^{\text{th}}$  iteration of AltMin.

## AltMinComplete

(Initialization)  $\hat{U}^0 \leftarrow$  top  $k$ -left s.v. of  $P_{\Omega_0}(M)$

FOR  $t = 0, \dots, T - 1$

$$\hat{V}^{t+1} \leftarrow \operatorname{argmin}_{V \in \mathbb{R}^{n \times k}} \|P_{\Omega_{t+1}}(\hat{U}^t V^\dagger - M)\|_F^2$$

$$\hat{U}^{t+1} \leftarrow \operatorname{argmin}_{U \in \mathbb{R}^{m \times k}} \|P_{\Omega_{T+t+1}}(U (\hat{V}^{t+1})^\dagger - M)\|_F^2$$

ENDFOR

**Conjecture:** Do not need this partition.

# Existing Results

Existing results assume uniform sampling and incoherence of  $M$ .

## Incoherence [CR09]

$M = U^* \Sigma^* (V^*)^\dagger$  is incoherent with parameter  $\mu$  if

- $\|u^{(i)}\|_2 \leq \frac{\mu\sqrt{k}}{\sqrt{m}} \forall i \in [m]$  and
- $\|v^{(j)}\|_2 \leq \frac{\mu\sqrt{k}}{\sqrt{n}} \forall j \in [n]$ .

- [CR09, CT09] (Nuclear norm):  $Ckn \log n$ 
  - need many SVD calculations
- [KMO10] (Opt. on Grassman manifold):  $C f\left(\frac{\sigma_1^*}{\sigma_k^*}\right) kn \log n$ 
  - slower in practice; rate of convergence not known

# Our Results

## Theorem

Let  $M$  be incoherent with parameter  $\mu$  and  $\sigma_1^* \geq \dots \geq \sigma_k^*$  be its singular values. If

$$p > C \left( \frac{\sigma_1^*}{\sigma_k^*} \right)^4 \frac{\mu^2 k^{4.5} \log n \log \frac{k \|M\|_F}{\epsilon}}{m},$$

then in  $T = C' \log \frac{\|M\|_F}{\epsilon}$  iteration of AltMinComplete, we have:

$$\left\| M - \widehat{U}^T (\widehat{V}^T)^\dagger \right\|_F < \epsilon.$$

**Weakness:** Dependence on

- condition number
- required accuracy
- $k$

**Advantages:**

- linear convergence :  $\log \frac{1}{\epsilon}$  vs  $\frac{1}{\sqrt{\epsilon}}$
- low rank intermediate matrices

# Main Idea of the Proof

- If  $\Omega =$  all elements, then AltMin becomes the well-known power method.
- In general, iterates take the form:

$$\hat{V}^{t+1} = \underbrace{V^* \Sigma^* U^{*\dagger} U^t}_{\text{Power-method Update}} - \underbrace{F}_{\text{Error Term}} \text{ and}$$

$$\|F\|_2 \downarrow \text{ as } \# \text{ observations } \uparrow .$$

# Summary

- Showed AltMin is globally optimal for
  - Matrix sensing and
  - Matrix completion
- **First** such result for AltMin
- Linear convergence:  $\epsilon$  error in  $\log \frac{1}{\epsilon}$  iterations
- However, requires more samples

# Future Work

## Future Work

- **Completion:** remove the dependence on condition number and desired accuracy?
- **Other Problems:** application of the current analysis to obtain guarantees on AltMin for clustering, sparse PCA etc.

Full version: <http://arxiv.org/abs/1212.0467>

Thank you!

# References



Emmanuel J. Candès and Benjamin Recht.

Exact matrix completion via convex optimization.

*Foundations of Computational Mathematics*, 9(6):717–772, December 2009.



Emmanuel J. Candès and Terence Tao.

The power of convex relaxation: Near-optimal matrix completion.

*IEEE Trans. Inform. Theory*, 56(5):2053–2080, 2009.



Prateek Jain, Raghu Meka, and Inderjit S. Dhillon.

Guaranteed rank minimization via singular value projection.

In *NIPS*, pages 937–945, 2010.



Raghunandan H. Keshavan, Andrea Montanari, and Sewoong Oh.

Matrix completion from a few entries.

*IEEE Transactions on Information Theory*, 56(6):2980–2998, 2010.



Yehuda Koren.

The BellKor solution to the Netflix grand prize, 2009.



Benjamin Recht, Maryam Fazel, and Pablo A. Parrilo.

Guaranteed minimum-rank solutions of linear matrix equations via nuclear norm minimization.

*SIAM Review*, 52(3):471–501, 2010.